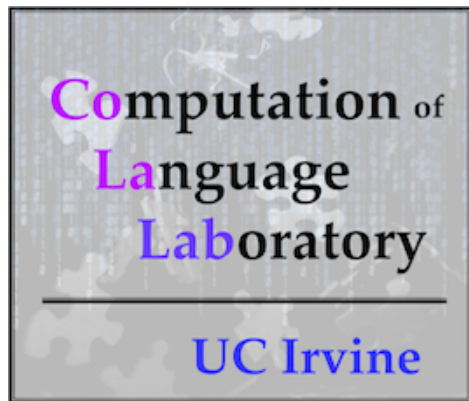


The development of verb classes: A computational adventure with implications for linguistic theory

Lisa Pearl

University of California, Irvine

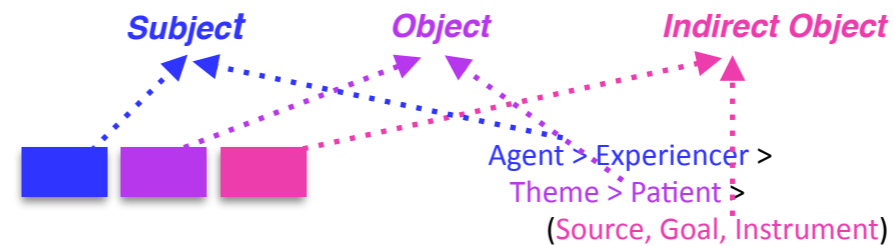
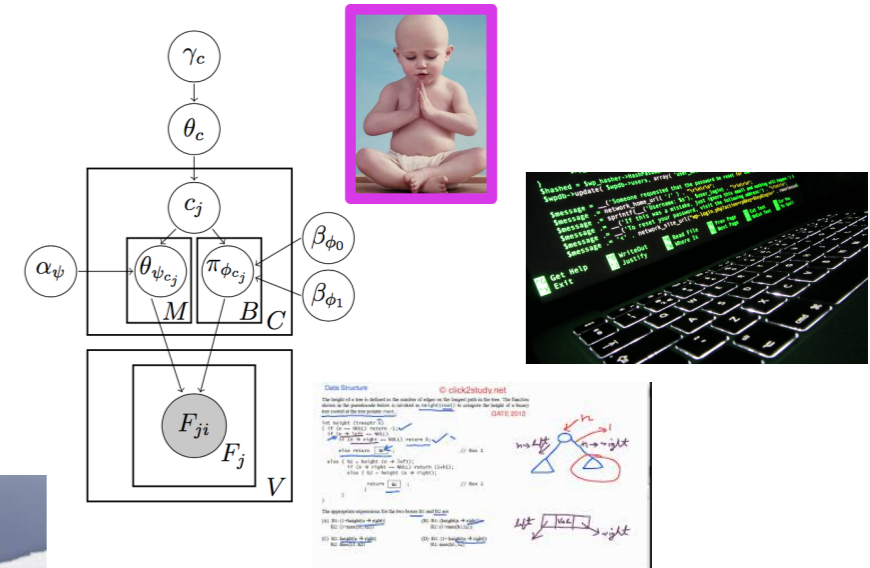


done-to

The ice melted.

The penguin climbed.

doer



June 5, 2017: Language Science Colloquium

University of California, Irvine

Today's plan

Verb classes



done-to

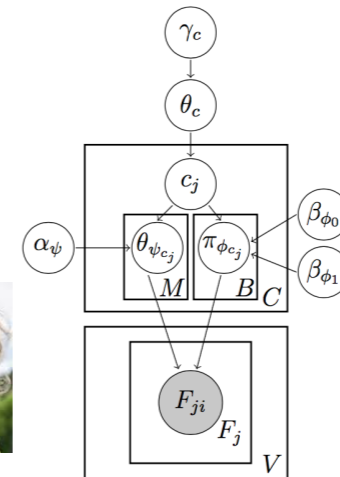
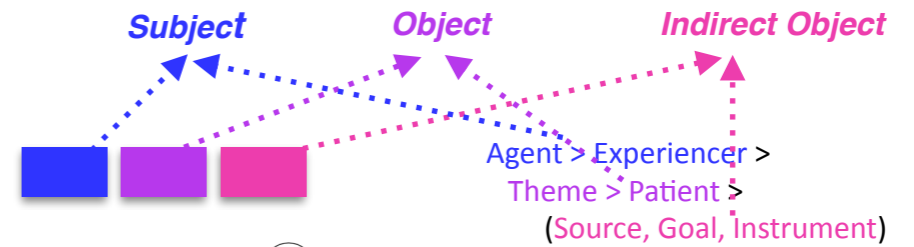
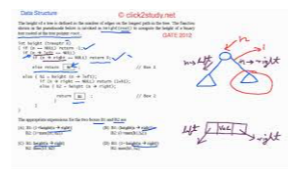
The ice melted.

The penguin climbed.

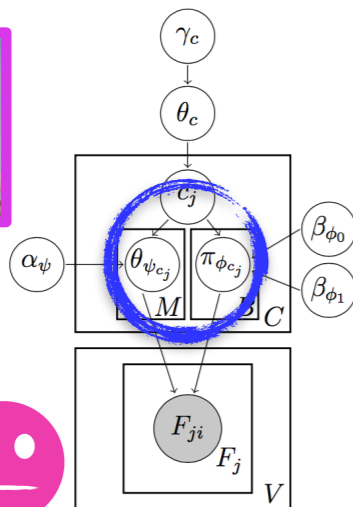
doer



Computational modeling



Results & implications



Today's plan

Verb classes

done-to

The ice melted.



The penguin climbed.

doer



Verb classes

Verbs allow a variety of options for where their arguments appear ...

try

She **tried** to **melt** the ice.

It **tried that she **melted** the ice.*



seem

The penguin **seemed** to **climb** the hill.

It **seemed** that the penguin **climbed** the hill.



Verb classes

Verbs allow a variety of options for where their arguments appear and how they're interpreted.

*doer*_{melt} **try** *done-to*_{melt}
*doer*_{tried} She **tried** to **melt** the ice.

*doer*_{melted} *done-to*_{melt}
*It **tried** that she **melted** the ice.



*doer*_{climb} **seem** *done-to*_{climb}
The penguin **seemed** to **climb** the hill.

*doer*_{climb} *done-to*_{climb}
It **seemed** that the penguin **climbed** the hill.



Verb classes

Verbs allow a variety of options for where their arguments appear and how they're interpreted.

*doer*_{melt} **try**

*doer*_{tried}

She **tried** to **melt** the ice.

**It tried that she melted the ice.*



seem

*doer*_{climb}

The penguin **seemed** to **climb** the hill.

It **seemed** that the penguin **climbed** the hill.



melt

*doer*_{melted} *done-to*_{melted}

She **melted** the ice.

*done-to*_{melted}

The ice was **melted**.

*done-to*_{melted}

The ice **melted**.

*doer*_{climbed}

The penguin **climbed** the hill.

*done-to*_{climbed}

The hill was **climbed**.

*doer*_{climbed}

The penguin **climbed**.

climb

Verb classes

Each verb has **certain linguistic patterns of behavior**, which are shared with other verbs in the same **verb class**.

want need

subject-control

*doer*_{melt}

try

*doer*_{tried}

She **tried** to **melt** the ice.

**It tried that she melted the ice.*

appear

subject-raising

seem

*doer*_{climb}

The penguin **seemed** to **climb** the hill.

It **seemed** that the penguin **climbed** the hill.

*done-to*_{melted}

The ice **melted**.

melt

unaccusative

break fall



*doer*_{climbed}

The penguin **climbed**.

climb

unergative

laugh dance

Verb classes

How do we tell how a **new verb** will behave?



The water **daxed** to **blick**.

want need

subject-control

*doer*_{melt}

try

*doer*_{tried}

She **tried** to **melt** the ice.

*It **tried** that she **melted** the ice.

appear

subject-raising

seem

*doer*_{climb}

The penguin **seemed** to **climb** the hill.

It **seemed** that the penguin **climbed** the hill.

*done-to*_{melted}

The ice **melted**.

melt

unaccusative

break fall



*doer*_{climbed}

The penguin **climbed**.

climb

unergative

laugh dance

Verb classes

We can recognize that it belongs to a specific **verb class**, and use that knowledge to predict its behavior.

want need

subject-control

*doer*_{melt}

try

*doer*_{tried}

She **tried** to **melt** the ice.

**It tried that she melted the ice.*



It **daxed** that the water **blicked**.

appear **dax**

subject-raising

seem

*doer*_{climb}

The penguin **seemed** to **climb** the hill.

It **seemed** that the penguin **climbed** the hill.

*done-to*_{melted}

The ice **melted**.

blick melt

unaccusative

break fall



*doer*_{climbed}

The penguin **climbed**.

climb

unergative

laugh dance

*done-to*_{blicked}

The water **blicked**.



Verb classes

This is what we think kids are doing, too.



want need

subject-control

doer_{melt}

try

doer_{tried}

She tried to melt the ice.

*It tried that she melted the ice.



It daxed that the water blicked.

appear dax

subject-raising

seem

doer_{climb}

The penguin seemed to climb the hill.

It seemed that the penguin climbed the hill.

done-to_{melted}

The ice melted.

blick melt

unaccusative

break fall



doer_{climbed}

The penguin climbed.

climb

unergative

laugh dance

done-to_{blicked}

The water blicked.



Verb classes

Important developmental step:
Grouping verbs into useful **classes**.



melt
unaccusative
break fall

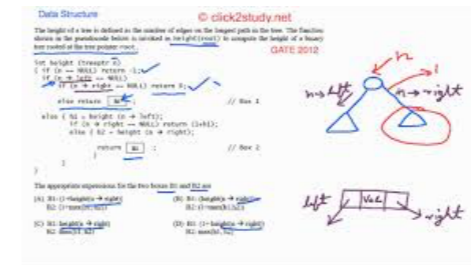
want need
subject-control
try

appear
subject-raising
seem

climb
unergative
laugh dance

So how might children do this?

And how can we test different proposals about how they might do this?



Today's plan

Verb classes



done-to

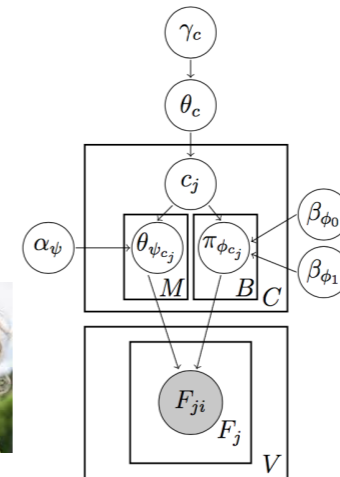
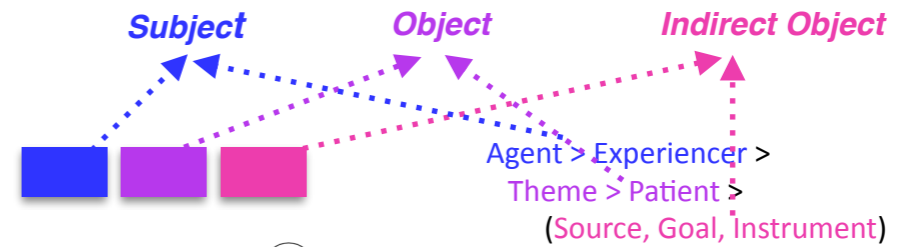
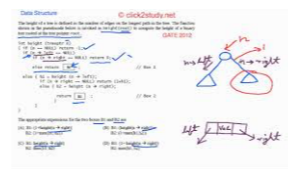
The ice melted.

The penguin climbed.

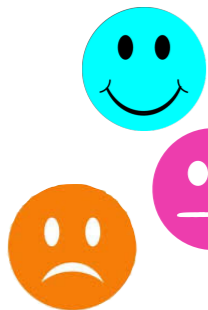
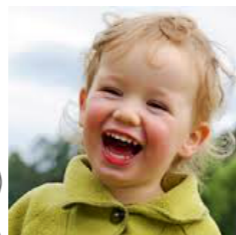
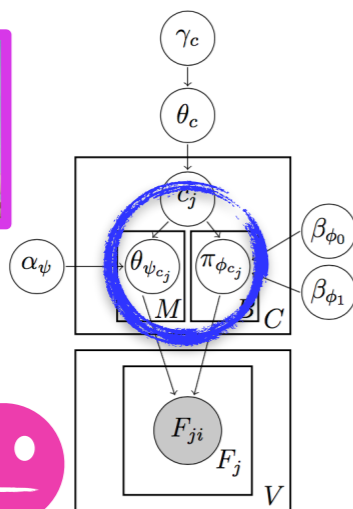
doer



Computational modeling



Results & implications



Today's plan

Computational modeling of language acquisition

Data Structure © click2study.net

The height of a tree is defined as the number of edges on the longest path to the leaf. The function below on the pseudocode below is used to compute the height of a binary tree rooted at the tree pointer root.

```
int height (TreeNode* root) { if (root == NULL) return 0; if (root->left == NULL) return 1; else return 1 + max(height(root->left), height(root->right)); }
```

Handwritten notes and diagrams:

- A diagram of a binary tree with root node 'A', left child 'B', and right child 'C'. Node 'B' has a left child 'D'. Node 'C' has a right child 'E'. Red arrows point from 'A' to 'B' and 'C', and from 'B' to 'D'. A red circle highlights node 'C' and its child 'E'. The word 'height' is written in red above the tree.
- A diagram showing a box labeled 'max' with 'left' on the left and 'right' on the right, with arrows pointing to the box.



A brief overview

Language acquisition = Information processing task

Given the available input ...



The penguin
tried to climb.



The ice seemed
to melt.



Language acquisition = Information processing task

Given the available input, information processing done by human minds...



The penguin
tried to climb.



The ice seemed
to melt.



Language acquisition = Information processing task

Given the available input, information processing done by human minds to build a **system of linguistic knowledge** ...



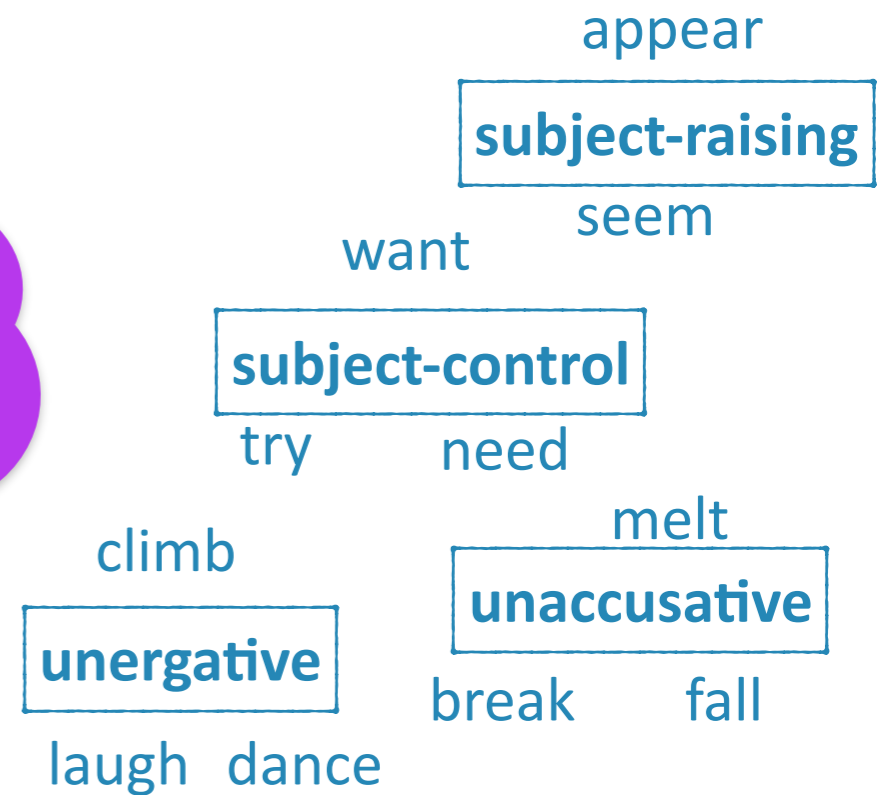
The penguin tried to climb.



The ice seemed to melt.



processing & generalization



Language acquisition = Information processing task

Given the available input, information processing done by human minds to build a system of linguistic knowledge **whose output we observe**



appear
subject-raising

seem
want

subject-control
try need

climb
unergative

melt
unaccusative

laugh dance

break fall



The penguin tried to climb.



The ice seemed to melt.



The penguin wanted to dance.



It appeared that the ice broke.

Language acquisition = Information processing task

To understand how children solve the acquisition task, we need to make explicit the relevant components of the task.



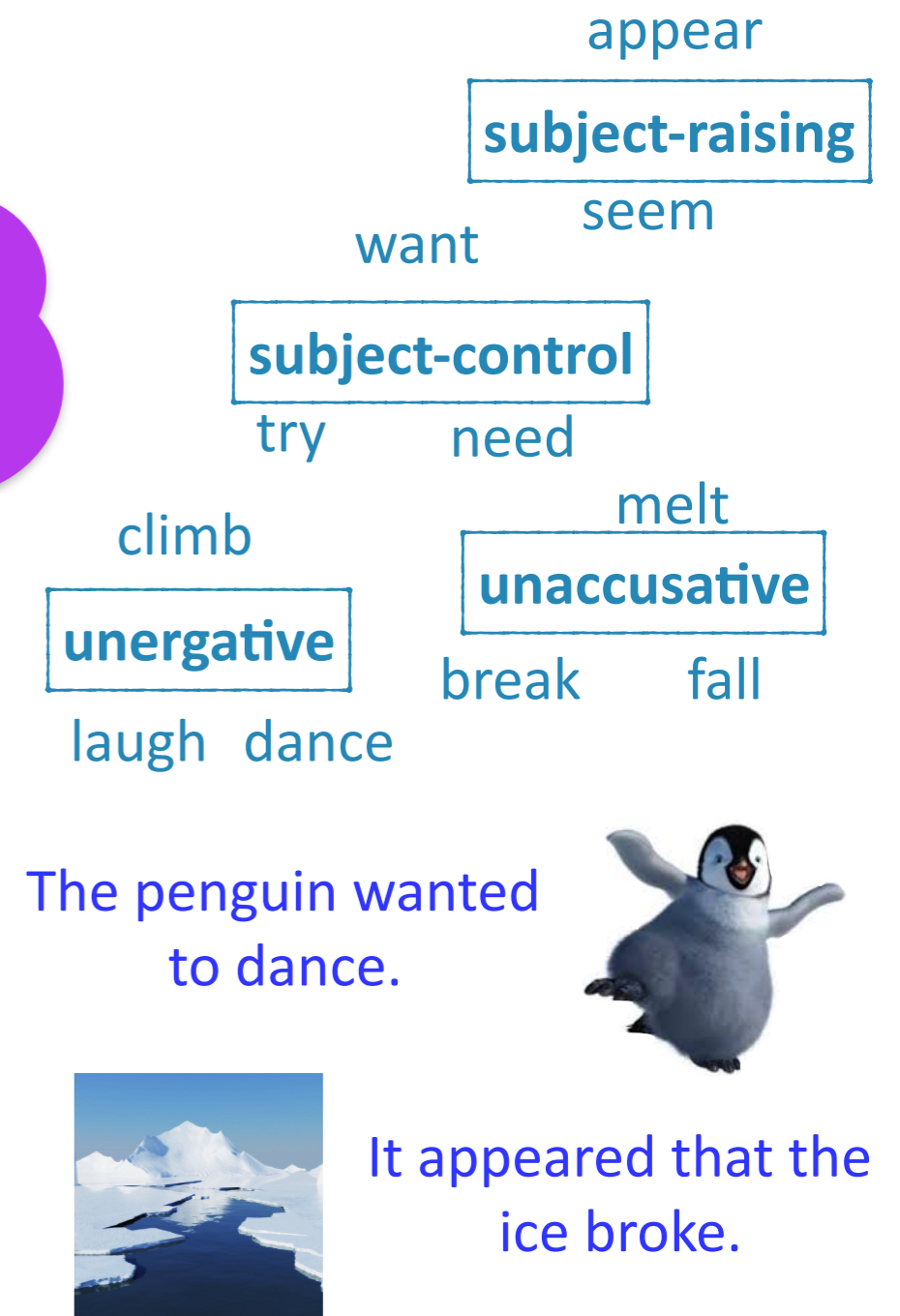
The penguin tried to climb.



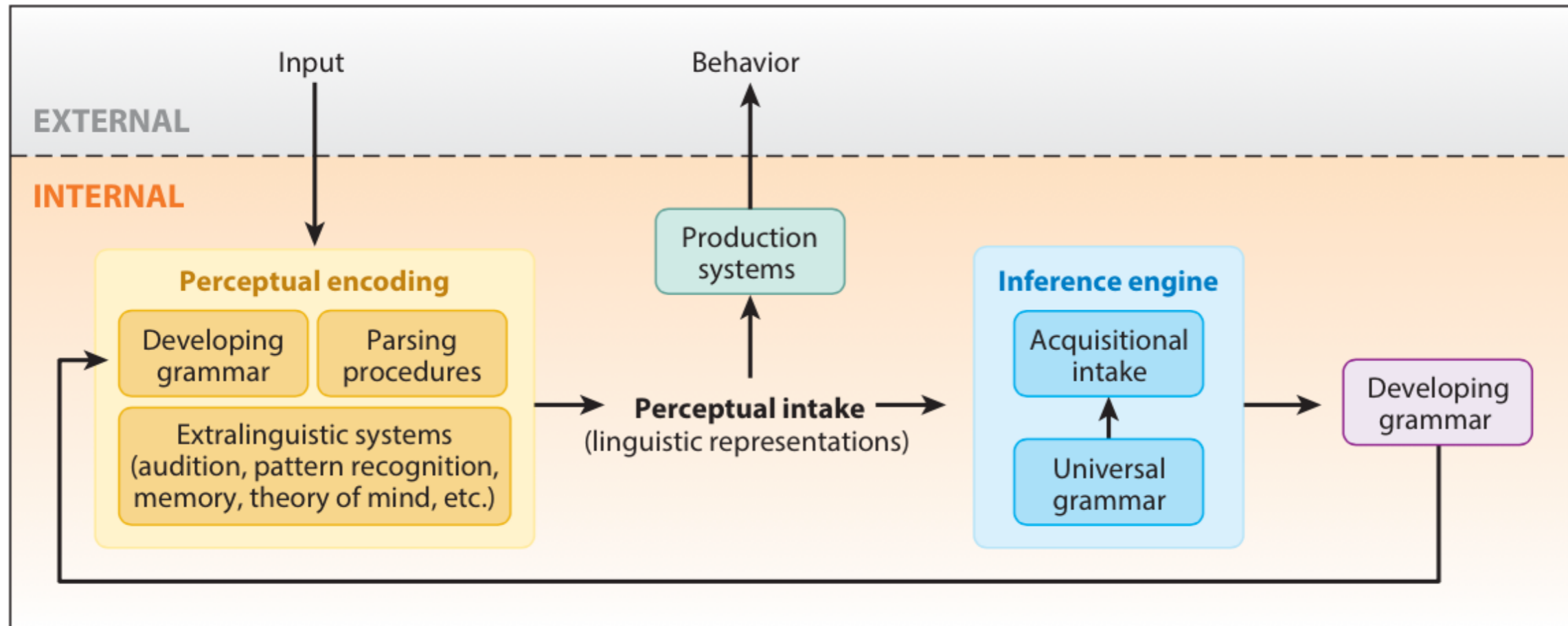
The ice seemed to melt.



processing & generalization



Language acquisition = Information processing task



Lidz & Gagliardi 2015



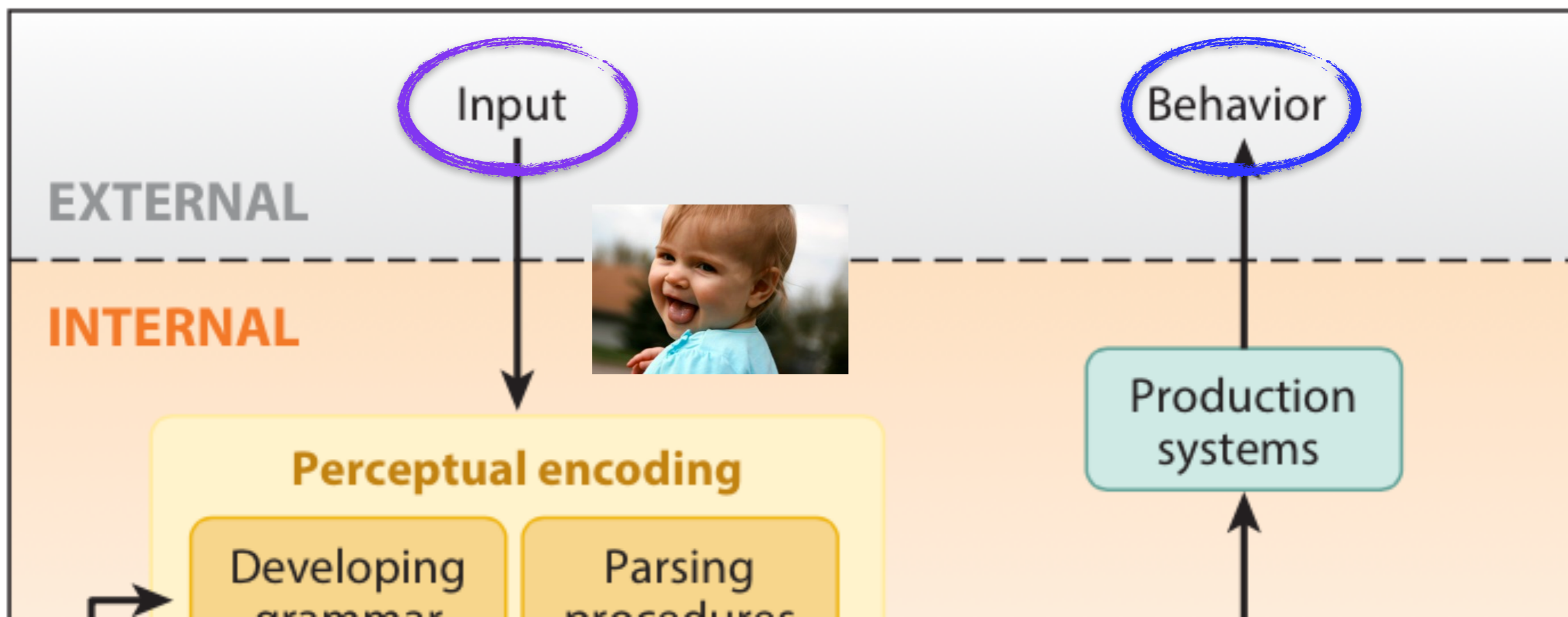
A framework that makes components of the acquisition task more explicit.

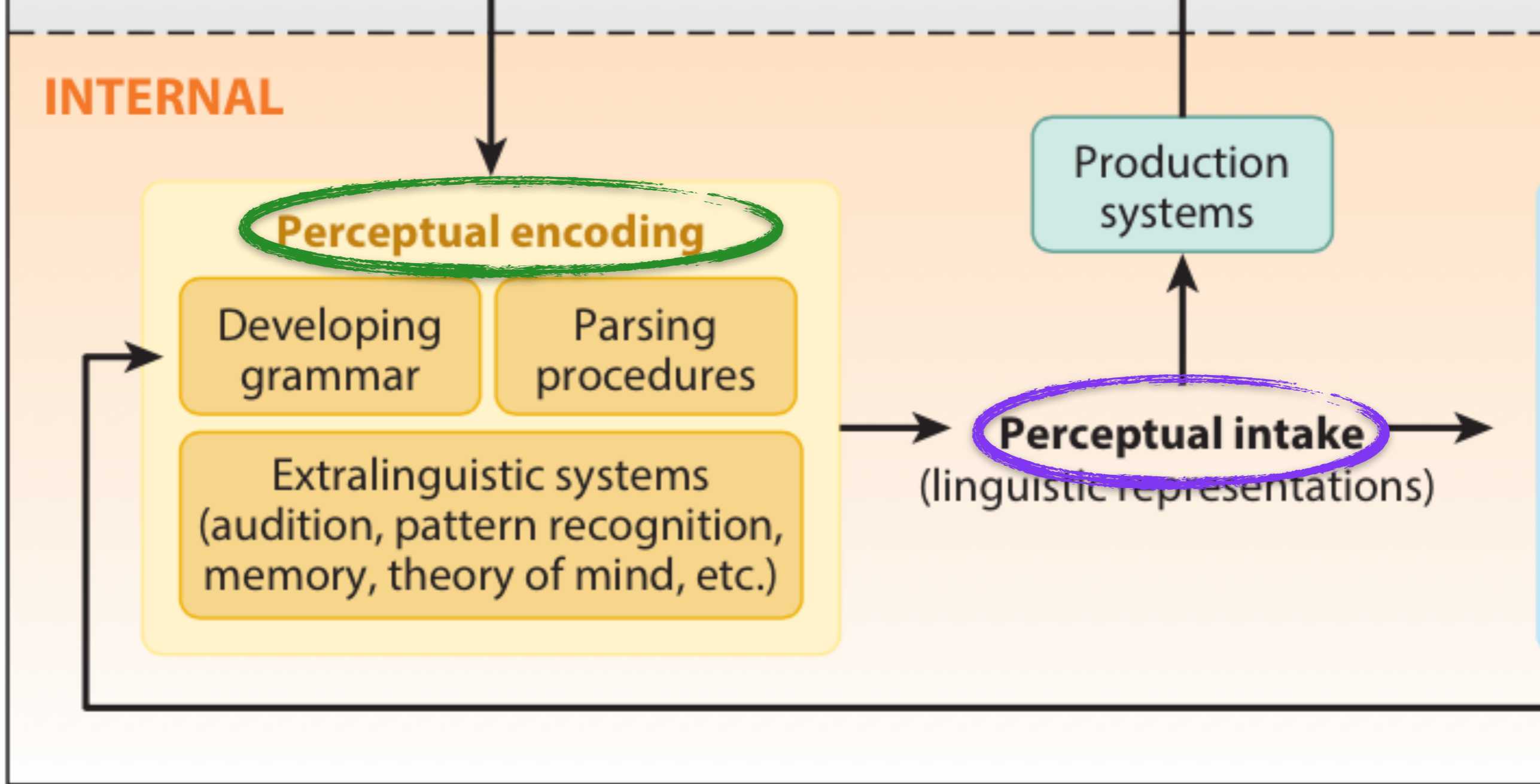
A framework that makes components of the acquisition task more explicit.

Distinguishes between things external to the child that we can observe (**input signal, child's behavior**) vs. things internal to the child (everything else).

**Experimental &
Corpus methods**

Experimental methods



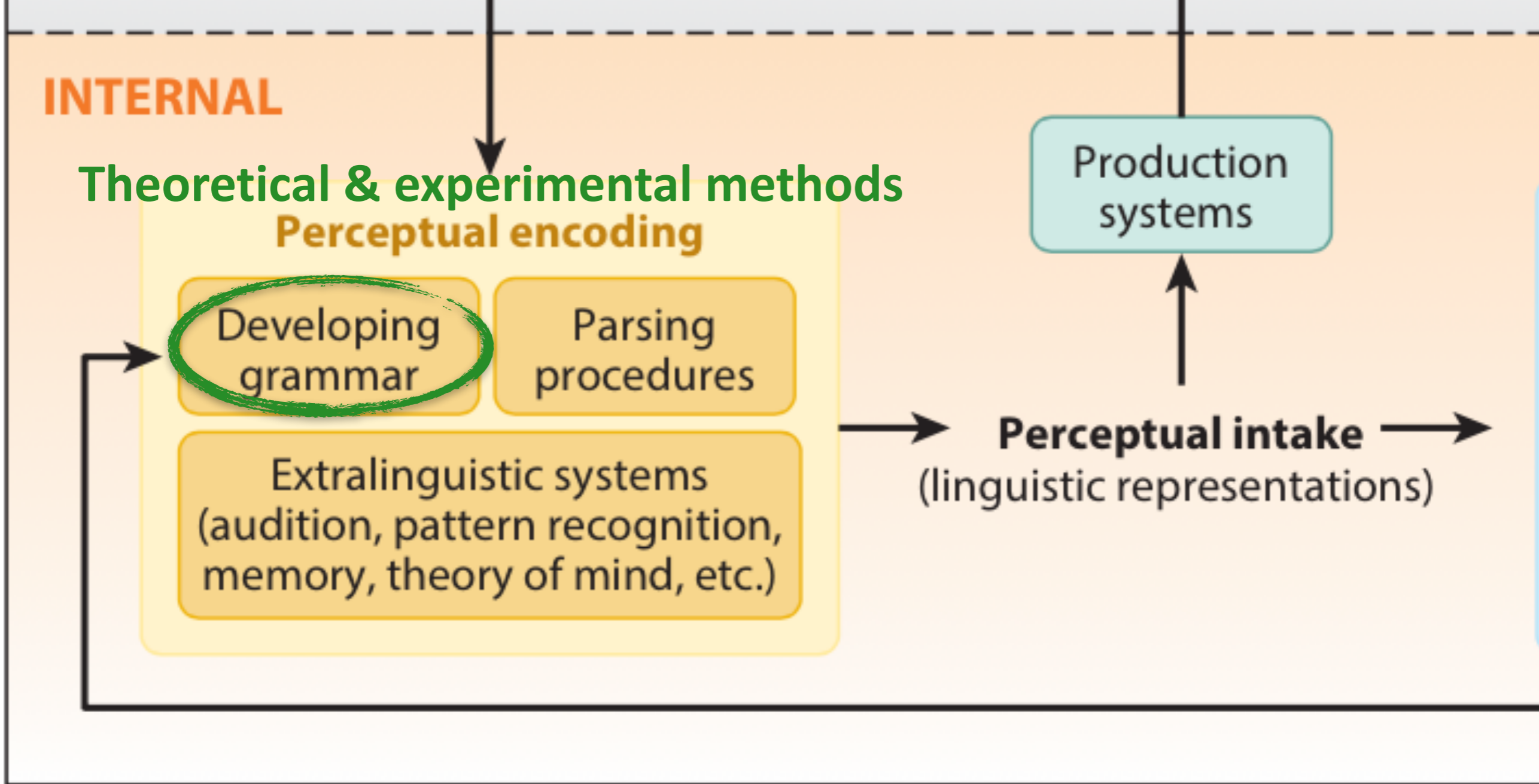


Lidz & Gagliardi 2015



Perceptual encoding:

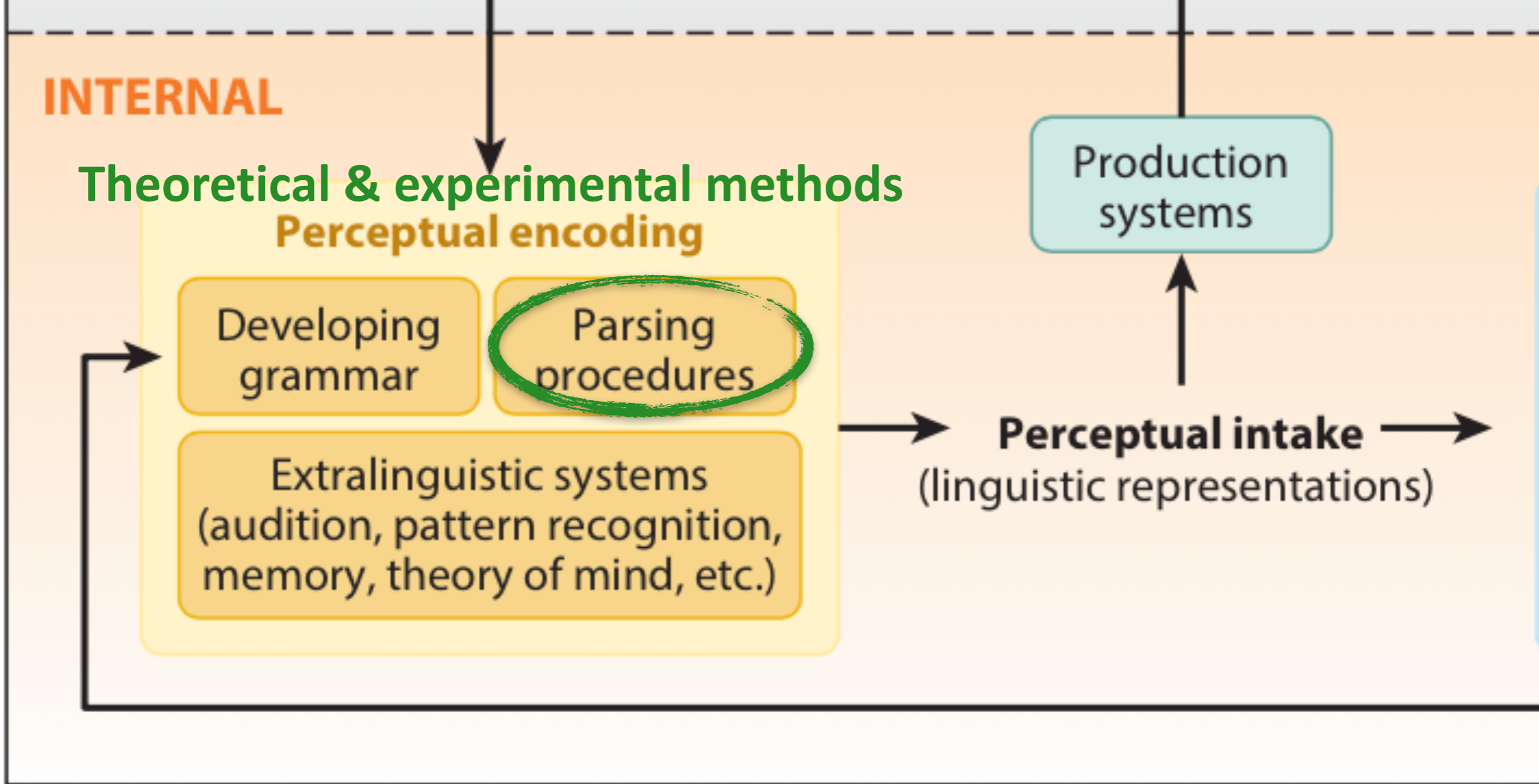
Turning the input signal into an internal linguistic representation = **perceptual intake**.



Lidz & Gagliardi 2015



Perceptual encoding:
Involves **current grammar**

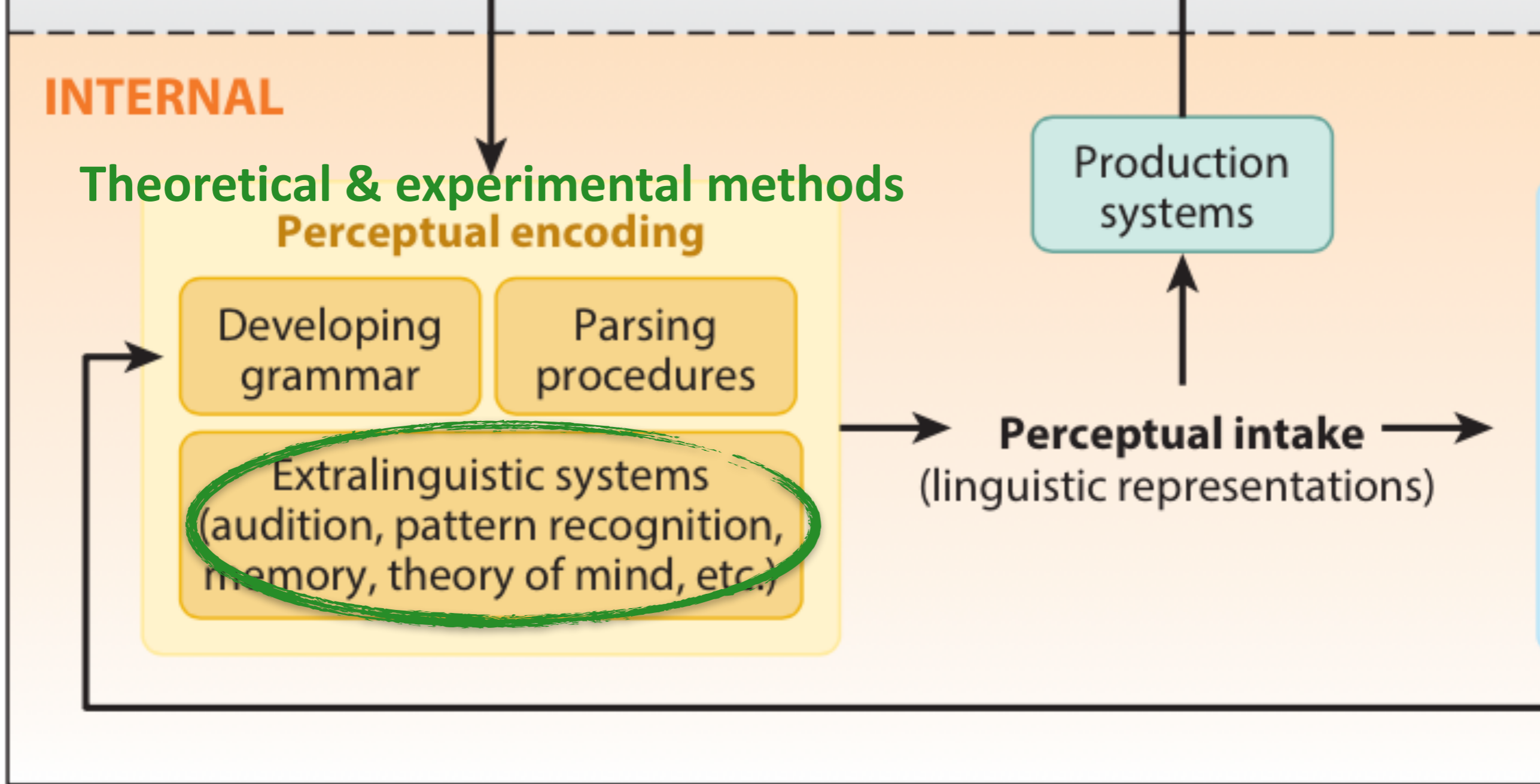


Lidz & Gagliardi 2015

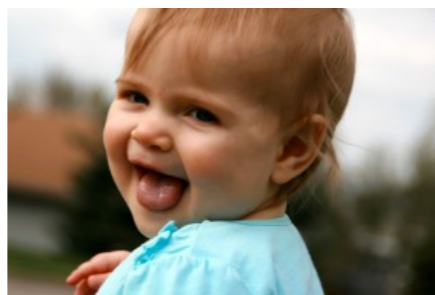


Perceptual encoding:

Involves current grammar being **deployed in real time to parse** the input

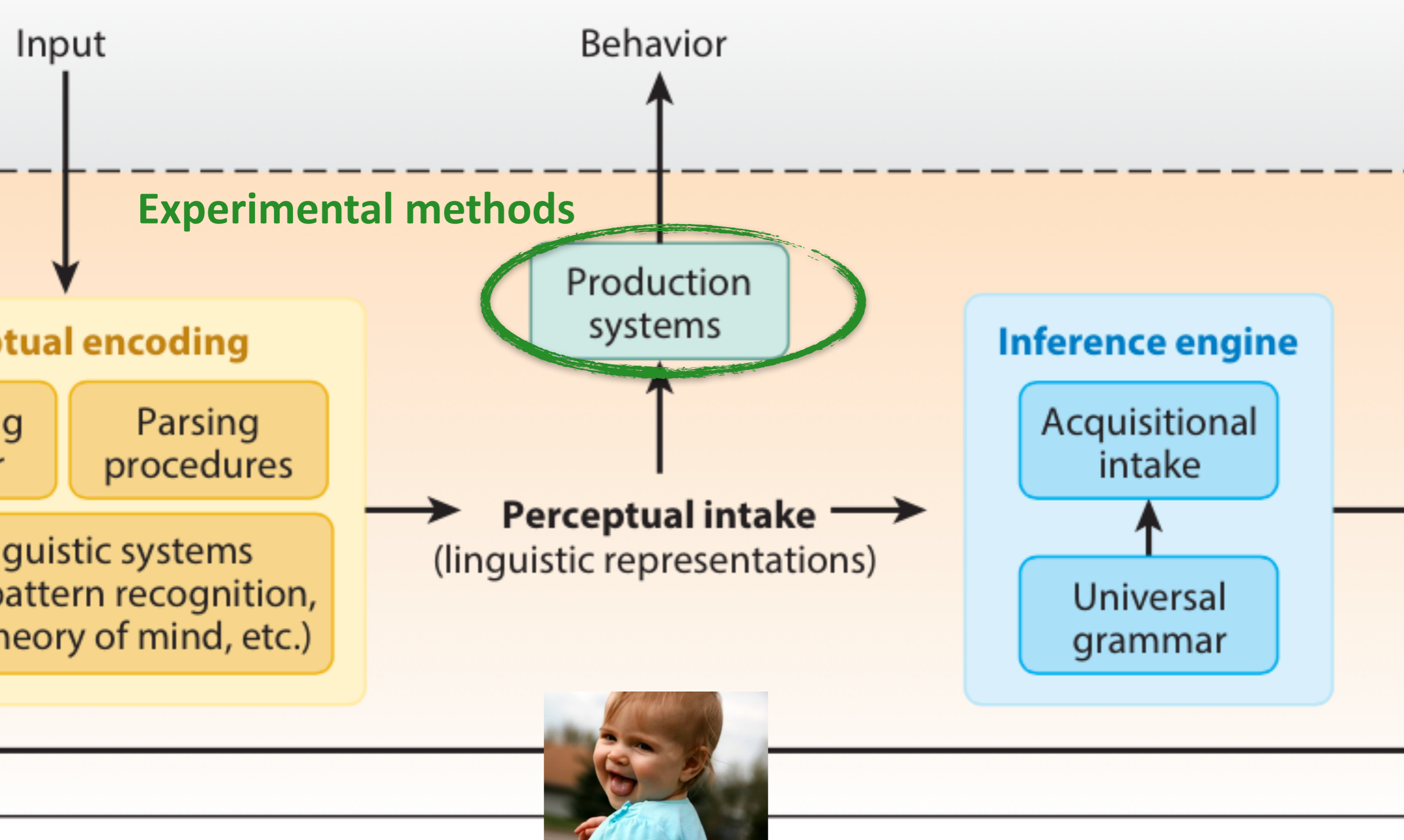


Lidz & Gagliardi 2015



Perceptual encoding:

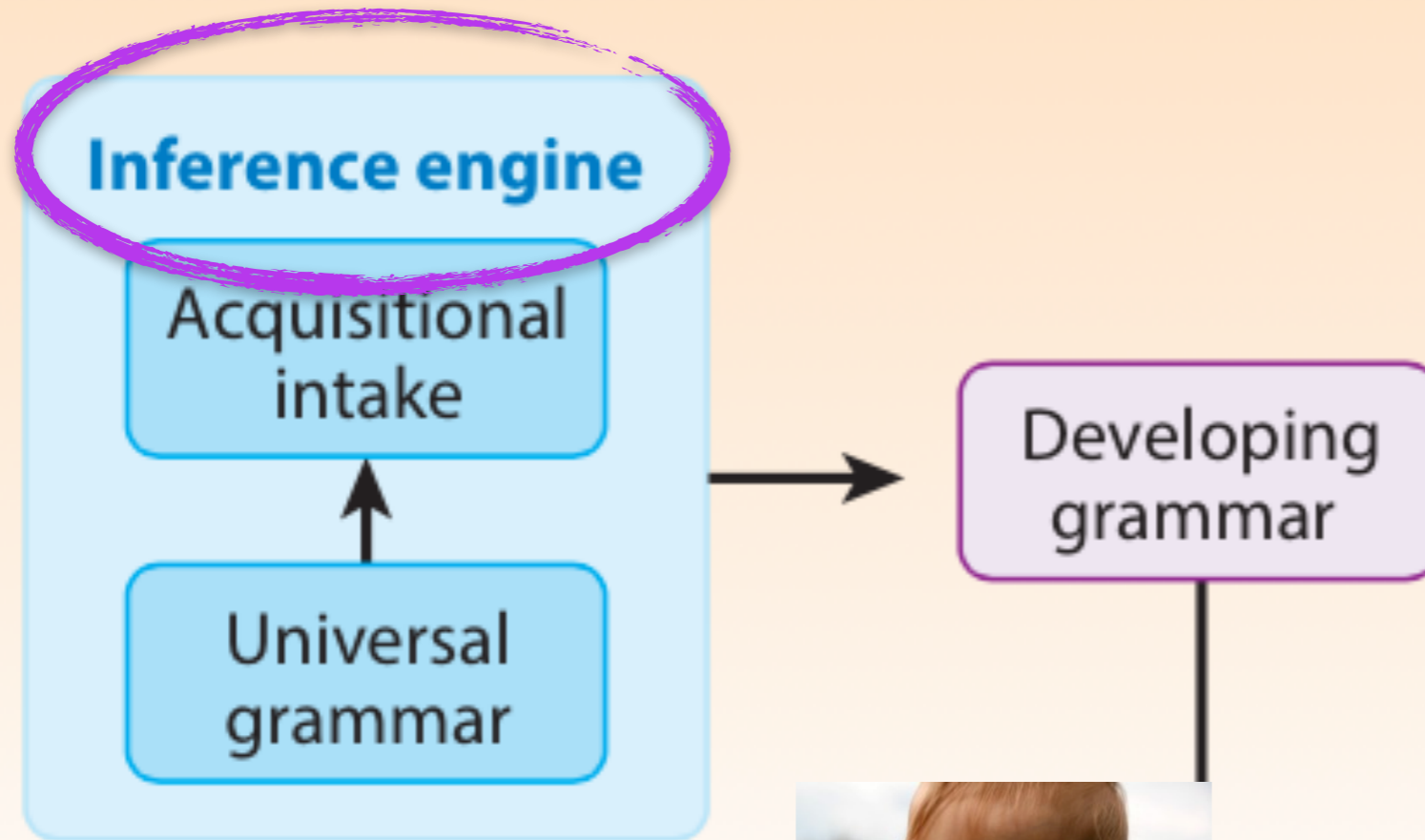
Involves current grammar being deployed in real time to parse the input, often drawing on **extralinguistic systems**



Generating observable **behavior**

Involves current linguistic representations being used by **production systems**.

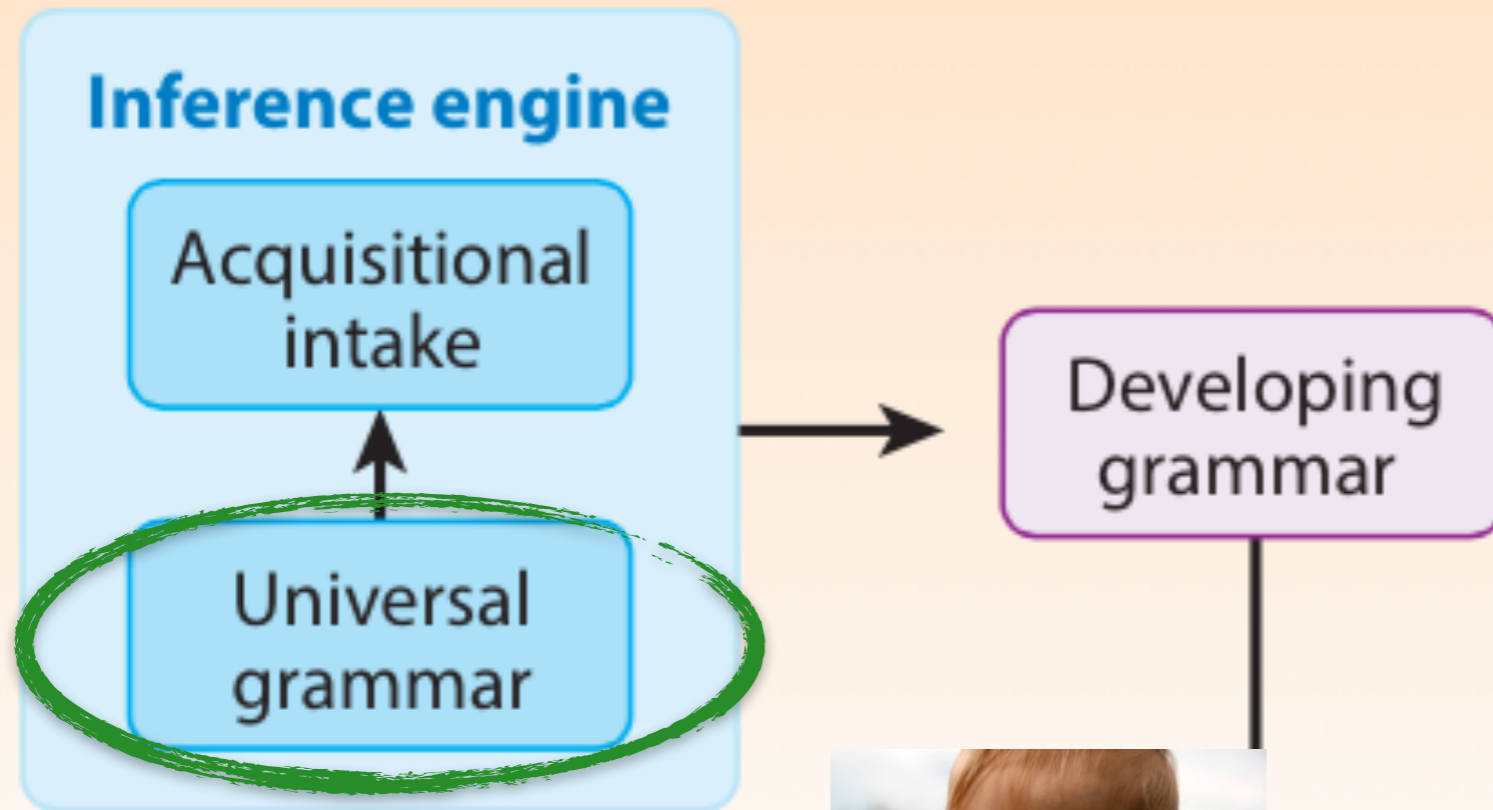
Experimental & computational methods



Doing **inference**

Generalization happens

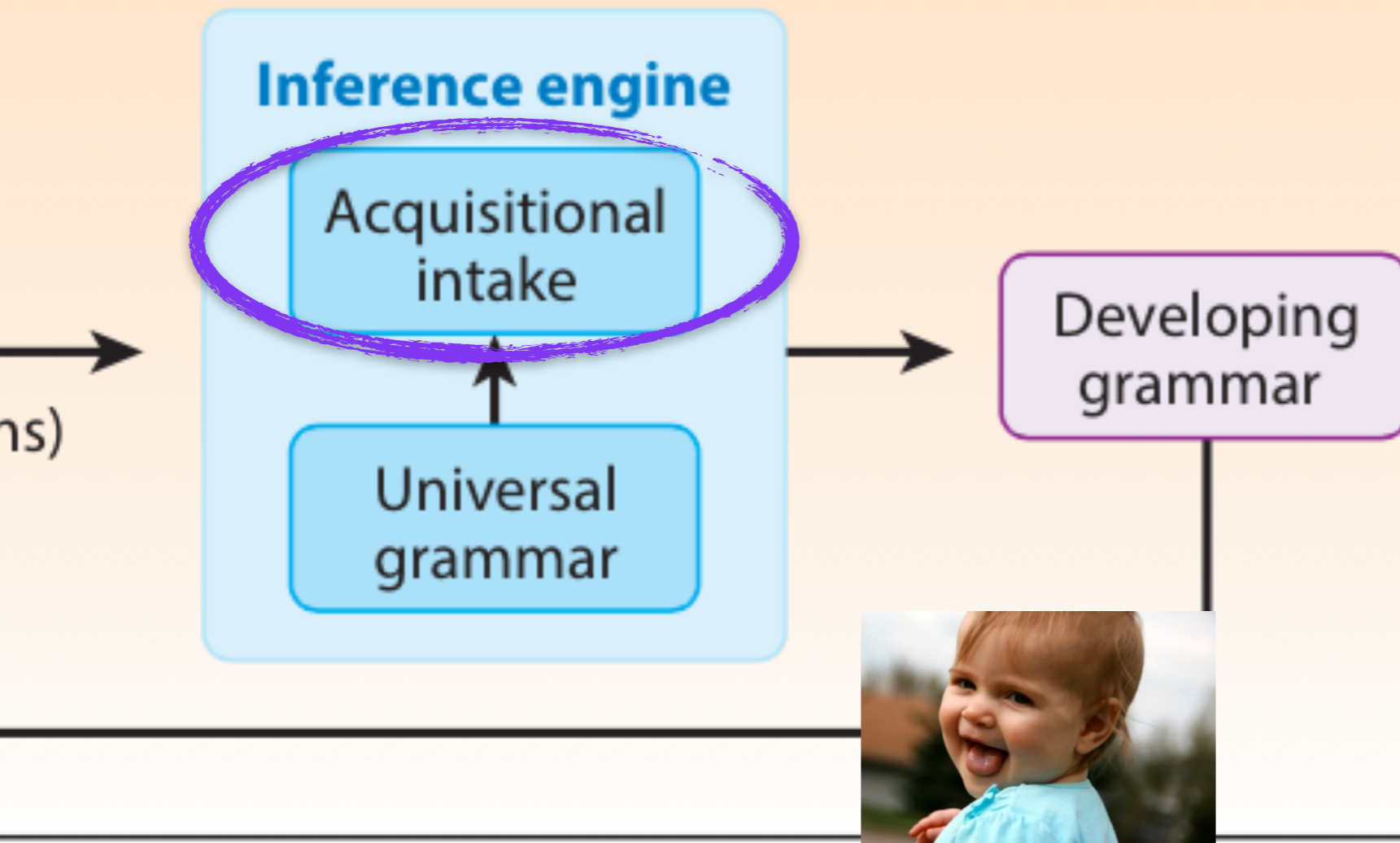
Theoretical & computational methods



Doing inference

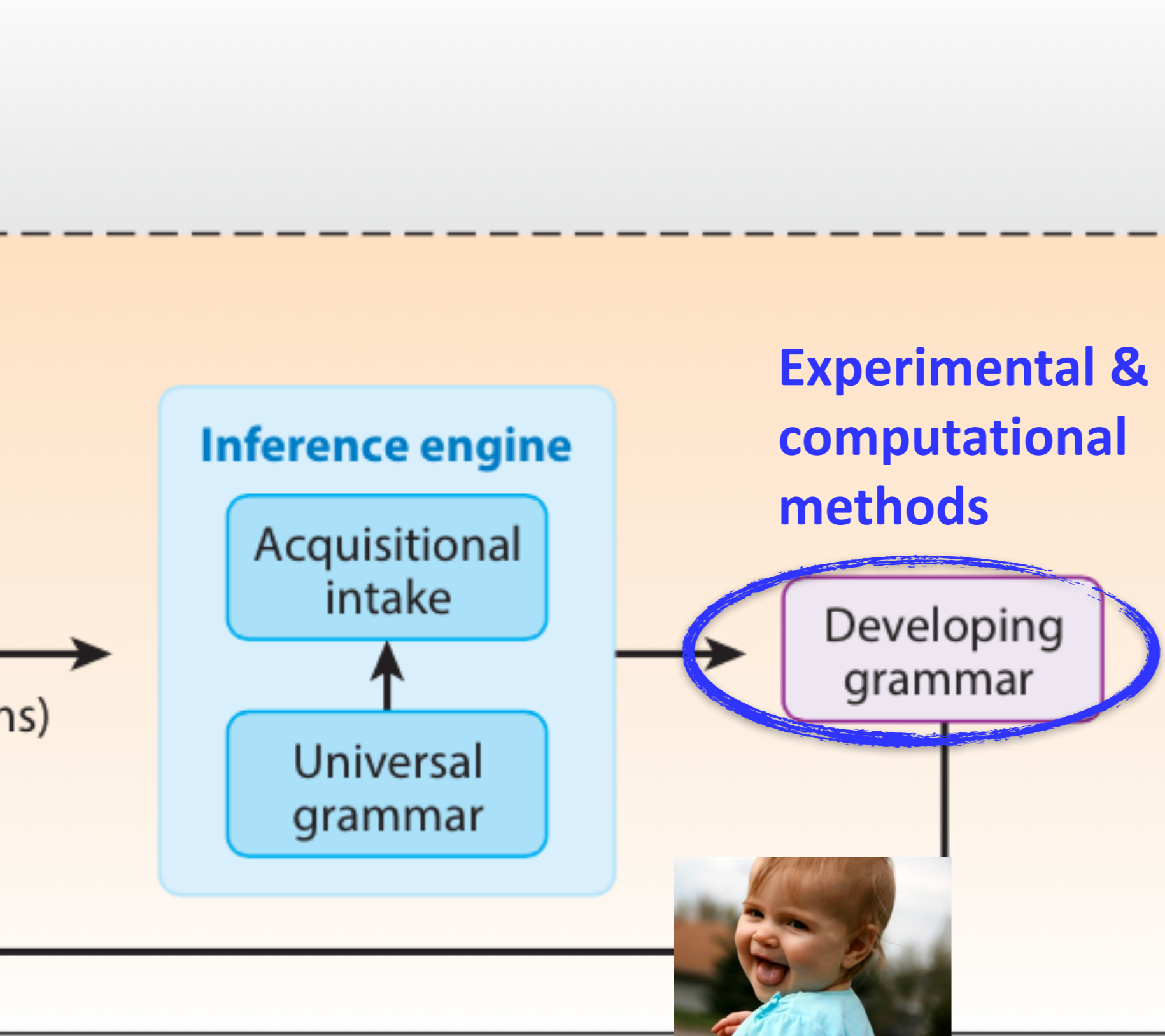
Generalization happens by using **existing learning biases**, (some of which may be innate and language-specific)

Theoretical & computational methods



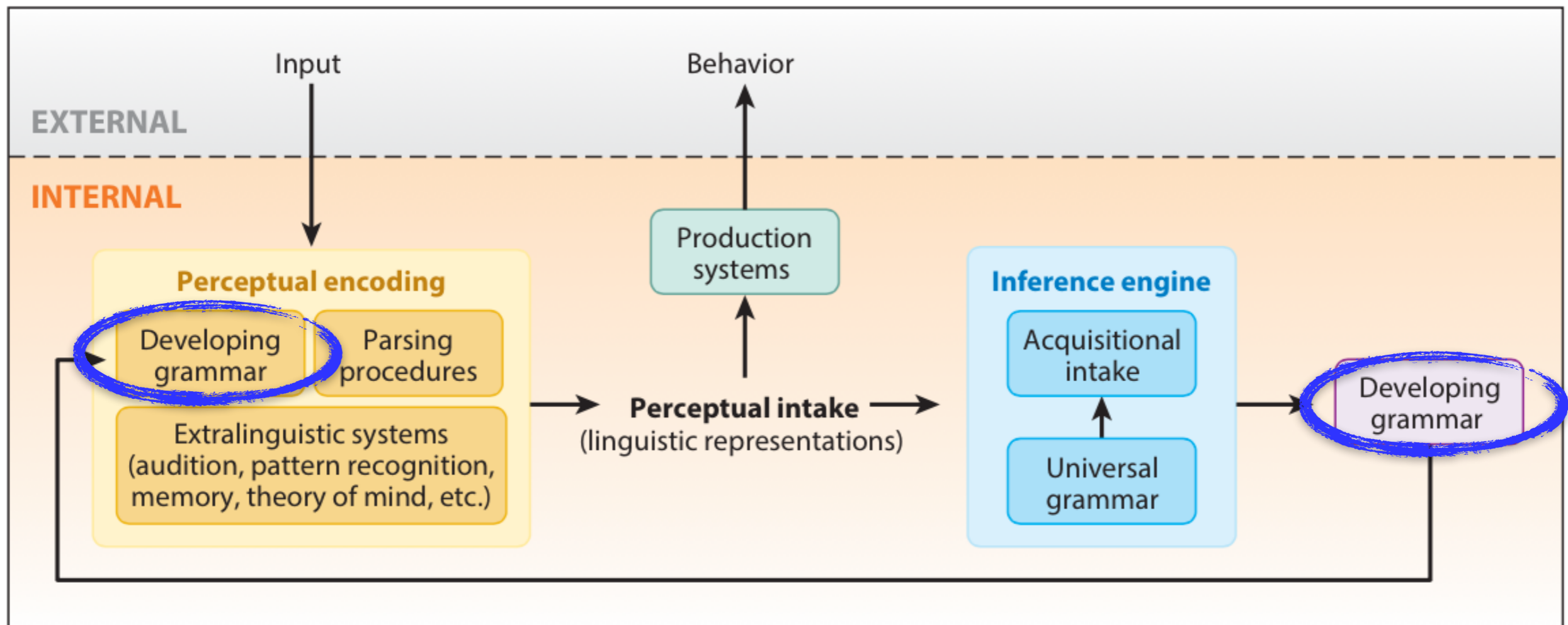
Doing inference

Generalization happens by using existing learning biases, (some of which may be innate and language-specific) operating over the **acquisitional intake** — what's perceived as relevant for acquisition

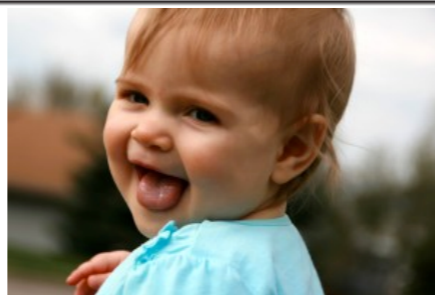


Doing inference

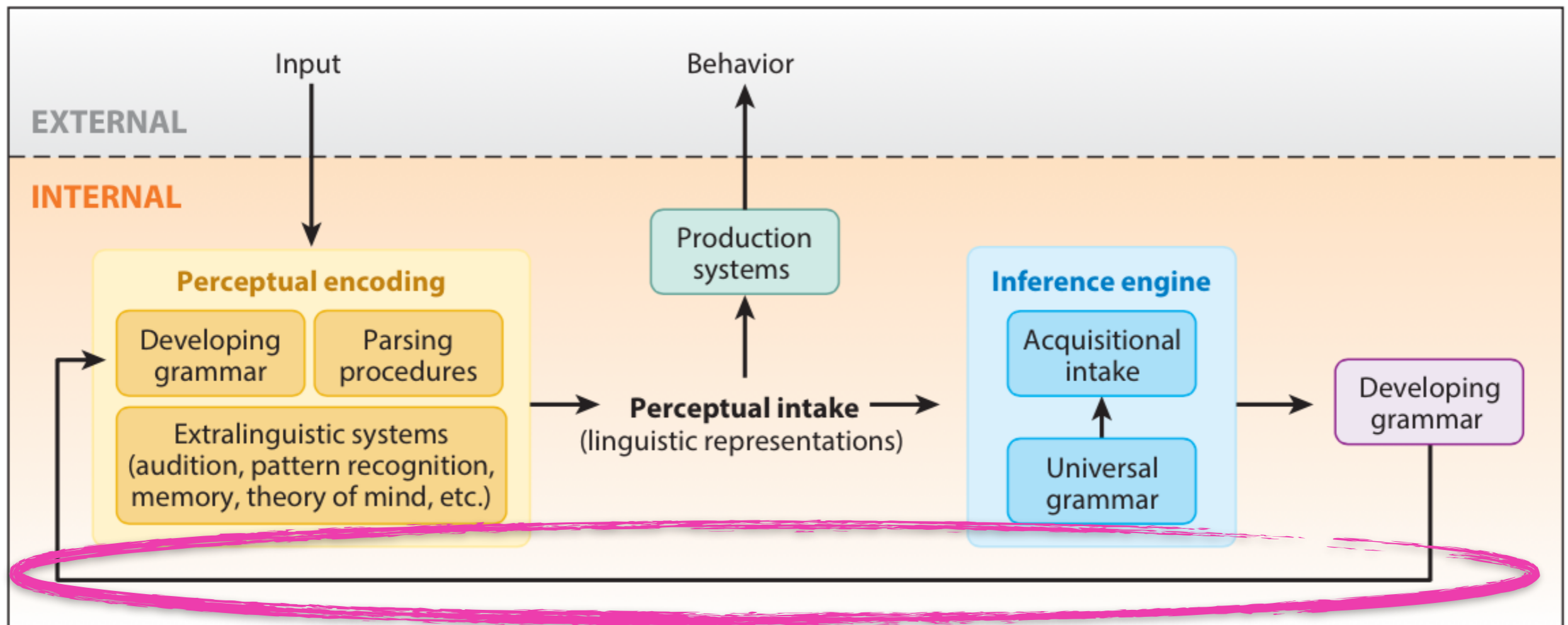
Generalization happens by using existing learning biases, (some of which may be innate and language-specific) operating over the acquisitional intake — what's perceived as relevant for acquisition to produce the most **up-to-date hypotheses** about linguistic knowledge



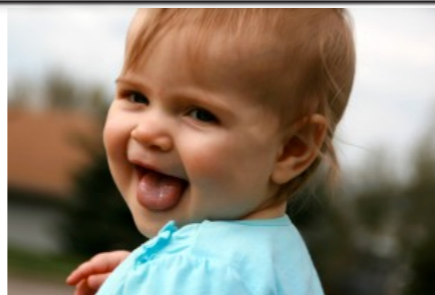
Lidz & Gagliardi 2015



The current linguistic hypotheses are
used in subsequent perceptual encoding



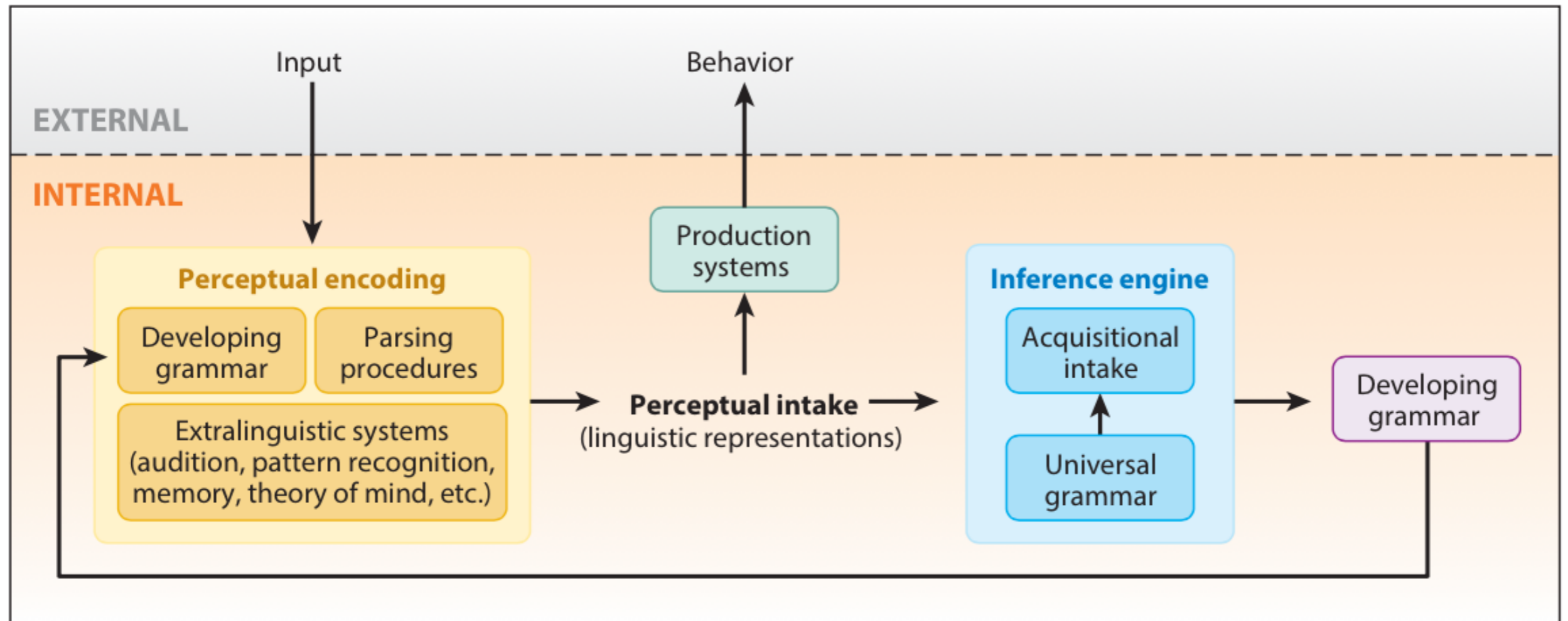
Lidz & Gagliardi 2015



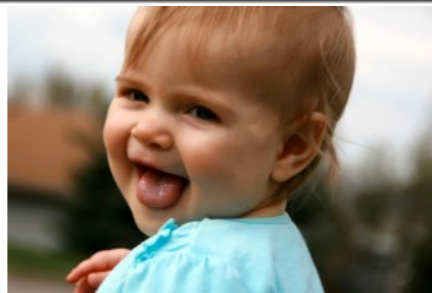
Experimental methods

This whole process happens over and over again throughout the **learning period**

This is language acquisition



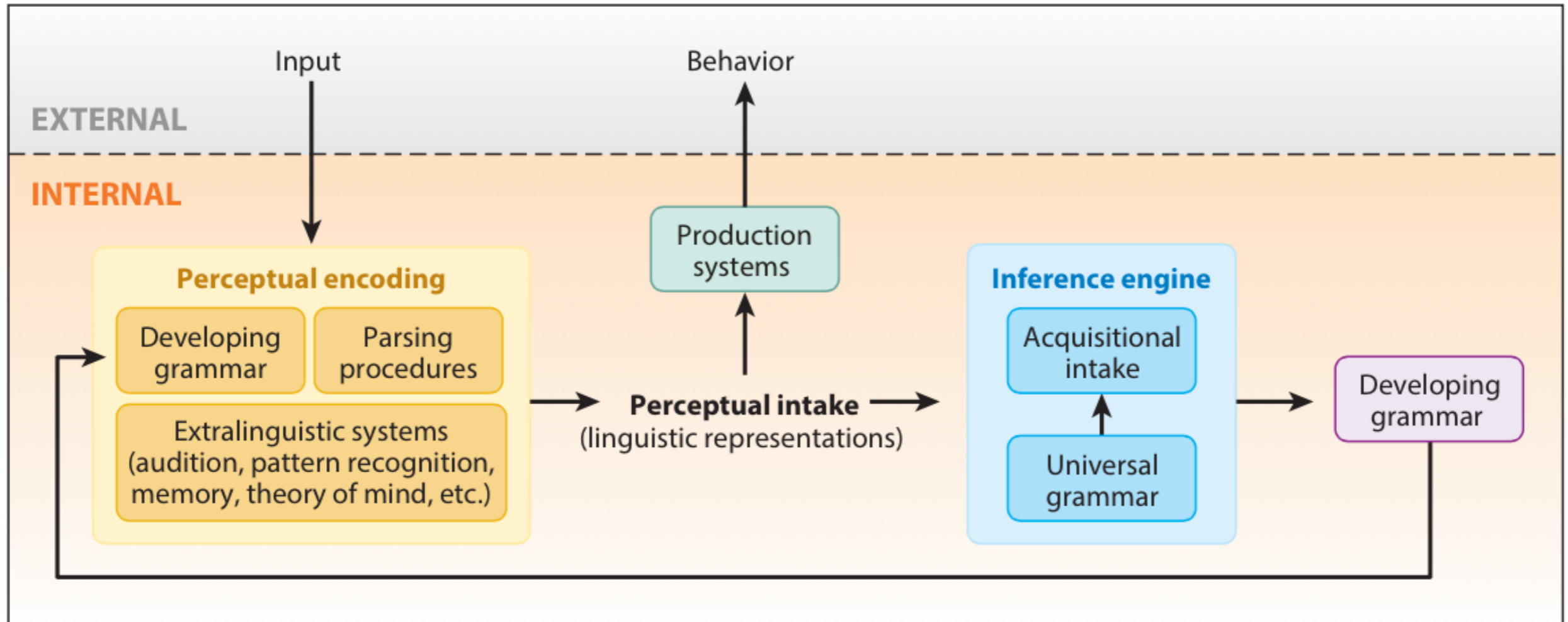
Lidz & Gagliardi 2015



Corpus Experimental
Theoretical Computational

An informative computational model of language acquisition captures these important pieces in an **empirically-grounded** way.

This is language acquisition



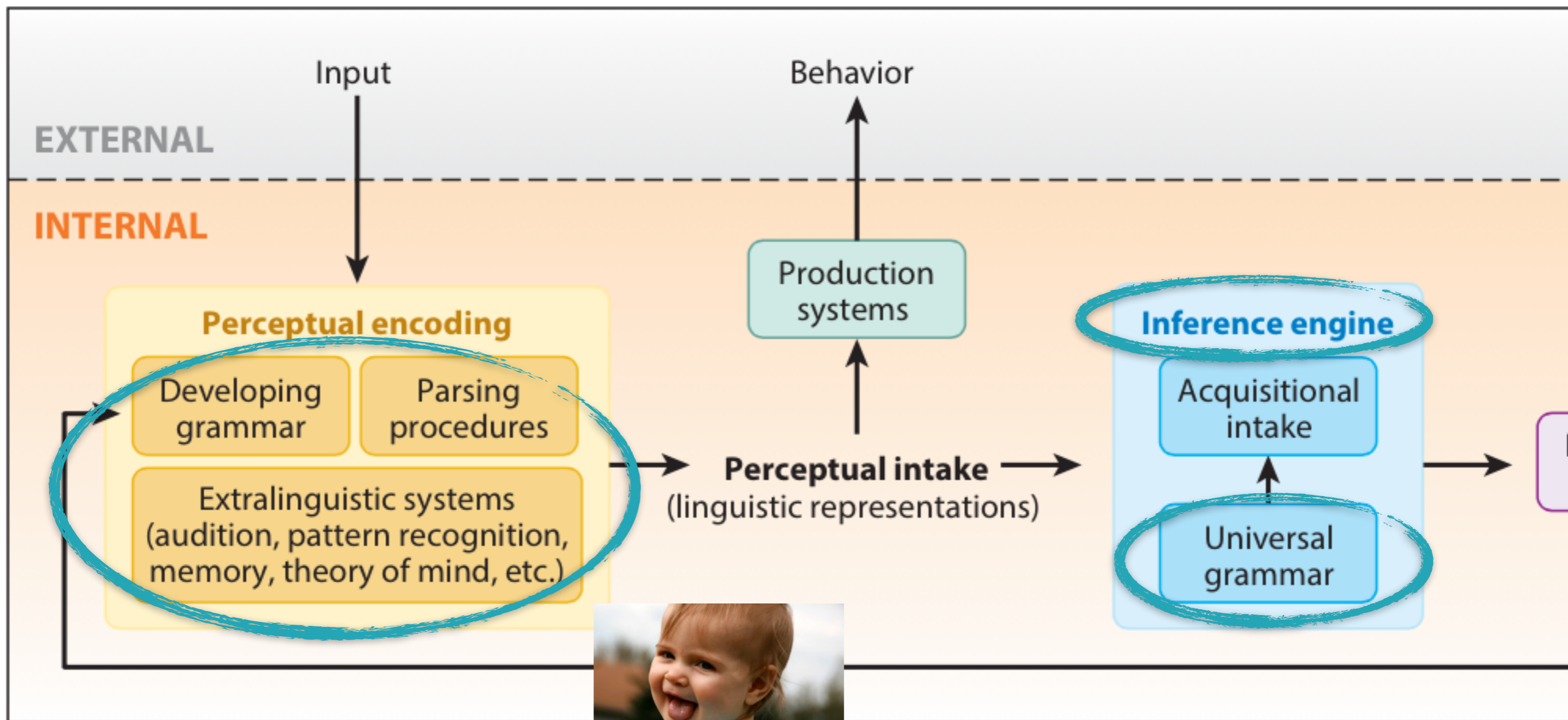
Lidz & Gagliardi 2015



Informative computational models =
informative about **the learning strategies children use**

Learning strategies children use

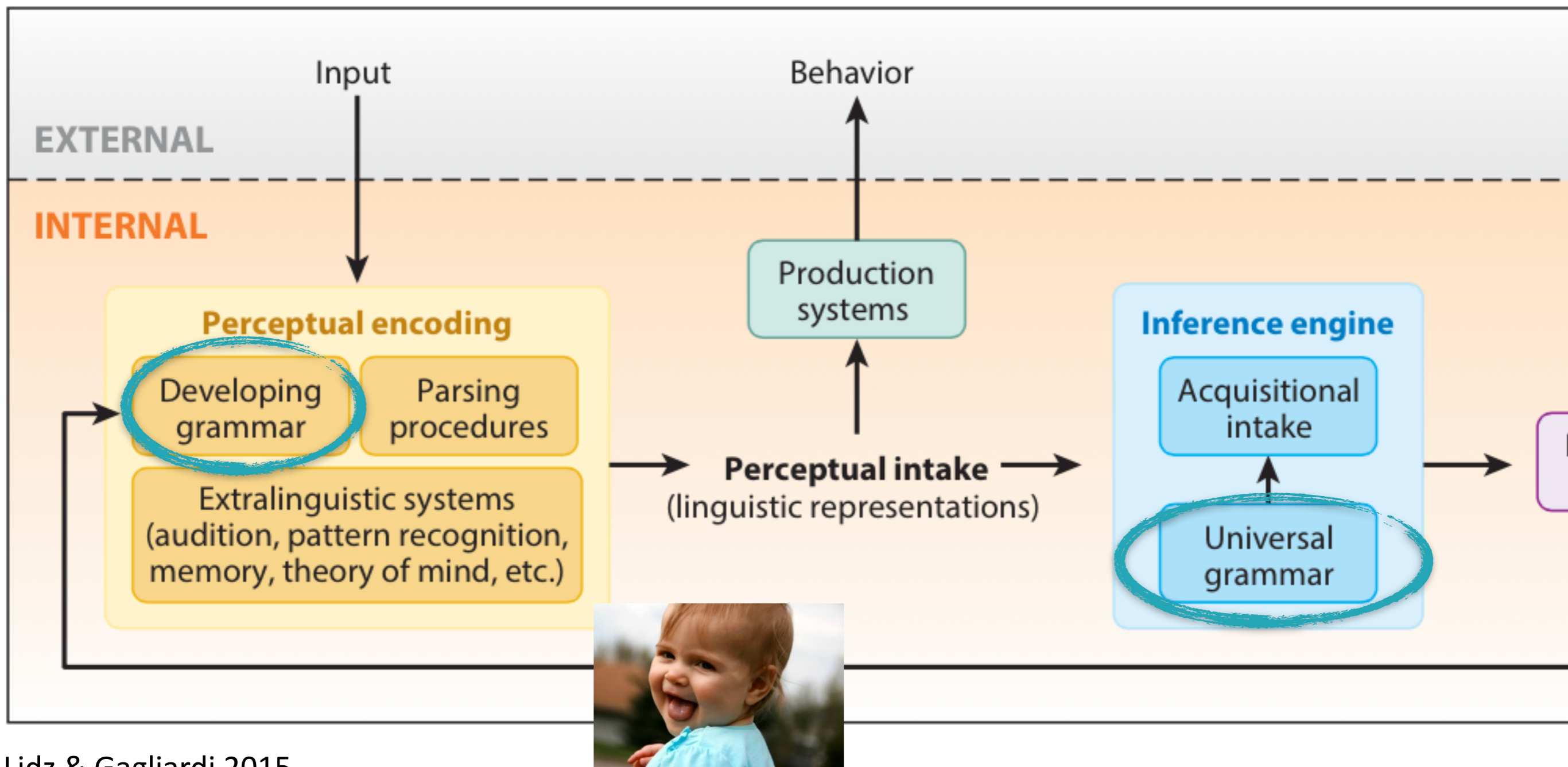
A successful learning strategy is an existence proof that linguistic knowledge is attainable using **the knowledge, learning biases, and capabilities comprising that strategy.**



Learning strategies children use

Important learning strategy components include

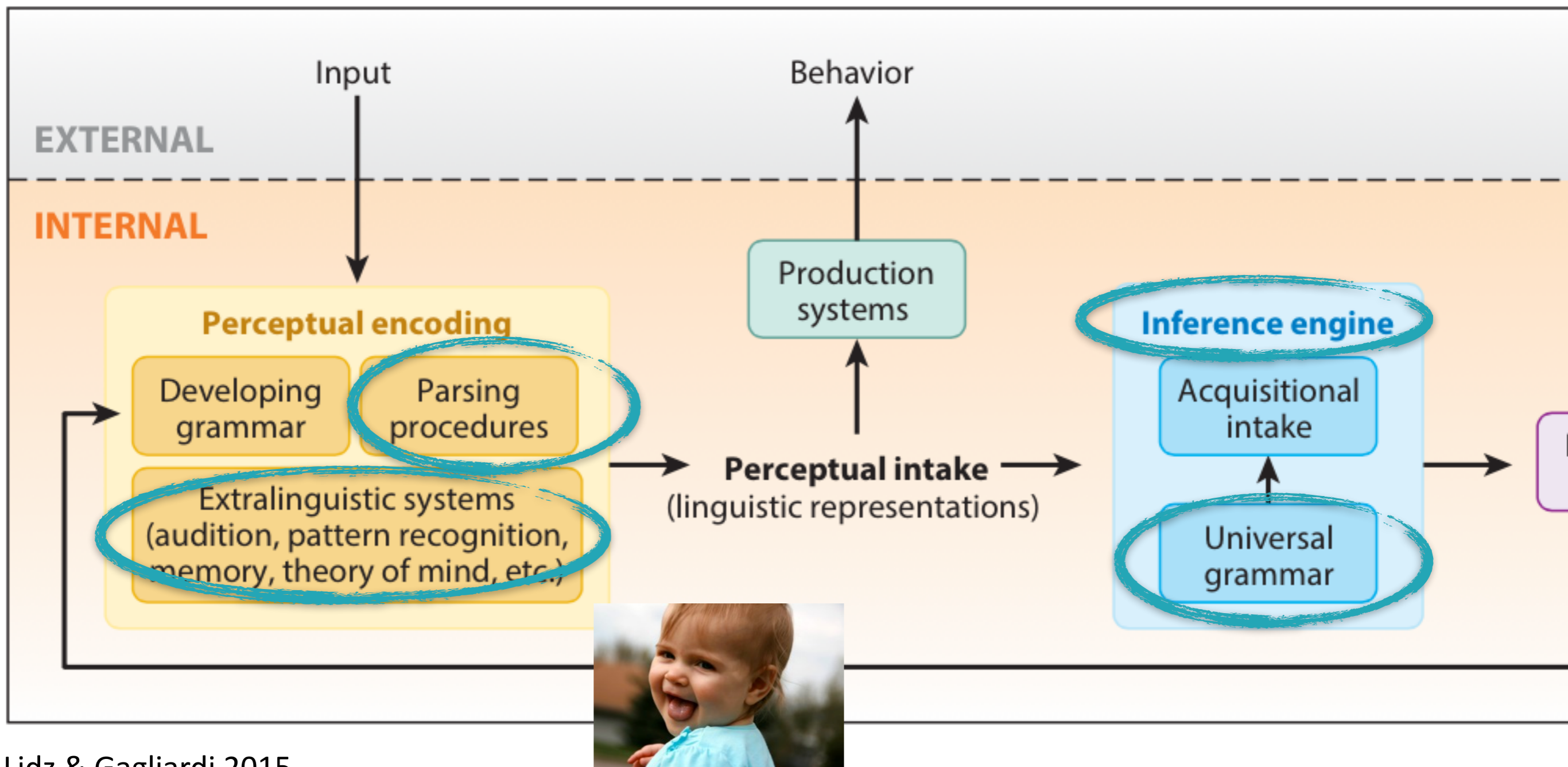
- knowledge (= theories of **representation**)



Learning strategies children use

Important learning strategy components include

- theories of **representation**
- biases & capabilities that must exist for that knowledge to be successfully deployed during acquisition (= theories of the **learning process**).



Learning strategies children use

theories of **representation**

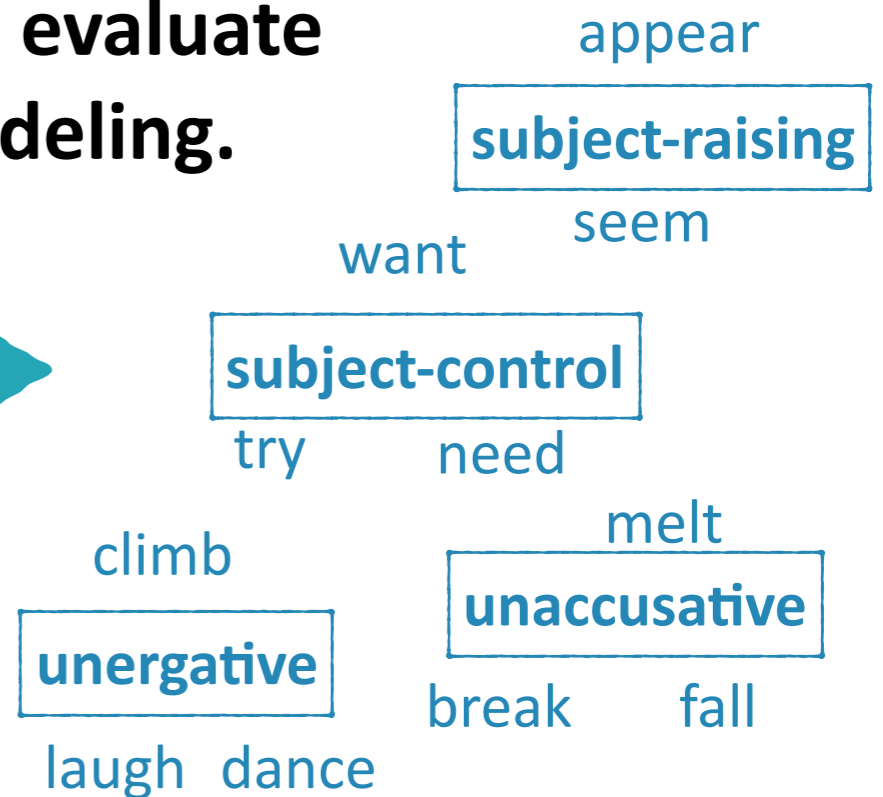
theories of the **learning process**

This is what we want to evaluate with computational modeling.

The penguin tried to climb.



The ice seemed to melt.



Today's plan

Verb classes



done-to

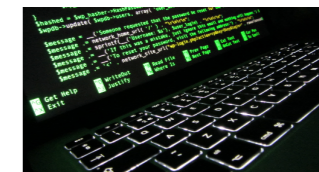
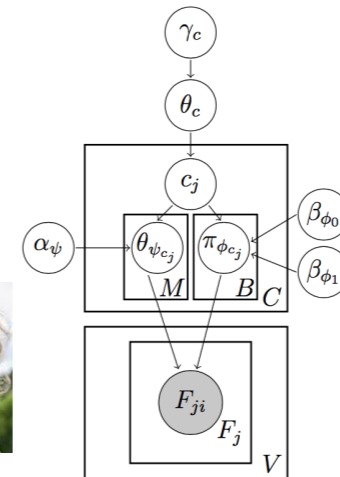
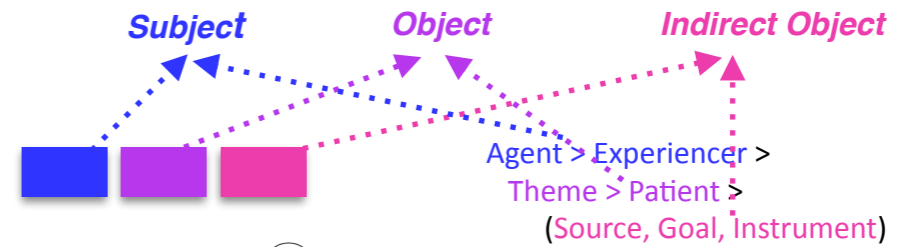
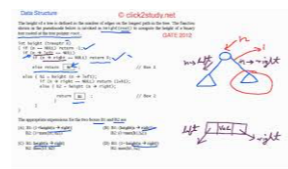
The ice melted.

The penguin climbed.

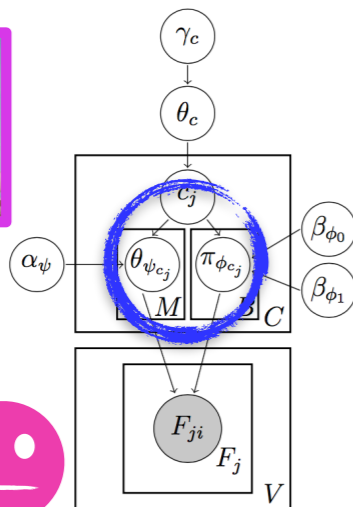
doer



Computational modeling

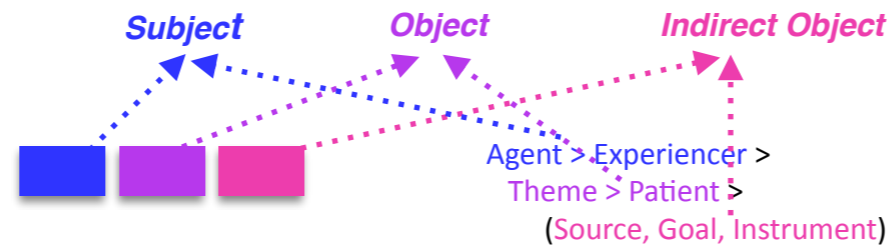


Results & implications



Today's plan

Computational modeling



Information available and how to use it

Information available

The penguin tried
to climb.



The ice seemed
to melt.



want
subject-control

try need

climb

unergative

laugh dance

appear
subject-raising

seem

melt

unaccusative

break fall

Syntactic cues

Syntactic frame **Shallow “syntactic skeleton” (Gutman et al. 2015)**

Children are very adept at using **syntactic bootstrapping** to learn useful generalizations about how verbs behave (e.g., Fisher et al. 2010, Gutman et al. 2015, Harrigan et al. 2016).

Information available



The ice seemed to melt.



Syntactic cues

Syntactic frame

The penguin **tried** to climb.

NP _____ S_{nonfinite} -surface morphology
NP _____+past S_{nonfinite} +surface morphology

Information available



Syntactic frame

NP _____ S_{nonfinite} -surfmorph
 NP _____+past S_{nonfinite} +surfmorph

Conceptual cues Animacy

+animate



The penguin tried
to climb.

-animate



The ice seemed
to melt.

Information available



climb
unergative
 laugh dance

melt
unaccusative
 break fall

Syntactic frame

NP _____ S_{nonfinite} -surfmorph

NP _____+past S_{nonfinite} +surfmorph

Conceptual cues

Animacy

+animate
 The penguin tried
 to climb.



-animate
 The ice seemed
 to melt.



Becker 2009, Kirby 2009, Kirby 2010,
 Becker 2014, Becker 2015, Hartshorne et al. 2015

appear seem

subject-raising

ask beg

object-raising

It's useful:

It can distinguish verb classes like
 raising vs. control verbs, and psych
 object-experiencer verbs.

try

subject-control

want

need

object-control

believe

surprise

psych object-experiencer

annoy

worry

Information available



want
subject-control

try need

climb

unergative

laugh dance

appear
subject-raising

seem

melt

unaccusative

break fall

Syntactic frame

NP _____ S_{nonfinite} -surfmorph

NP _____+past S_{nonfinite} +surfmorph

Conceptual cues

Animacy

+animate

The penguin tried
to climb.



-animate

The ice seemed
to melt.



Becker 2009, Kirby 2009, Kirby 2010,
Becker 2014, Becker 2015, Hartshorne et al. 2015

Children use it:

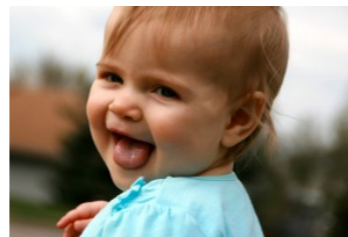
Young children have been shown to use
this cue in experimental studies.



Information available

The penguin tried
to climb.

The ice seemed
to melt.



want
subject-control

try need

climb

unergative

laugh dance

appear

subject-raising

seem

melt

unaccusative

break fall

Syntactic frame

NP ____ S_{nonfinite} -surfmorph

NP ____+past S_{nonfinite} +surfmorph

Animacy

+animate

The penguin tried
to climb.



-animate

The ice seemed
to melt.



Conceptual cues

Thematic roles

Children could use them:

Thematic roles that indicate event participant roles are salient to very young children.

(<10 months: Gordon 2003; 6 months: Hamlin, Wynn, & Bloom 2007, Hamlin, Wynn, Bloom, & Mahajan 2011)



doer = Agent



done-to = Patient



Information available

Conceptual cues + Syntactic-semantic knowledge
Thematic roles and how to use them

Syntax

She melted the ice with a blow dryer.

Subject

Object

Indirect Object



Syntactic frame

NP ____ S_{nonfinite} -surfmorph

NP ____+past S_{nonfinite} +surfmorph

Animacy

+animate

The penguin tried
to climb.



-animate

The ice seemed
to melt.



How do we get from here to here?



Thematic roles Agent, Experiencer, Patient, Theme, Goal, Source, Instrument...

Information available

Conceptual cues + Syntactic-semantic knowledge
Thematic roles and how to use them

Syntax

She melted the ice with a blow dryer.

Subject

Object

Indirect Object



Syntactic frame

NP ____ S_{nonfinite} -surfmorph

NP ____+past S_{nonfinite} +surfmorph

Animacy

+animate

The penguin tried to climb.



-animate

The ice seemed to melt.



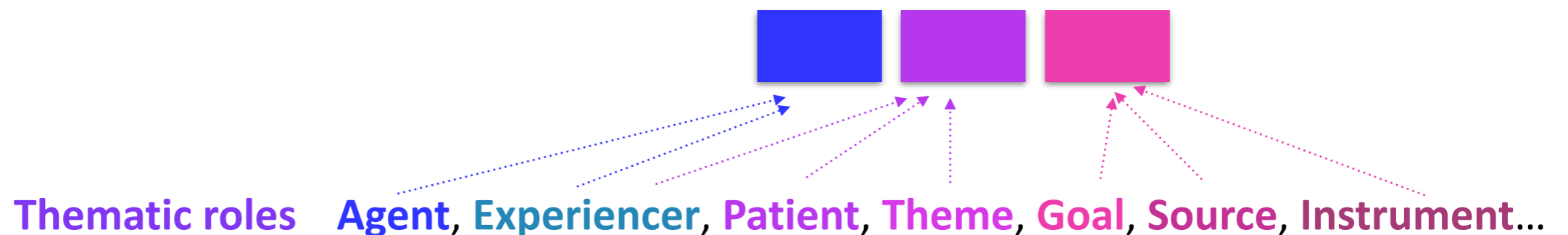
Theories of prior knowledge

Intermediate representations

Thematic roles map to one of three categories.

The **U**niformity of **T**heta **A**ssignment **H**ypothesis

Baker 1988, Baker 1997, Dowty 1991, Fillmore 1968, Grimshaw 1990, Jackendoff 1987, Perlmutter & Postal 1984, Speas 1990



Information available

Conceptual cues + Syntactic-semantic knowledge
Thematic roles and how to use them



Syntax

She melted the ice with a blow dryer.

Subject

Object

Indirect Object

Syntactic frame

NP ____ S_{nonfinite} -surfmorph

NP ____+past S_{nonfinite} +surfmorph

Animacy

+animate

The penguin tried to climb.



-animate

The ice seemed to melt.



Mapping to Syntax

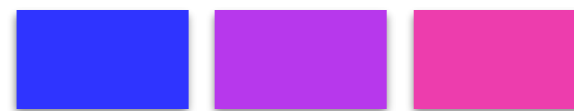
Theories of prior knowledge

Intermediate representations

These categories map to syntactic positions.

Thematic roles map to one of three categories.

UTAH



Thematic roles Agent, Experiencer, Patient, Theme, Goal, Source, Instrument...

Information available

Conceptual cues + Syntactic-semantic knowledge
Thematic roles and how to use them

Syntax

She melted the ice with a blow dryer.

Subject

Object

Indirect Object



Syntactic frame

NP ____ S_{nonfinite} -surfmorph

NP ____+past S_{nonfinite} +surfmorph

Animacy

+animate

The penguin tried to climb.



-animate

The ice seemed to melt.



Mapping to Syntax

Theories of prior knowledge

Intermediate representations

UTAH

Thematic roles are ordered with respect to each other.

The (relativized) UTAH

Larson 1988, Larson 1990

Agent > Experiencer >

Theme > Patient >

(Source, Goal, Instrument)

Thematic roles Agent, Experiencer, Patient, Theme, Goal, Source, Instrument...

Information available

Conceptual cues + Syntactic-semantic knowledge
Thematic roles and how to use them



Syntax

She melted the ice with a blow dryer.

Subject

Object

Indirect Object

Syntactic frame

NP _____ S_{nonfinite} -surfmorph

NP _____+past S_{nonfinite} +surfmorph

Animacy

+animate

The penguin tried to climb.



-animate

The ice seemed to melt.



Mapping to Syntax

Theories of prior knowledge

Intermediate representations

Whichever ones are present map in order to syntactic positions.

UTAH

rUTAH

Agent > Experiencer >

Theme > Patient >

(Source, Goal, Instrument)

Thematic roles Agent, Experiencer, Patient, Theme, Goal, Source, Instrument...

Information available

Conceptual cues + Syntactic-semantic knowledge
Thematic roles and how to use them

Syntax

She melted the ice with a blow dryer.

Subject

Object

Indirect Object



Syntactic frame

NP _____ S_{nonfinite} -surfmorph

NP _____+past S_{nonfinite} +surfmorph

Animacy

+animate

The penguin tried to climb.



-animate

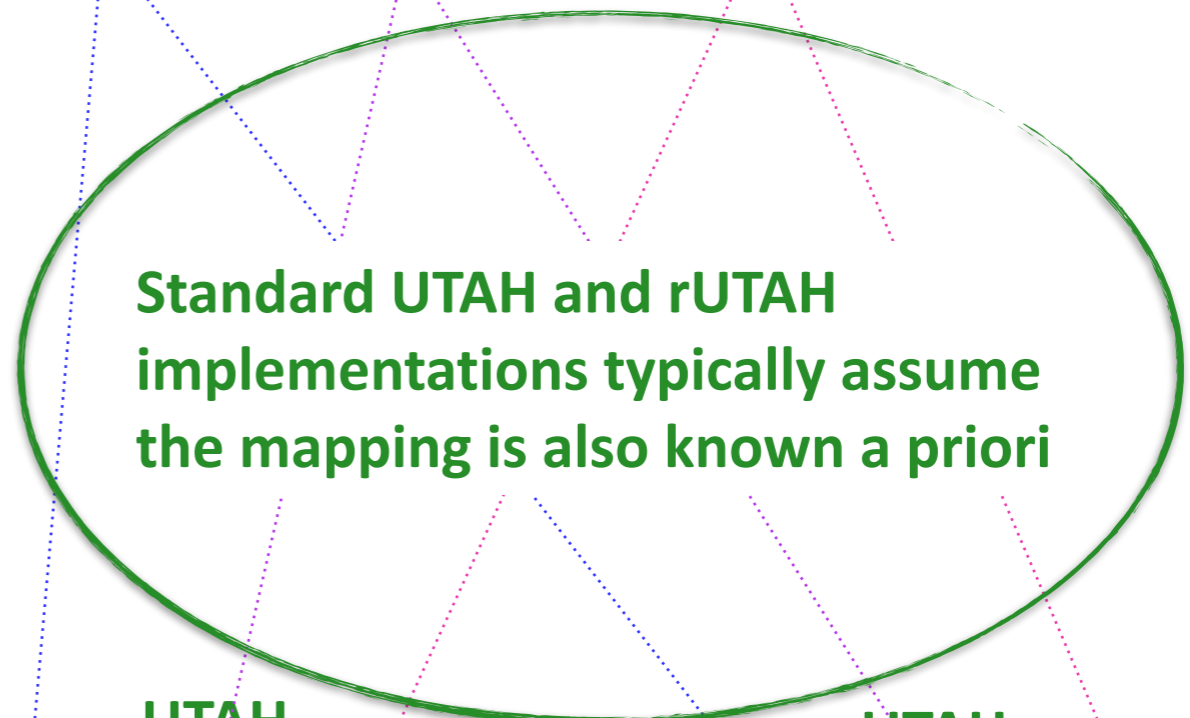
The ice seemed to melt.



Mapping to Syntax

Theories of prior knowledge

Intermediate representations



UTAH

rUTAH

Agent > Experiencer >
Theme > Patient >
(Source, Goal, Instrument)

Thematic roles Agent, Experiencer, Patient, Theme, Goal, Source, Instrument...

Information available

Conceptual cues + Syntactic-semantic knowledge
Thematic roles and how to use them

Syntax

She melted the ice with a blow dryer.

Subject

Object

Indirect Object



Syntactic frame

NP _____ S_{nonfinite} -surfmorph

NP _____+past S_{nonfinite} +surfmorph

But these are separate components

Mapping to Syntax

Animacy

+animate

The penguin tried to climb.



-animate

The ice seemed to melt.



Theories of prior knowledge

Intermediate representations

UTAH

rUTAH

Agent > Experiencer >

Theme > Patient >

(Source, Goal, Instrument)

Thematic roles Agent, Experiencer, Patient, Theme, Goal, Source, Instrument...

Information available

Conceptual cues + Syntactic-semantic knowledge
 Thematic roles and how to use them

Syntax

She melted the ice with a blow dryer.

Subject

Object

Indirect Object



Syntactic frame

NP _____ S_{nonfinite} -surfmorph

NP _____+past S_{nonfinite} +surfmorph

Whether children expect a mapping a priori impacts how they perceive the intake for acquisition

Mapping to Syntax

Theories of prior knowledge

Animacy

+animate

The penguin tried to climb.



-animate

The ice seemed to melt.



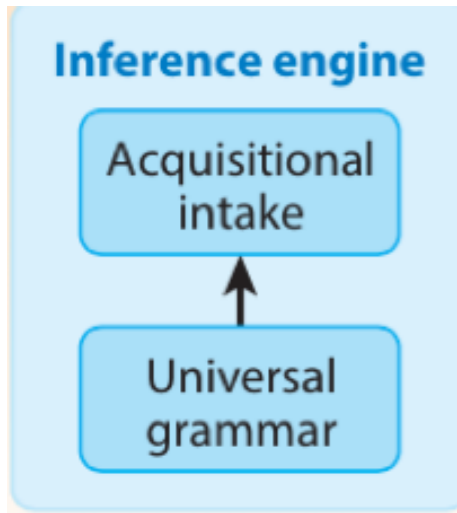
Intermediate representations

UTAH

rUTAH

Agent > Experiencer >
 Theme > Patient >
 (Source, Goal, Instrument)

Thematic roles Agent, Experiencer, Patient, Theme, Goal, Source, Instrument...



Information available

+expect a mapping

Salient when mapping doesn't hold:
Interpreted as movement



Syntax

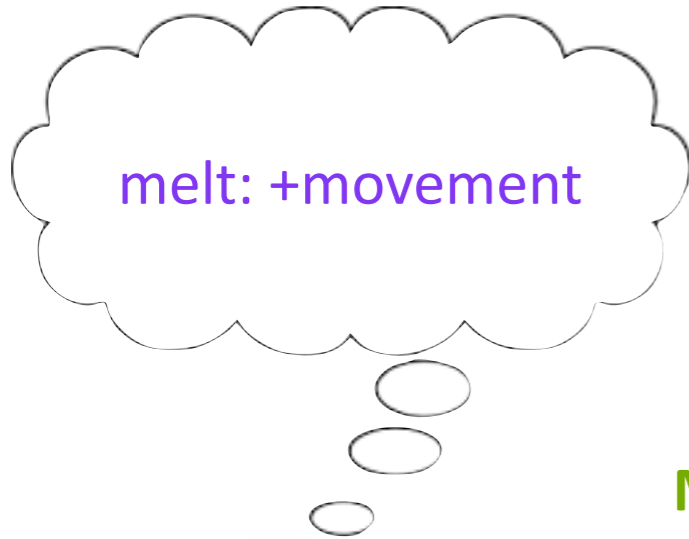
The ice was melted by the girl.

Subject

Indirect Object

done-to

doer



Mapping to Syntax

Theories of prior knowledge

Unexpected by UTAH

Intermediate representations

UTAH

rUTAH

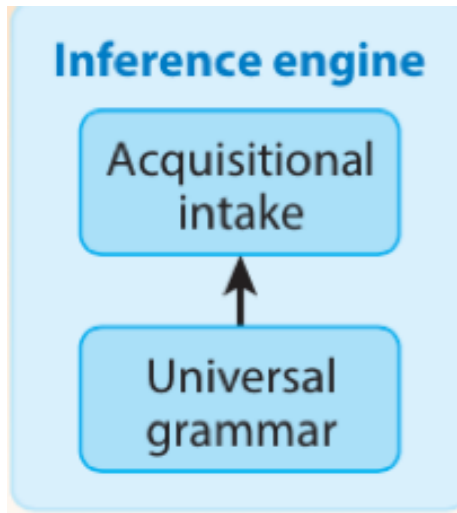
Agent > Experiencer >

Theme > Patient >

(Source, Goal, Instrument)



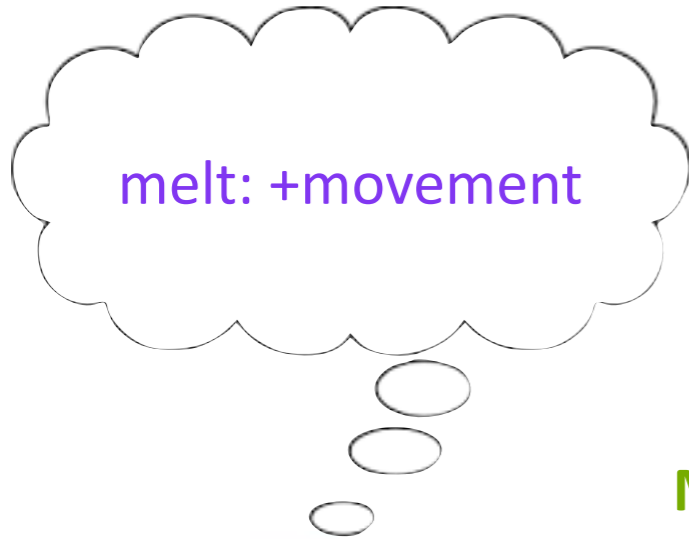
Thematic roles Agent, Experiencer, Patient, Theme, Goal, Source, Instrument...



Information available

+expect a mapping

Salient when mapping doesn't hold:
Interpreted as movement



Syntax

The ice was melted by the girl.

Subject

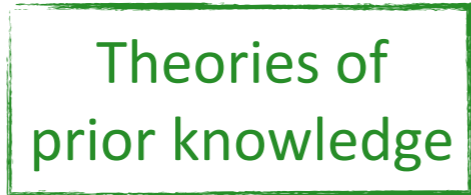
Indirect Object

2nd highest

Highest



Mapping to Syntax



Intermediate representations

UTAH

rUTAH



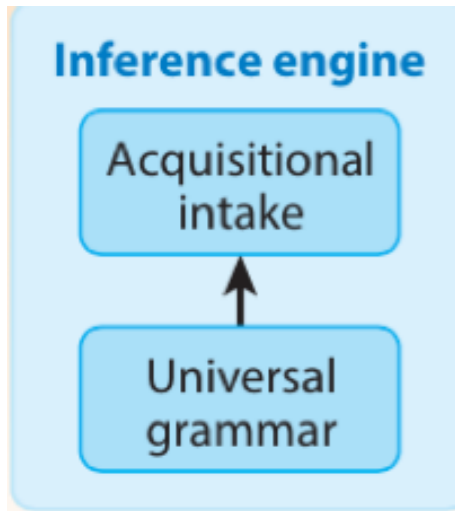
Agent > Experiencer >

Theme > Patient >

(Source, Goal, Instrument)

Thematic roles Agent, Experiencer, Patient, Theme, Goal, Source, Instrument...





Information available

-expect a mapping

Children track grammatical positions of intermediate representations

Syntax

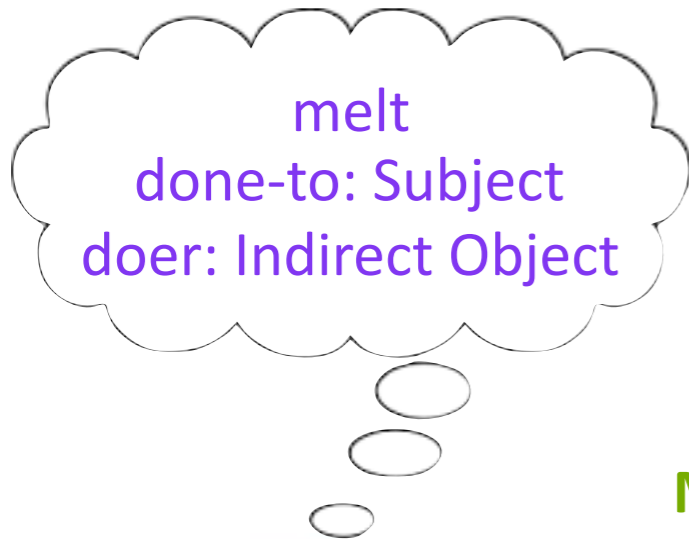
The ice was **melted** by the girl.

Subject

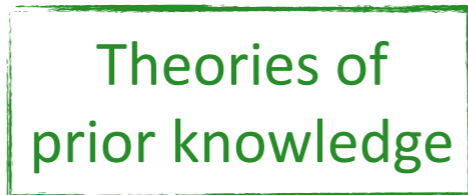
Indirect Object

done-to

doer



Mapping to Syntax



Intermediate representations

UTAH

rUTAH

Agent > Experiencer >

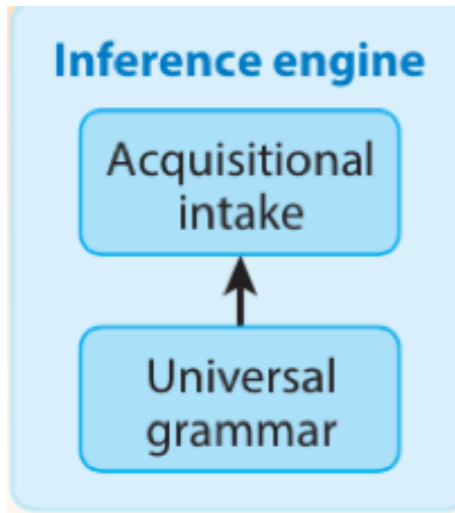
Theme > Patient >

(Source, Goal, Instrument)



Thematic roles Agent, Experiencer, Patient, Theme, Goal, Source, Instrument...





Information available

-expect a mapping Children track grammatical positions of intermediate representations

Syntax

The ice was **melted** by the girl.

Subject

Indirect Object

2nd highest

Highest



Mapping to Syntax

Theories of prior knowledge

Intermediate representations

UTAH

rUTAH

Agent > Experiencer >

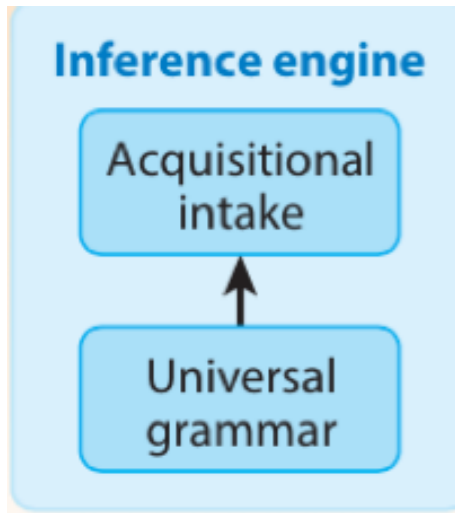
Theme > Patient >

(Source, Goal, Instrument)



Thematic roles Agent, Experiencer, Patient, Theme, Goal, Source, Instrument...





Information available

Conceptual cues + Syntactic-semantic knowledge
 Thematic roles and how to use them



Syntax

The ice was **melted** by the girl.

Subject

Indirect Object

Mapping to Syntax

+expmap

-expmap

Intermediate representations

UTAH

rUTAH

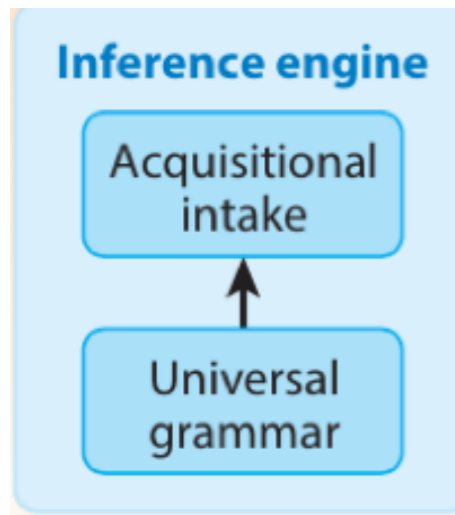
Agent > Experiencer >

Theme > Patient >

(Source, Goal, Instrument)

Thematic roles Agent, Experiencer, Patient, Theme, Goal, Source, Instrument...

Information available



Syntactic frame

NP ____ S_{nonfinite} -surfmorph
 NP ____+past S_{nonfinite} +surfmorph

Animacy

+animate

The penguin tried
to climb.



-animate

The ice seemed
to melt.



Thematic roles and how to use them

UTAH

Agent > Experiencer > rUTAH
 Theme > Patient >
 (Source, Goal, Instrument)

-expmap

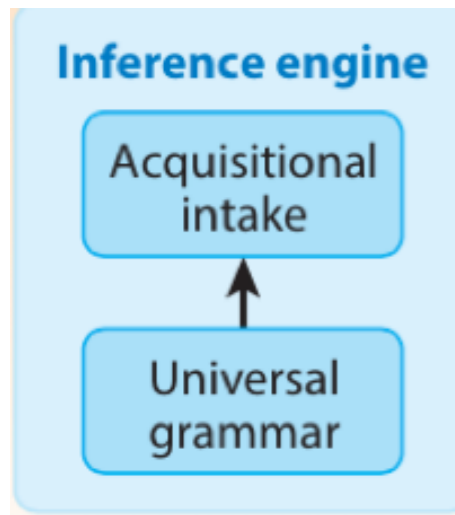
+expmap

Subject Object Indirect Object

Subject Object Indirect Object



Potential learning strategies



Animacy

+animate
The penguin tried
to climb.



-animate
The ice seemed
to melt.



Syntactic frame

NP ____ S_{nonfinite} -surfmorph
NP ____+past S_{nonfinite} +surfmorph

Thematic roles and how to use them

   UTAH

Agent > Experiencer > rUTAH
Theme > Patient >
(Source, Goal, Instrument)

-expmap

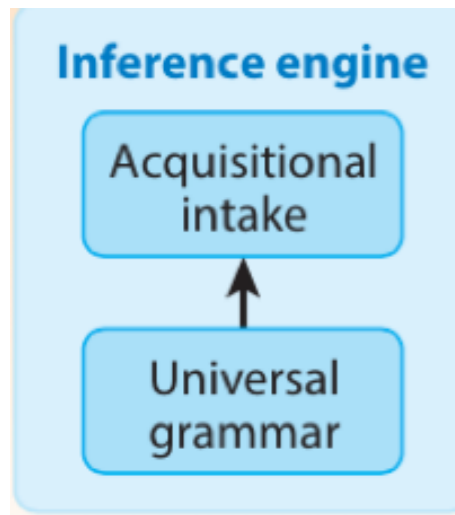
+expmap

Subject *Object* *Indirect Object*

Subject *Object* *Indirect Object*

movement?

Potential learning strategies



Animacy

+animate
The penguin tried
to climb.



-animate
The ice seemed
to melt.



Syntactic frame

Choice 1

NP _____ S_{nonfinite} -surfmorph
NP _____+past S_{nonfinite} +surfmorph

Thematic roles and how to use them

   UTAH

Agent > Experiencer > rUTAH
Theme > Patient >
(Source, Goal, Instrument)

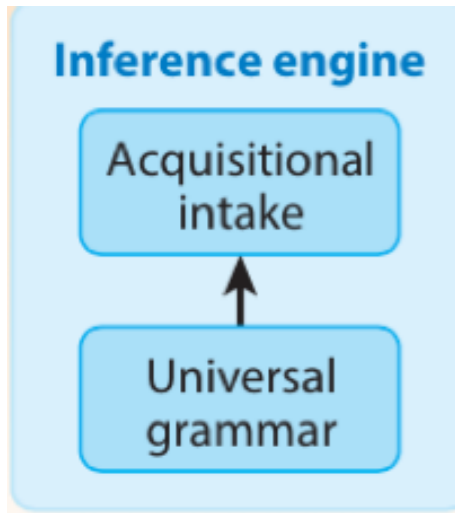
-expmap

Subject Object Indirect Object

+expmap

Subject Object Indirect Object





Potential learning strategies

Animacy

+animate
The penguin tried
to climb.



-animate
The ice seemed
to melt.



Syntactic frame

Choice 1

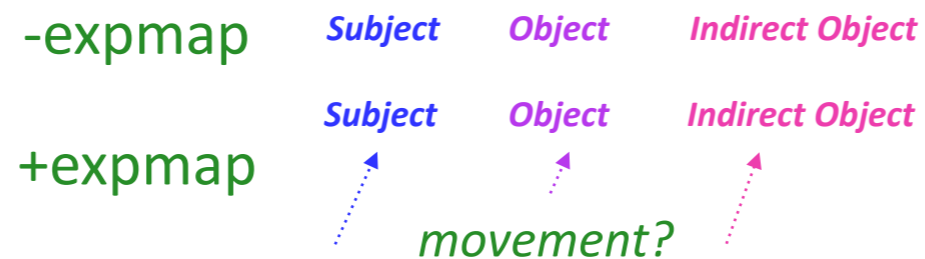
NP ____ S_{nonfinite} -surfmorph
NP ____+past S_{nonfinite} +surfmorph

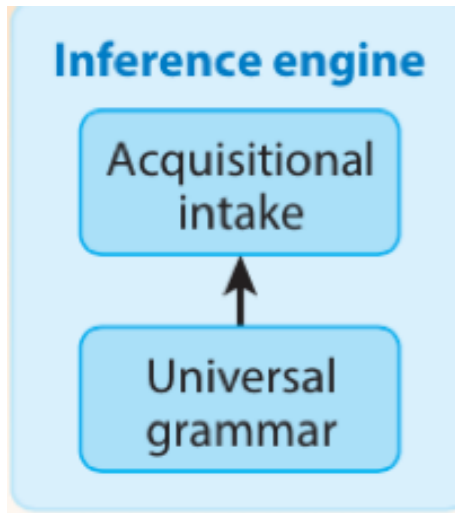
Thematic roles and how to use them

   UTAH

Choice 2

Agent > Experiencer > rUTAH
Theme > Patient >
(Source, Goal, Instrument)





Potential learning strategies

Animacy

+animate
The penguin tried
to climb.



-animate
The ice seemed
to melt.



Syntactic frame

Choice 1

NP ____ S_{nonfinite} -surfmorph
NP ____+past S_{nonfinite} +surfmorph

Thematic roles and how to use them

   UTAH

Choice 2

Agent > Experiencer > rUTAH
Theme > Patient >
(Source, Goal, Instrument)

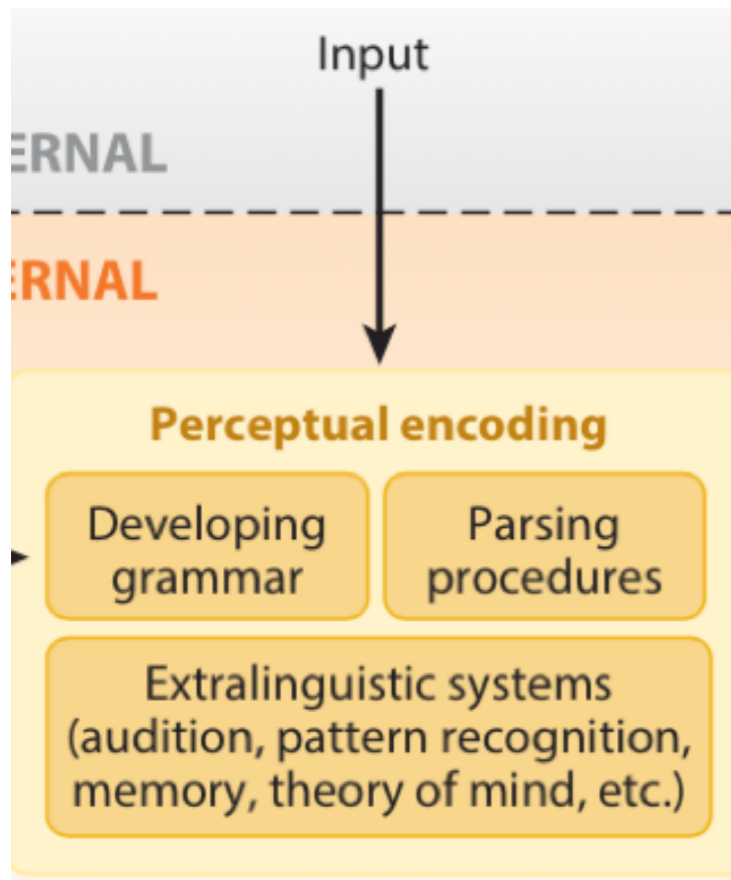
Choice 3

Subject Object Indirect Object -expmap
Subject Object Indirect Object +expmap

movement?

3 binary choices = 8 strategies

Potential learning strategies



Animacy

+animate
The penguin tried
to climb.



-animate
The ice seemed
to melt.



Syntactic frame

Choice 1

NP _____ S_{nonfinite} -surfmorph
NP _____+past S_{nonfinite} +surfmorph

Thematic roles and how to use them

Choice 2

■ ■ ■ UTAH
Agent > Experiencer > rUTAH
Theme > Patient >
(Source, Goal, Instrument)

Choice 3

Subject Object Indirect Object -expmap
Subject Object Indirect Object +expmap
movement?

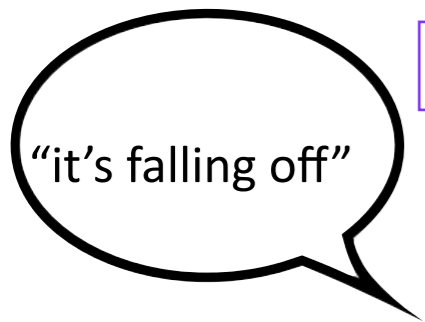
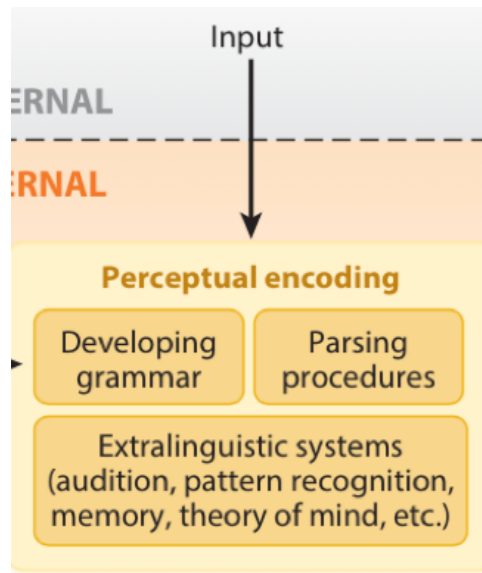
3 binary choices = 8 strategies

All strategies require learner's initial state to be sufficient to extract this information from the input

Potential acquisitional intakes

3 binary choices = 8 strategies

Each strategy has a different impact on the acquisitional intake



Input



Animacy

Syntactic frame

-surfmorph +surfmorph

Thematic roles and how to use them

UTAH



rUTAH

Agent > Experiencer >
Theme > Patient >
(Source, Goal, Instrument)

-expmap

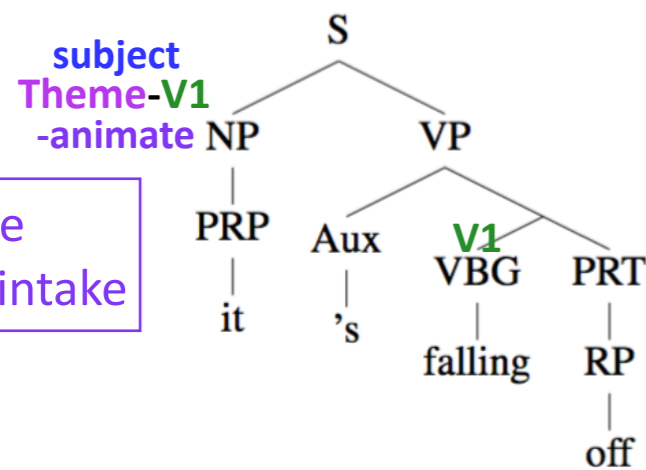
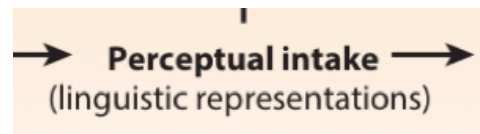
Subject Object Indirect Object

+expmap

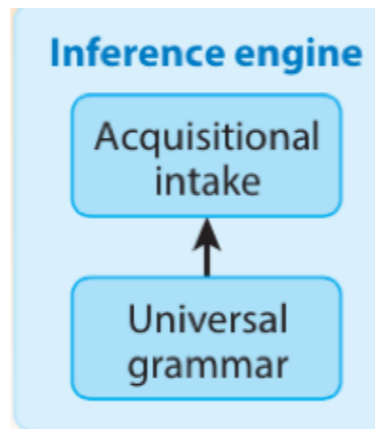
Subject Object Indirect Object

↑ ↑ ↑
movement?

(from Brown-Eve corpus in CHILDES Treebank)



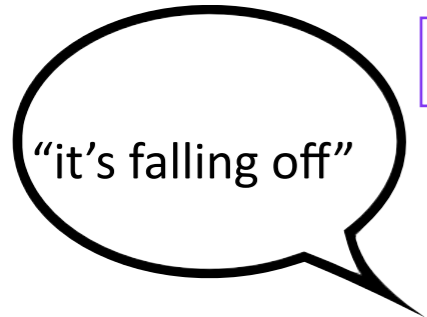
Possible perceptual intake



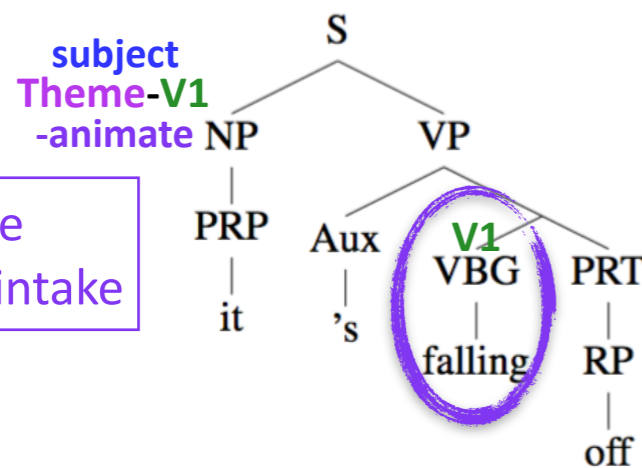
Potential acquisitional intakes

3 binary choices = 8 strategies

Each strategy has a different impact on the acquisitional intake



Input



Possible perceptual intake

Animacy

Syntactic frame

-surfmorph +surfmorph

Thematic roles and how to use them

UTAH



rUTAH

Agent > Experiencer >

Theme > Patient >

(Source, Goal, Instrument)

-expmap

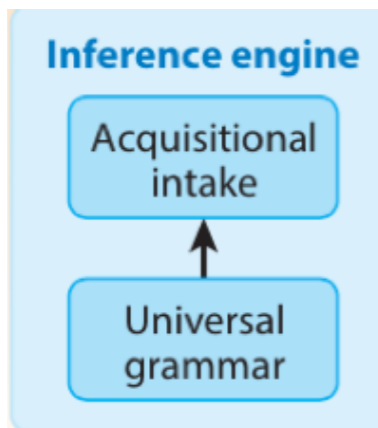
Subject Object Indirect Object

+expmap

Subject Object Indirect Object

movement?

FALL



Potential acquisitional intakes

3 binary choices = 8 strategies

Each strategy has a different impact on the acquisitional intake



Input



Animacy

Syntactic frame

-surfmorph +surfmorph

Thematic roles and how to use them

UTAH



rUTAH

Agent > Experiencer >

Theme > Patient >

(Source, Goal, Instrument)

-expmap

Subject Object Indirect Object

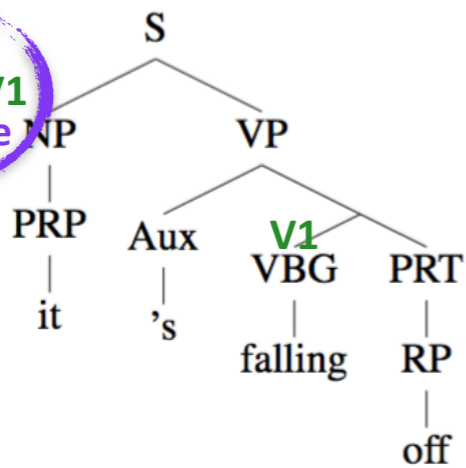
+expmap

Subject Object Indirect Object

movement?

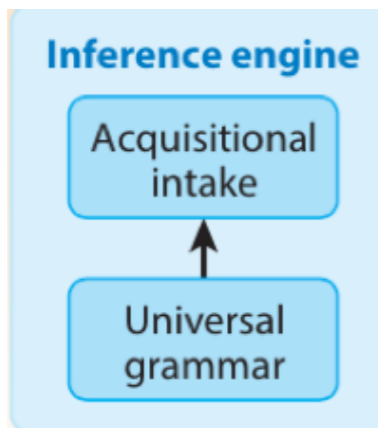
subject
Theme-V1
-animate

Possible
perceptual intake



FALL

-animate subject: 1



Potential acquisitional intakes

3 binary choices = 8 strategies

Each strategy has a different impact on the acquisitional intake



Animacy

Syntactic frame

+surfmorph

Thematic roles and how to use them

rUTAH

Agent > Experiencer >

Theme > Patient >

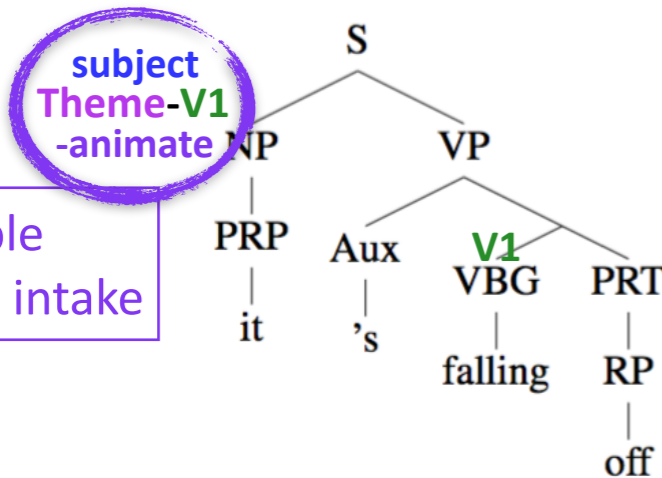
(Source, Goal, Instrument)

+expmap

Subject Object Indirect Object

Subject Object Indirect Object

movement?



FALL

-animate subject: 1

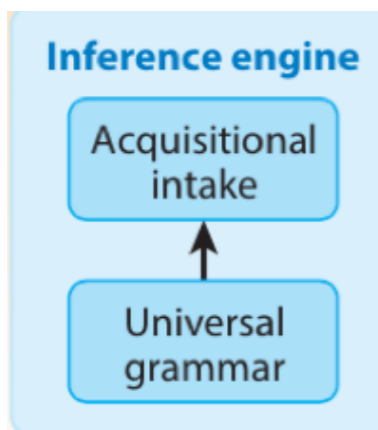
Done-to as subject: 1

UTAH



-expmap

-surfmorph



Potential acquisitional intakes

3 binary choices = 8 strategies

Each strategy has a different impact on the acquisitional intake



Animacy

Syntactic frame

+surfmorph

Thematic roles and how to use them

rUTAH

Agent > Experiencer >

Theme > Patient >

(Source, Goal, Instrument)

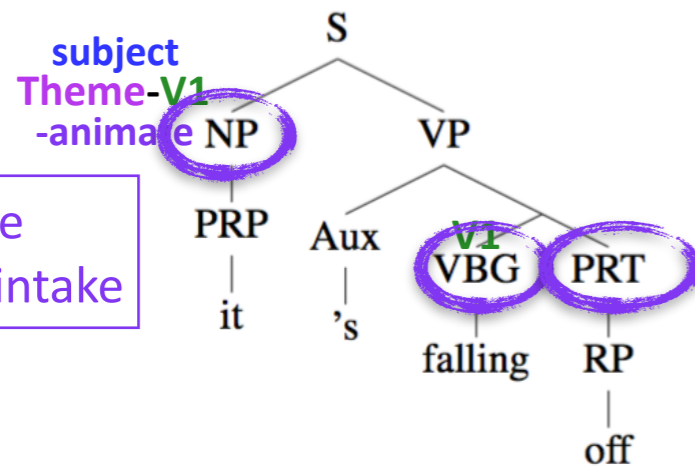
+expmap

Subject Object Indirect Object

Subject Object Indirect Object

movement?

Possible perceptual intake



FALL

-animate subject: 1

Done-to as subject: 1

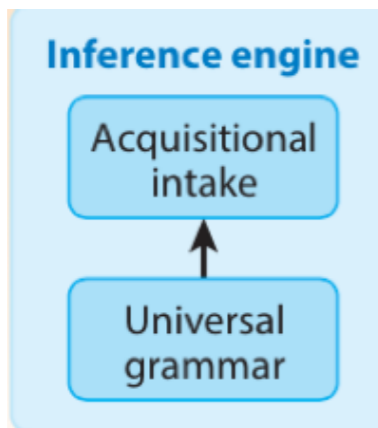
NP V PRT

UTAH



-expmap

-surfmorph



Potential acquisitional intakes

3 binary choices = 8 strategies

Each strategy has a different impact on the acquisitional intake



Input



Animacy

Syntactic frame

-surfmorph

Thematic roles and how to use them

rUTAH

Agent > Experiencer >

Theme > Patient >

(Source, Goal, Instrument)

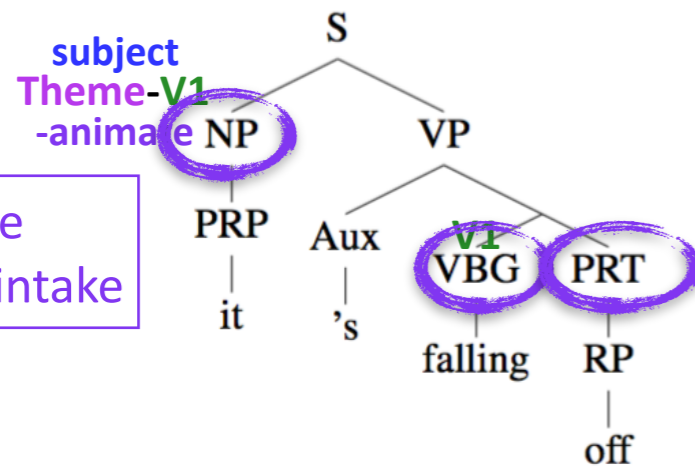
+expmap

Subject Object Indirect Object

Subject Object Indirect Object

movement?

Possible perceptual intake



FALL

-animate subject: 1

Done-to as subject: 1

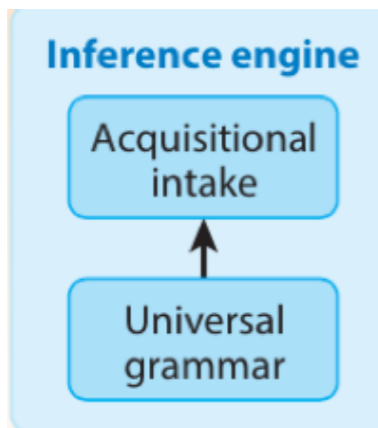
NP V_{+prog} PRT

UTAH



-expmap

+surfmorph



Potential acquisitional intakes

3 binary choices = 8 strategies

Each strategy has a different impact on the acquisitional intake



Input



Animacy

Syntactic frame

-surfmorph

Thematic roles and how to use them

rUTAH

Agent > Experiencer >

Theme > Patient >

(Source, Goal, Instrument)

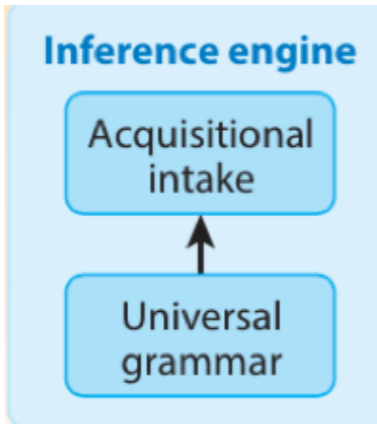
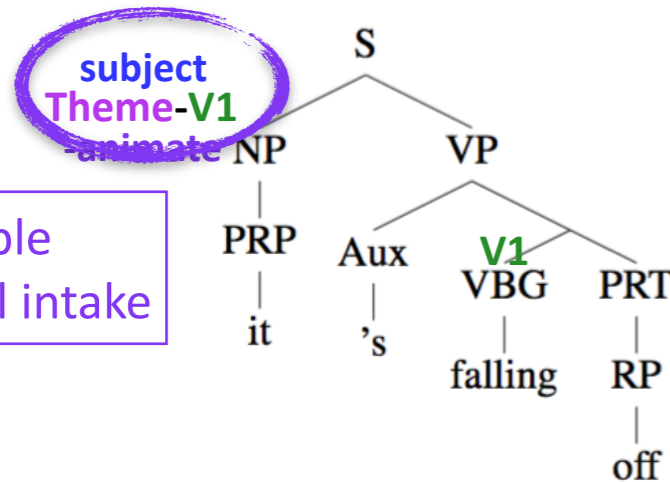
-expmap

Subject Object Indirect Object

Subject Object Indirect Object

movement?

Possible perceptual intake



Theme is expected to map to object, not subject. Indicator of movement.

FALL

-animate subject: 1

+movement: 1

NP V_{+prog} PRT

UTAH



+expmap

+surfmorph

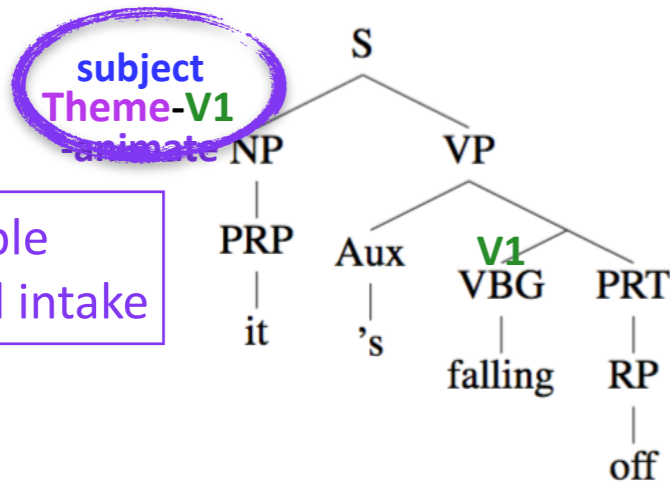
Potential acquisitional intakes

3 binary choices = 8 strategies

Each strategy has a different impact on the acquisitional intake



Input
"it's falling off"



Animacy

Syntactic frame

-surfmorph

Thematic roles and how to use them

UTAH



-expmap

Subject Object Indirect Object

Subject Object Indirect Object



FALL

-animate subject: 1

+movement: 0

NP V_{+prog} PRT

rUTAH

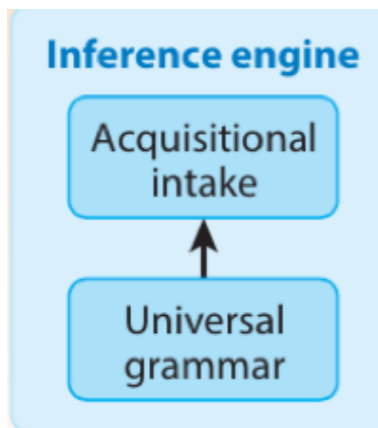
Agent > Experiencer >

Theme > Patient >

(Source, Goal, Instrument)

+expmap

+surfmorph



Theme is only role so is default highest. Expected mapping is to highest syntactic position (subject).

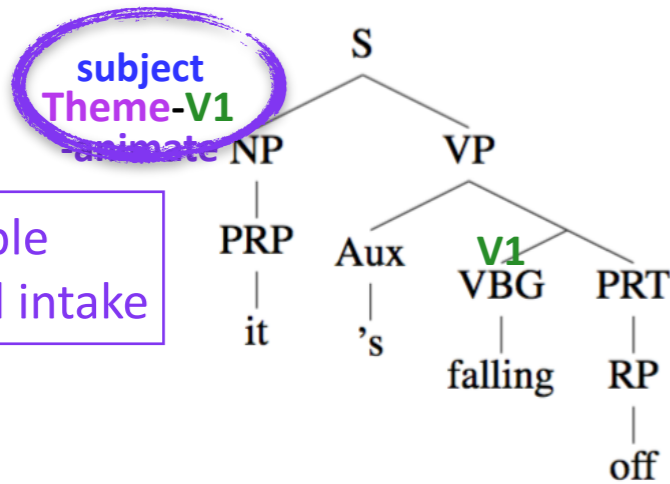
Potential acquisitional intakes

3 binary choices = 8 strategies

Each strategy has a different impact on the acquisitional intake



Input



Animacy

Syntactic frame

-surfmorph

Thematic roles and how to use them

UTAH



Subject Object Indirect Object

+expmap

Subject Object Indirect Object

movement?

FALL

-animate subject: 1

rUTAH

Agent > Experiencer >

Theme > Patient >

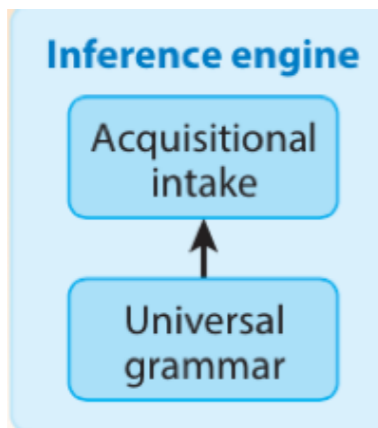
(Source, Goal, Instrument)

Highest role as subject: 1

-expmap

NP V_{+prog} PRT

+surfmorph



8 modeled learners and their acquisitional intakes

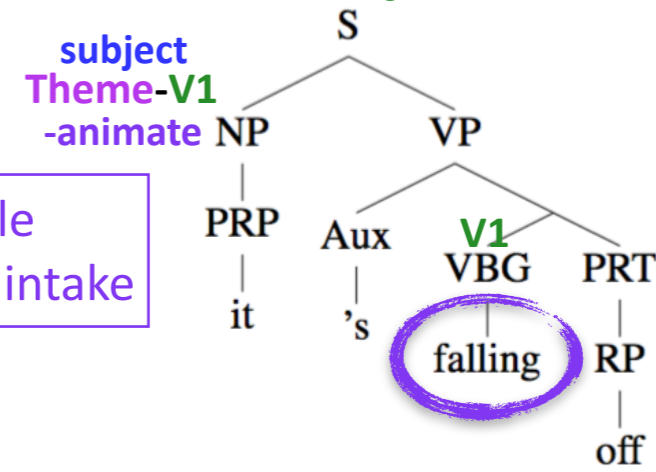


"it's falling off"

Input

Possible
perceptual intake

FALL



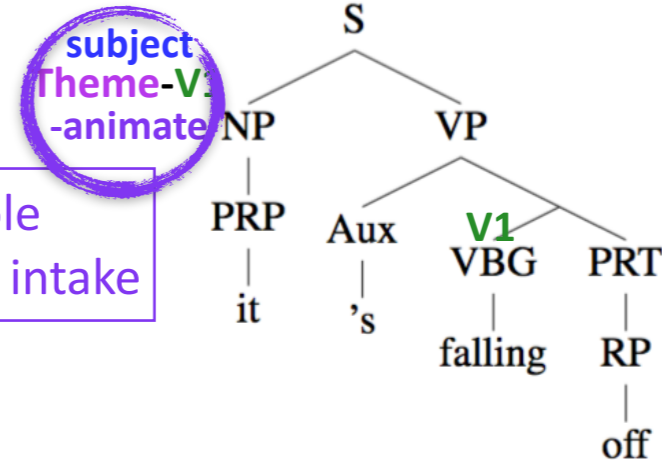
8 modeled learners and their acquisitional intakes



“it’s falling off”

Input

Possible perceptual intake



FALL

Animacy

-animate subject: 1

All 8 learners

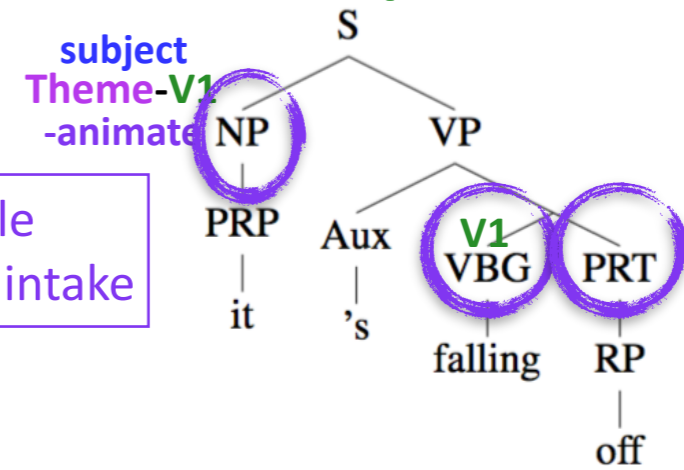
8 modeled learners and their acquisitional intakes



“it’s falling off”

Input

Possible perceptual intake



FALL

Animacy

-animate subject: 1

All 8 learners

Syntactic frame

-surfmorph

+surfmorph

4 learners

4 learners

NP V PRT

NP V_{+prog} PRT

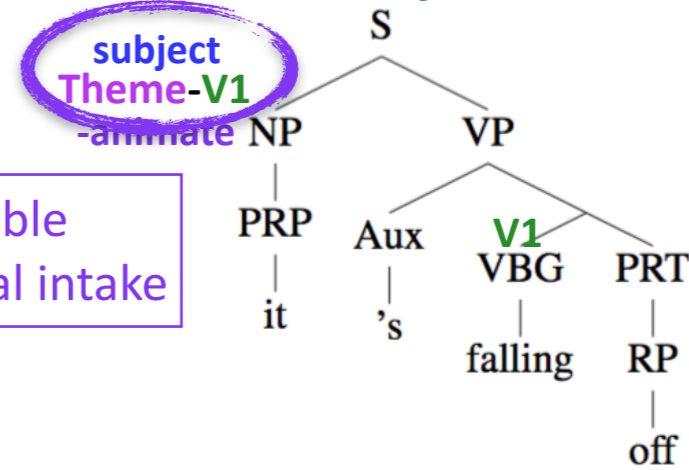
8 modeled learners and their acquisitional intakes



“it’s falling off”

Input

Possible perceptual intake



FALL

Animacy

-animate subject: 1

All 8 learners

Syntactic frame

-surfmorph

+surfmorph

4 learners

4 learners

NP V PRT

NP V_{+prog} PRT

Intermediate representation

UTAH

Done-to as subject

2 learners

rUTAH

Highest as subject

2 learners

UTAH

Done-to as subject

2 learners

rUTAH

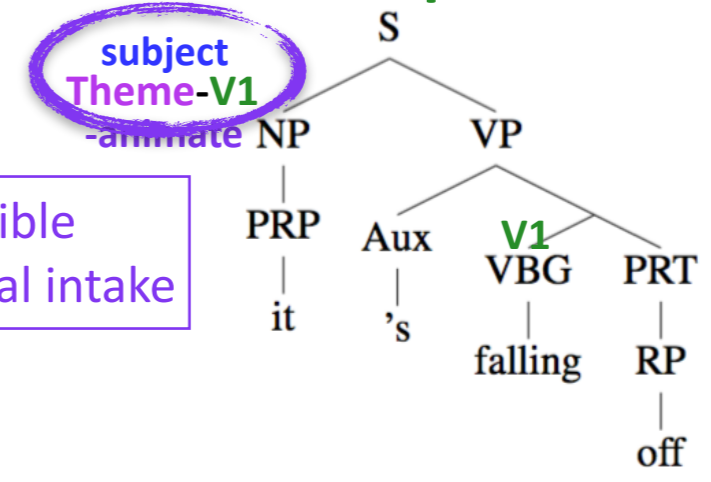
Highest as subject

2 learners

8 modeled learners and their acquisitional intakes



Input
"it's falling off"



FALL

Animacy **-animate subject: 1** All 8 learners

Syntactic frame **-surfmorph**

+surfmorph

4 learners
NP V PRT

4 learners
NP V_{+prog} PRT

Intermediate representation

UTAH
Done-to as subject
2 learners

rUTAH
Highest as subject
2 learners

UTAH
Done-to as subject
2 learners

rUTAH
Highest as subject
2 learners

Mapping to syntax

+expmap
+mvmt: 1

-expmap
Done-to as subject: 1

+expmap
+mvmt: 0

-expmap
Highest as subject: 1

+expmap
+mvmt: 1

-expmap
Done-to as subject: 1

+expmap
+mvmt: 0

-expmap
Highest as subject: 1

1 learner

1 learner

1 learner

1 learner

1 learner

1 learner

1 learner

1 learner

Today's plan

Verb classes



done-to

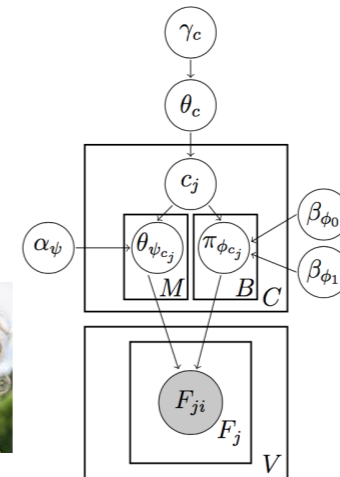
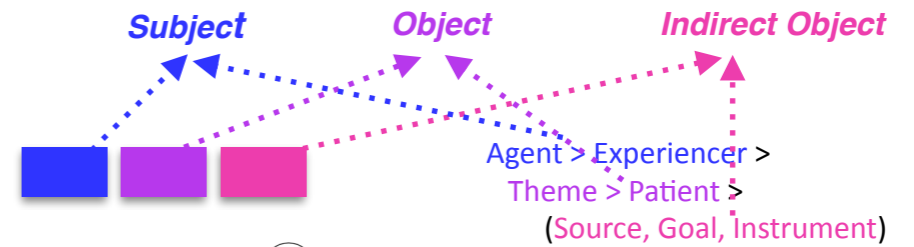
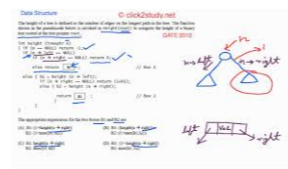
The ice melted.

The penguin climbed.

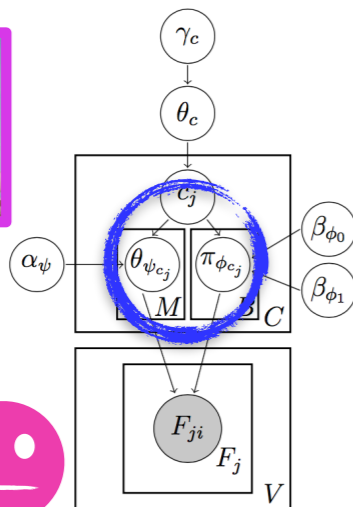
doer



Computational modeling

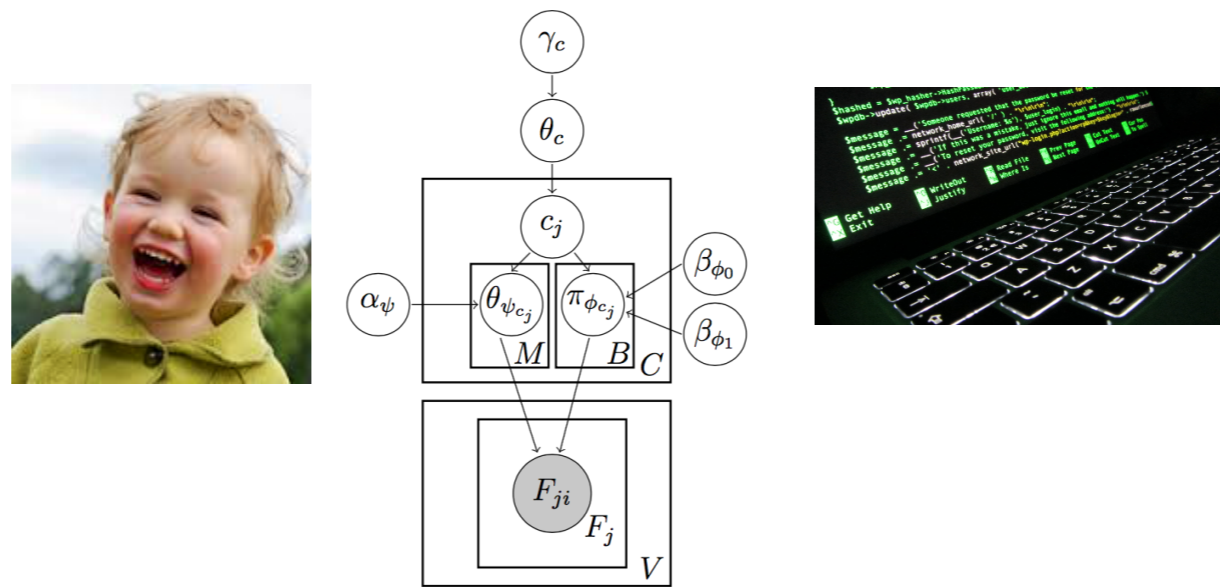


Results & implications

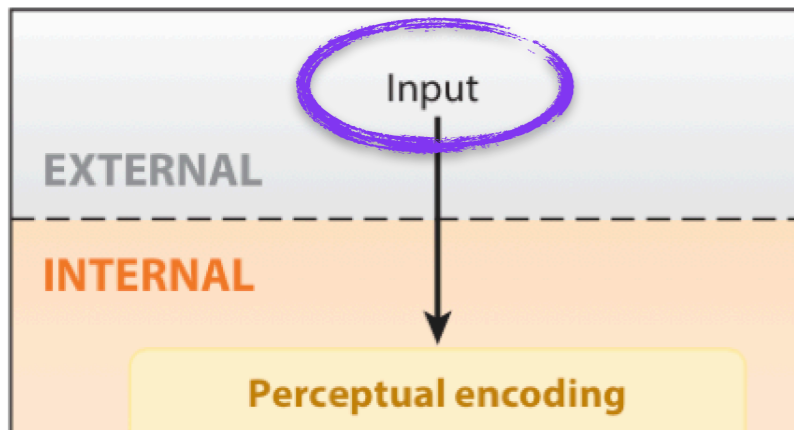


Today's plan

Computational modeling



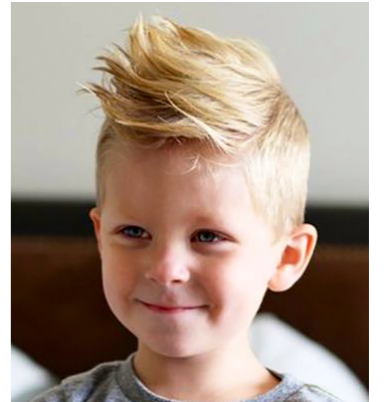
How do we model this?

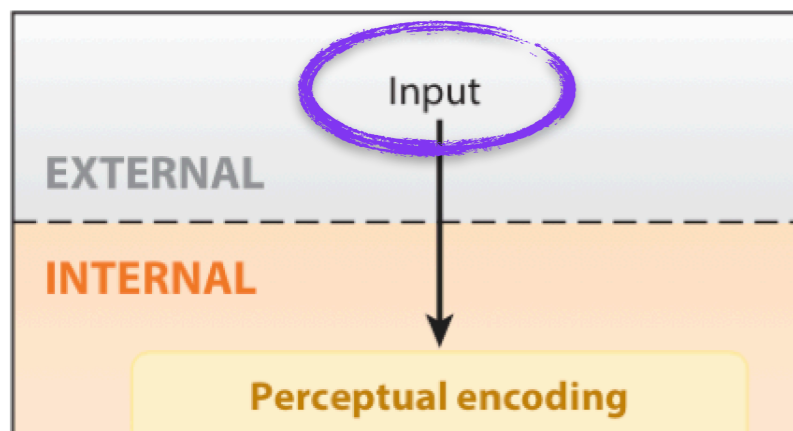


Goal: Model the developmental trajectory from 3 to 4 to 5 years old

“it’s falling off”

Input



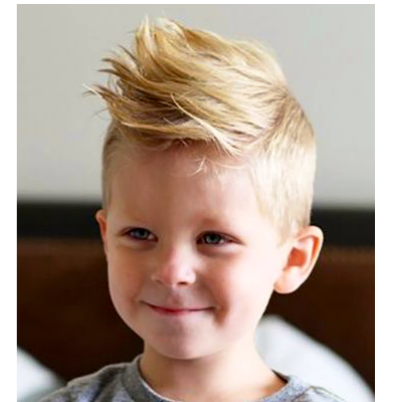


CHILDES Treebank

Goal: Model the developmental trajectory from 3 to 4 to 5 years old



Input



<3 years old

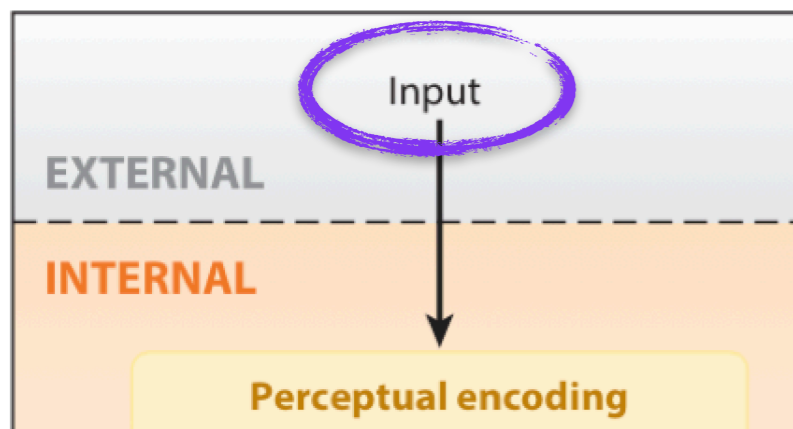
Brown-Eve corpus (Brown 1973) and the Valian corpus (Valian 1991), with syntactic & thematic annotations provided by the CHILDES Treebank (Pearl & Sprouse 2013).

Speech directed at 22 children between 18 and 32 months.

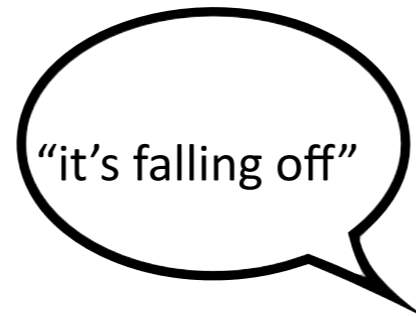
~40,000 utterances (~197,000 word tokens, 555 verbs)



Focus on the 239 verbs occurring 5 or more times.



Goal: Model the developmental trajectory from 3 to 4 to 5 years old



Input

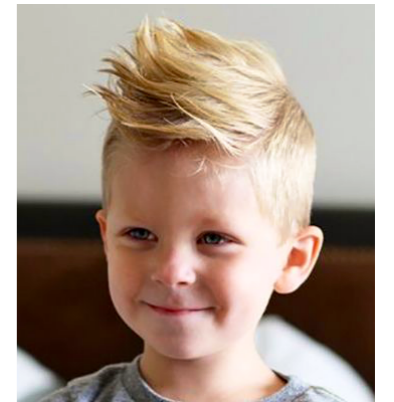
CHILDES Treebank

<3yrs



18 and 32 months
~40,000 utterances
239 verbs

<4 years old



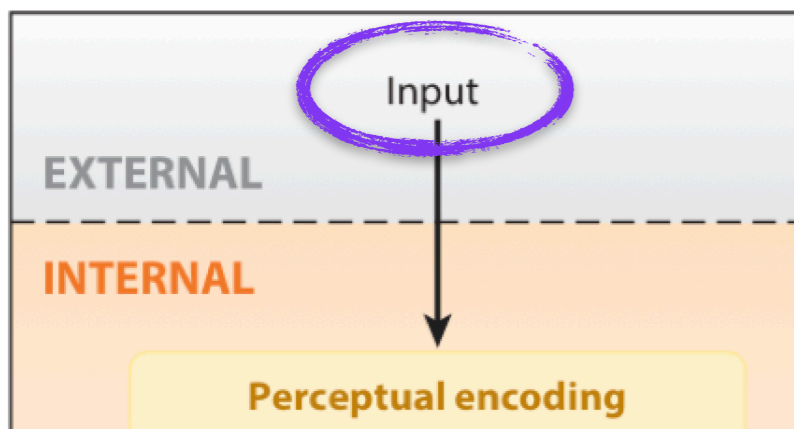
<3yrs + Brown-Adam subsection (Brown 1973), with syntactic & thematic annotations provided by the CHILDES Treebank (Pearl & Sprouse 2013).



Speech directed at 23 children between 18 and 48 months.

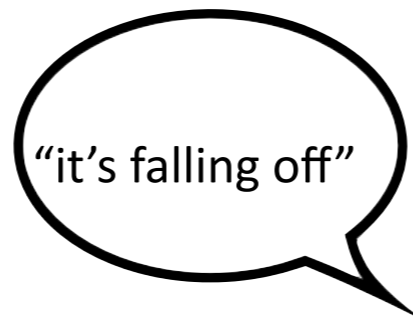
~51,000 utterances (~254,000 word tokens, 617 verbs)

Focus on the 267 verbs occurring 5 or more times.



CHILDES Treebank

Goal: Model the developmental trajectory from 3 to 4 to 5 years old



Input

<3yrs



18 and 32 months
~40,000 utterances
239 verbs

<4yrs



18 and 48 months
~51,000 utterances
267 verbs

<5 years old

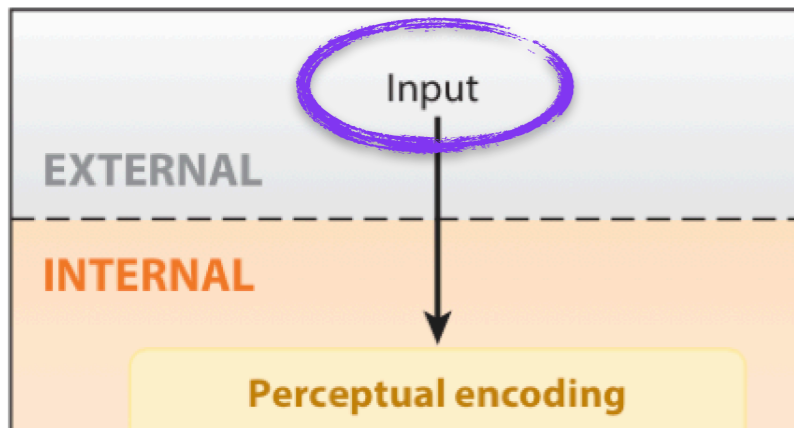


<4yrs + Brown-Adam subsection (Brown 1973), with syntactic & thematic annotations provided by the **CHILDES Treebank** (Pearl & Sprouse 2013).

Speech directed at 23 children between 18 and 58 months.

~56,500 utterances (~285,000 word tokens, 651 verbs)

Focus on the 284 verbs occurring 5 or more times.



CHILDES Treebank

<3yrs



18 and 32 months
~40,000 utterances
239 verbs

<4yrs



18 and 48 months
~51,000 utterances
267 verbs

<5yrs

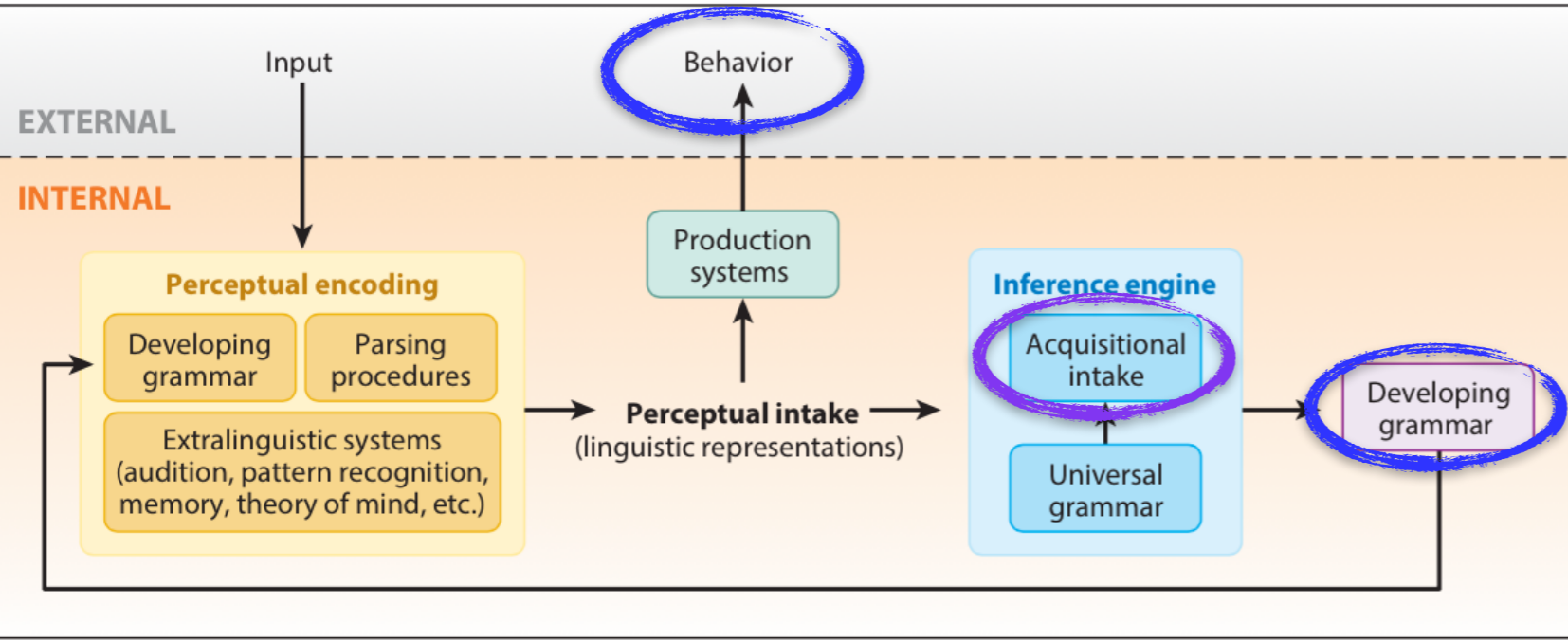


18 and 58 months
~56,500 utterances
284 verbs

Goal: Model the developmental trajectory from 3 to 4 to 5 years old



Input




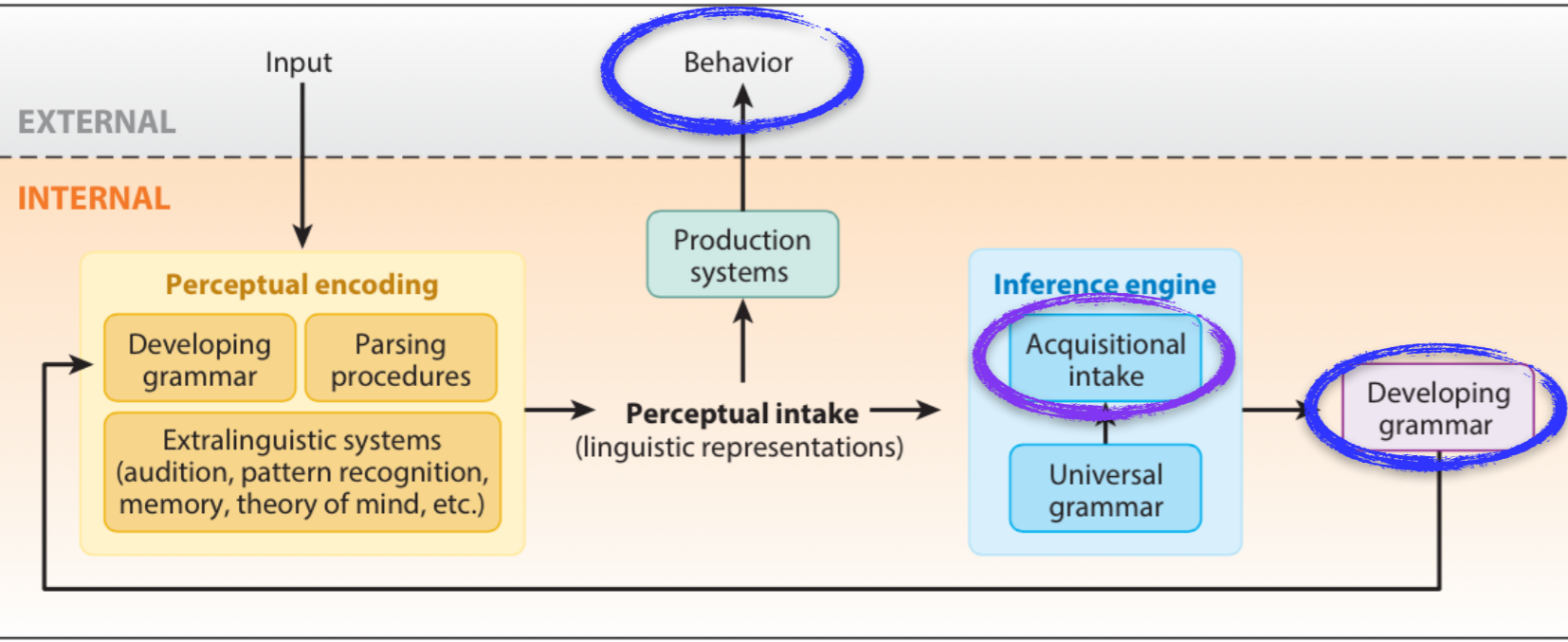
Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



Basic question: Is it possible for the child to use the **acquisitional intake** to achieve the **target knowledge/behavior**?

- +animate**  **-surfmorph**
NP ____ S_{nonfinite}
- UTAH**
- rUTAH** **Agent > Experiencer >**
Theme > Patient >
(Source, Goal, Instrument)
- expmap** *Subject* *Object* *Indirect Object*
- +expmap** *movement?*



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

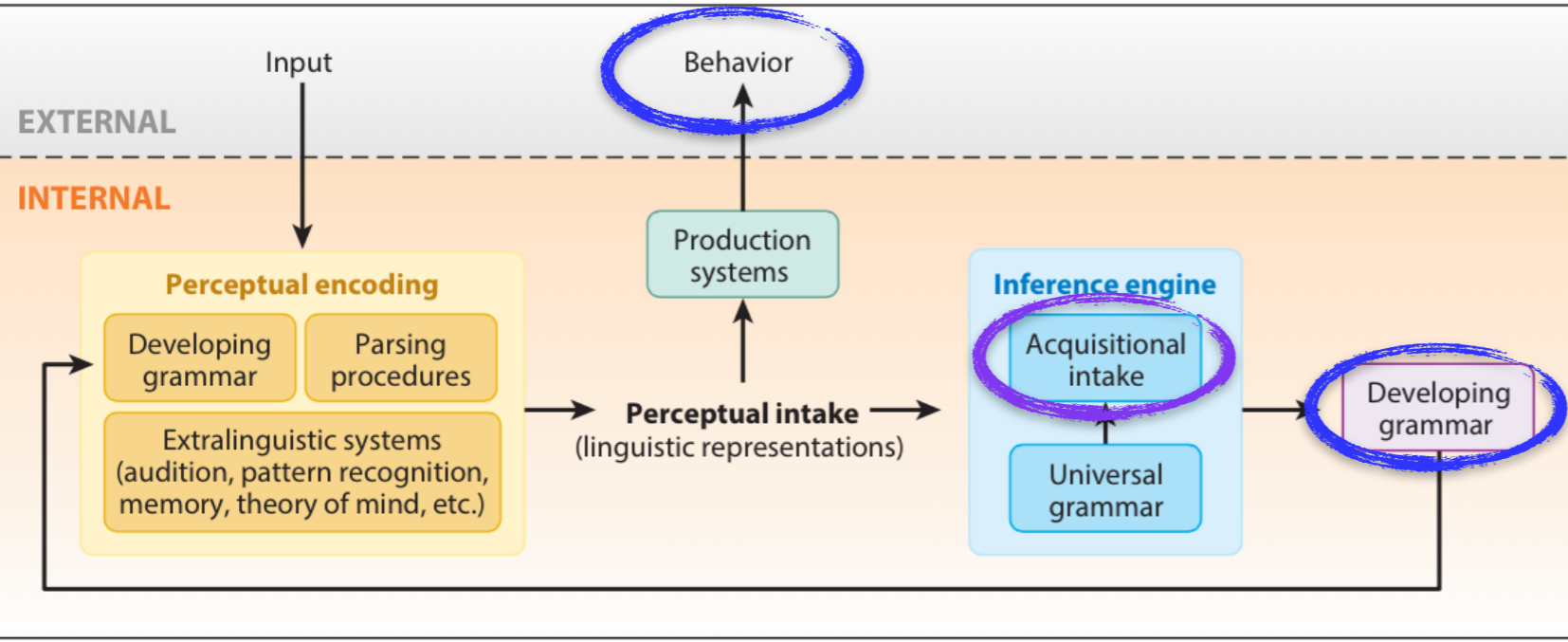
<3yrs <4yrs <5yrs



Basic question: Is it possible for the child to use the **acquisitional intake** to achieve the **target knowledge/behavior**?

This is the goal of **learnability** approaches (**computational-level** of analysis: Marr 1982)

Frank et al. 2009, Goldwater et al. 2009, Pearl et al. 2010, Pearl 2011, Legate & Yang 2012, Dillon et al. 2013, Doyle & Levy 2013, Feldman et al. 2013, Orita et al. 2013



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



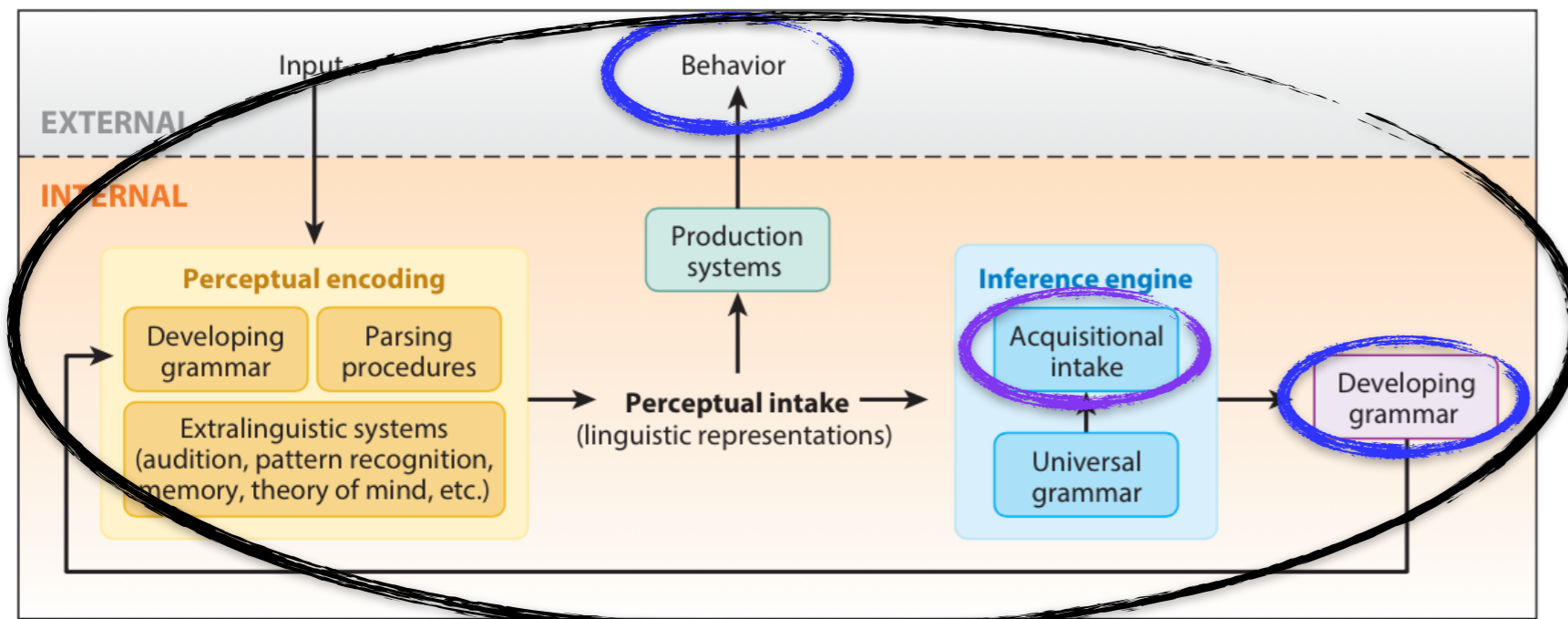
Basic question: Is it possible for the child to use the **acquisitional intake** to achieve the **target knowledge/behavior**?

Ideal learner model: not concerned with the cognitive limitations and incremental learning restrictions children have.

Concerned with what **assumptions** are **useful** for children to have.



- surfmorph
- +surfmorph
- UTAH
- rUTAH
- expmap
- +expmap



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs

<5yrs

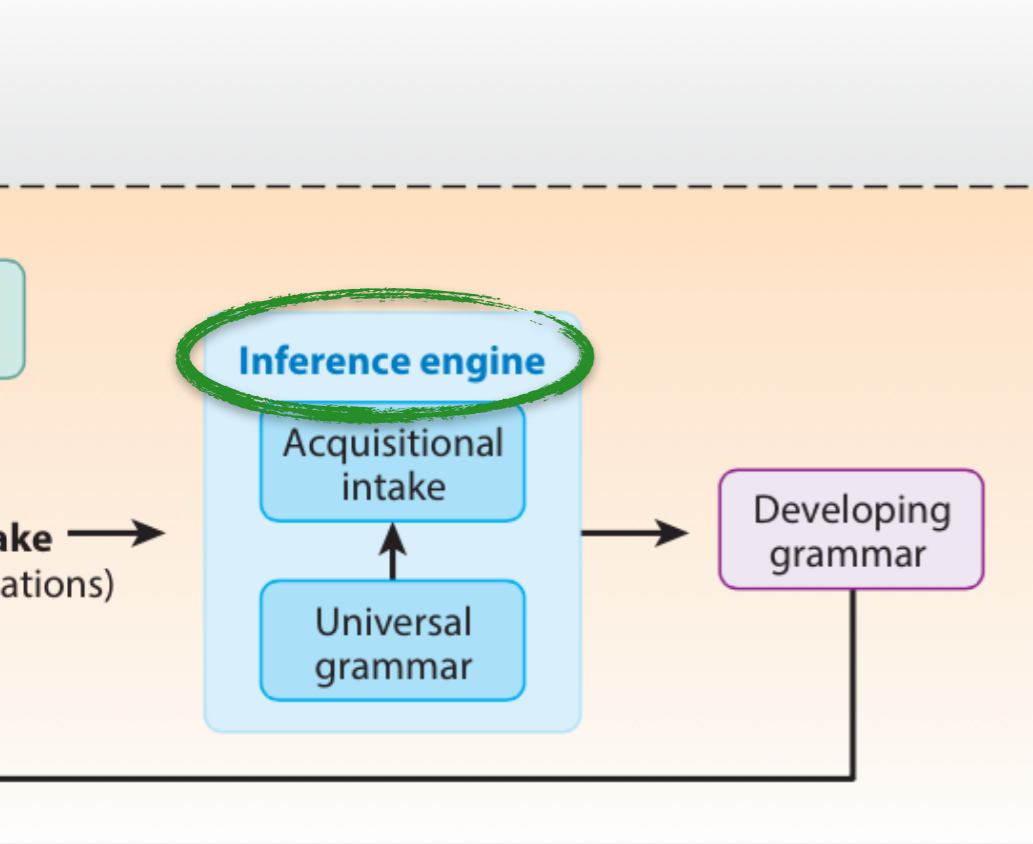


Basic question: Is it possible for the child to use the **acquisitional intake** to achieve the **target knowledge/behavior**?

Ideal learner model: Also an excellent first step to see if this is the **right conceptualization** of the acquisition task.



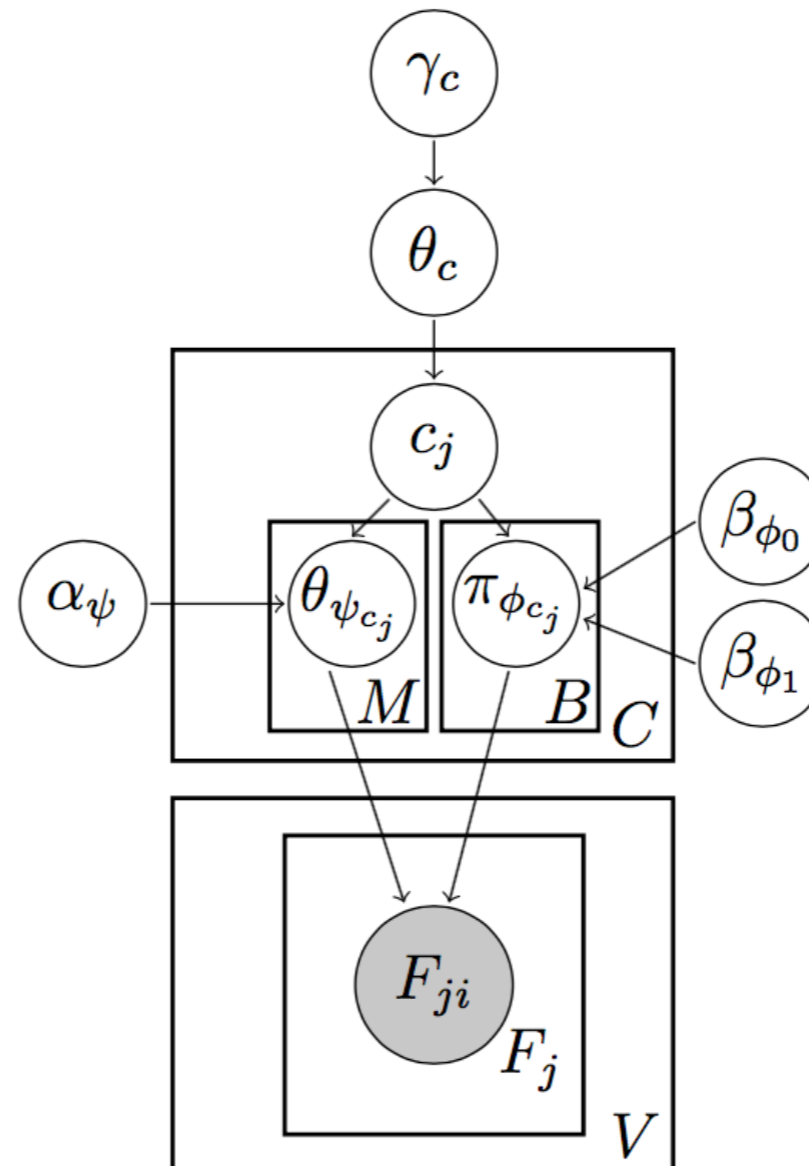
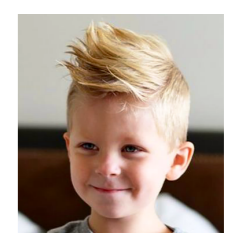
-surfmorph
+surfmorph
UTAH
rUTAH
-expmap
+expmap

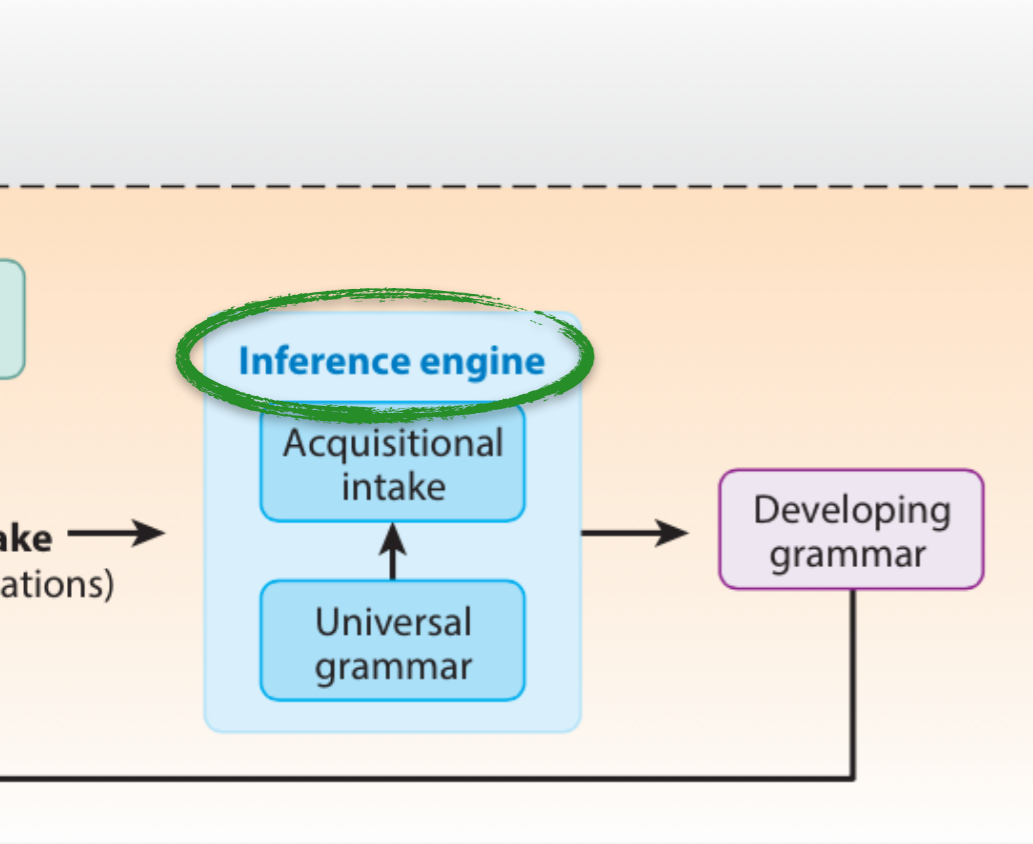


Learners use a **generative model** of how the observable data for each verb are created.

Goal: Model the **developmental trajectory** from 3 to 4 to 5 years old

<3yrs **<4yrs** **<5yrs**



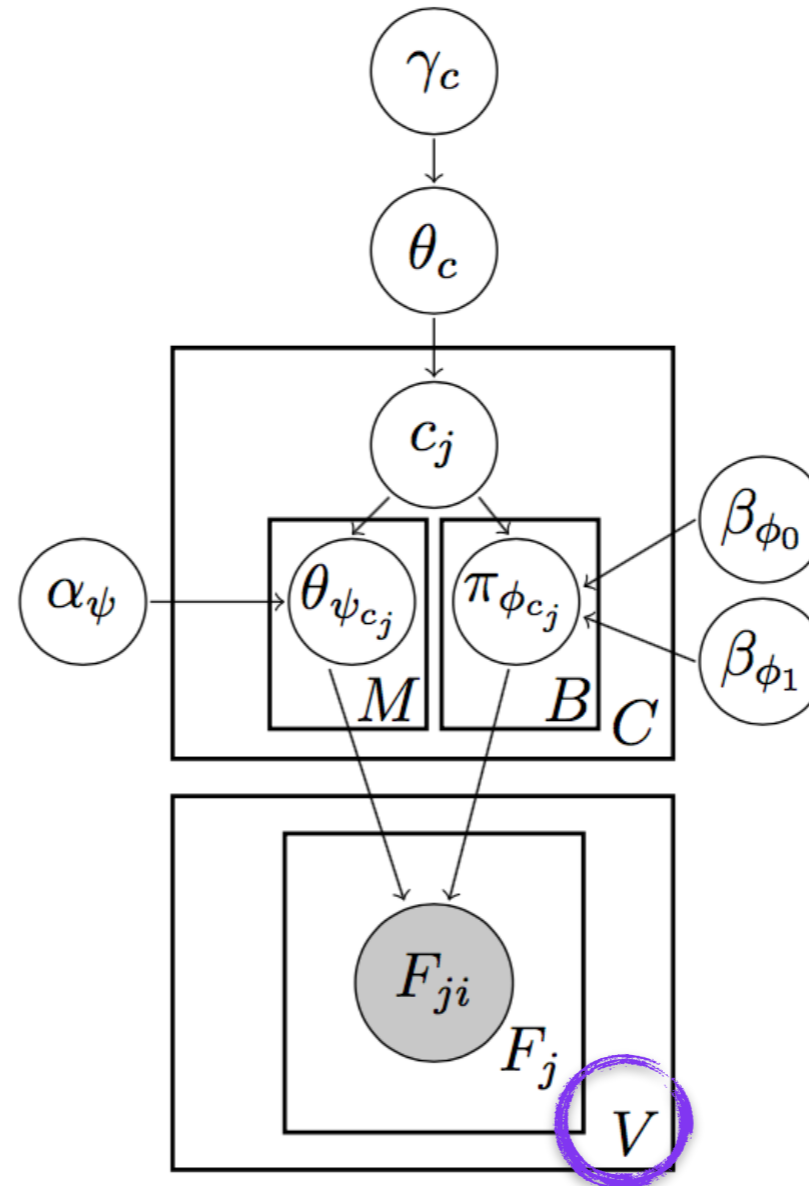
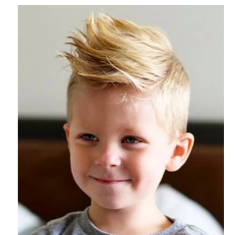


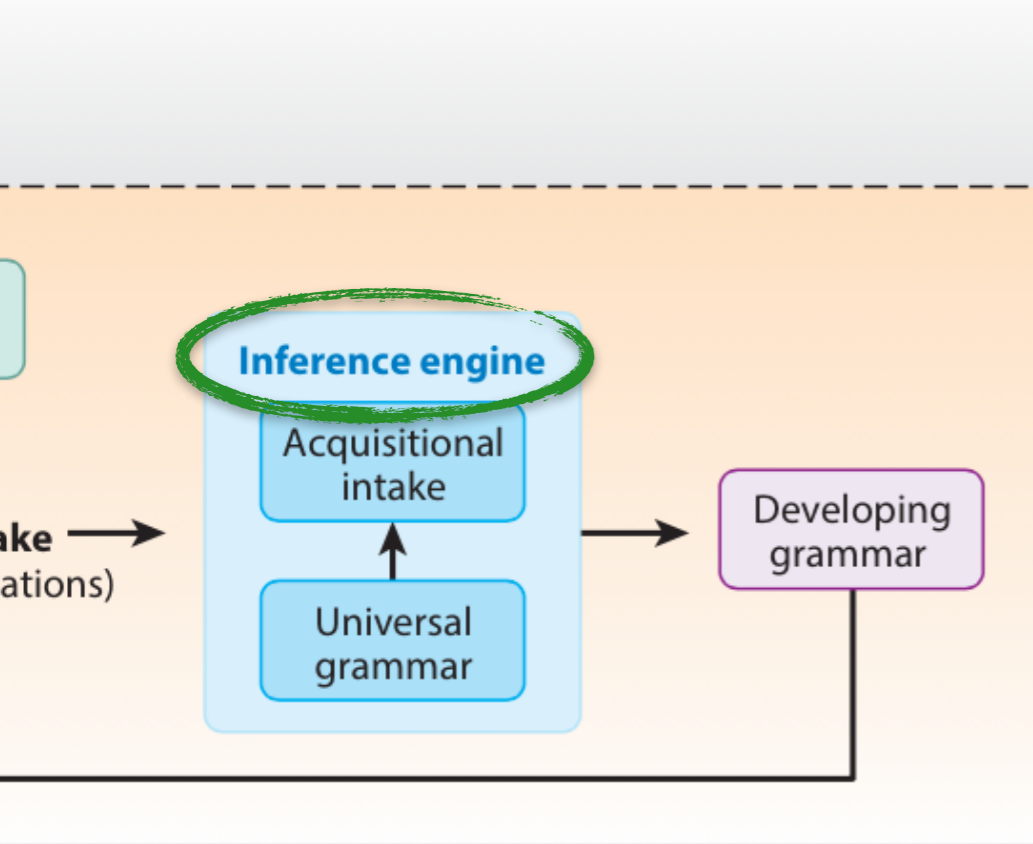
Learners use a **generative model** of how the observable data for each **verb** are created.

FALL

Goal: Model the **developmental trajectory** from 3 to 4 to 5 years old

<3yrs **<4yrs** **<5yrs**



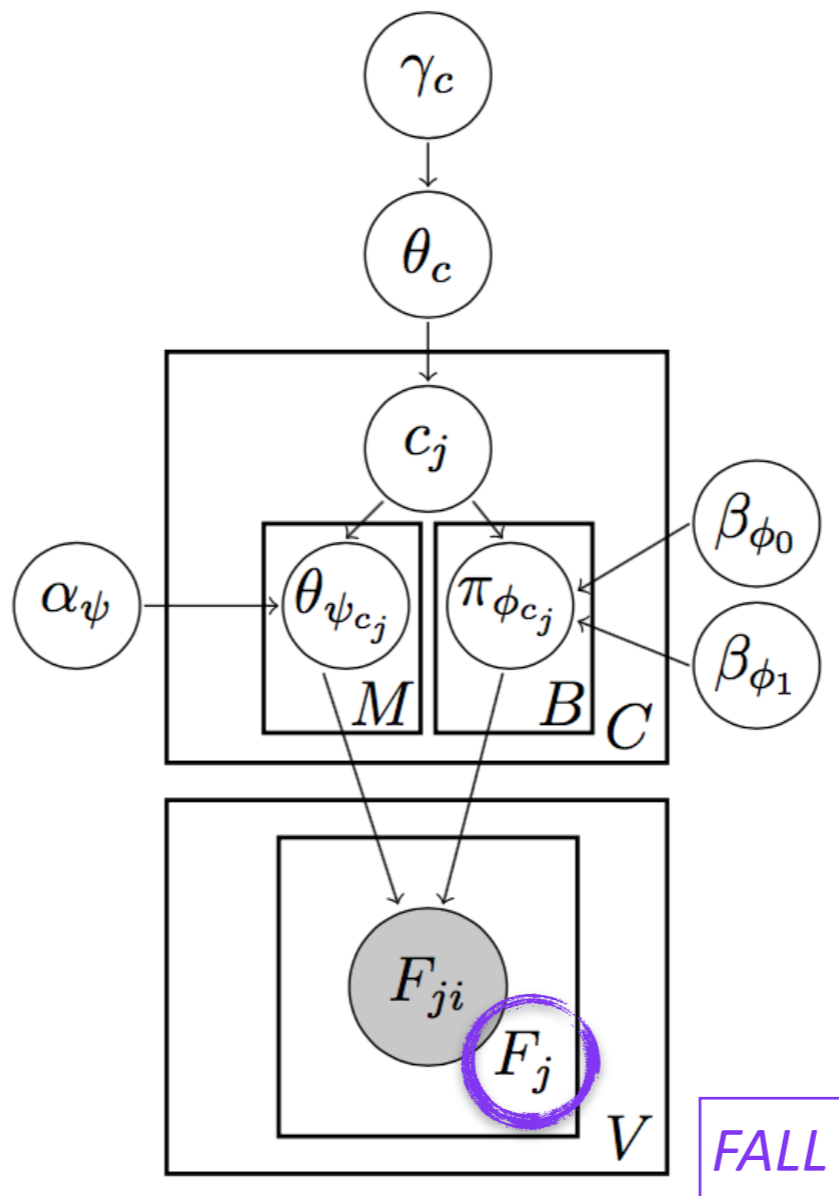
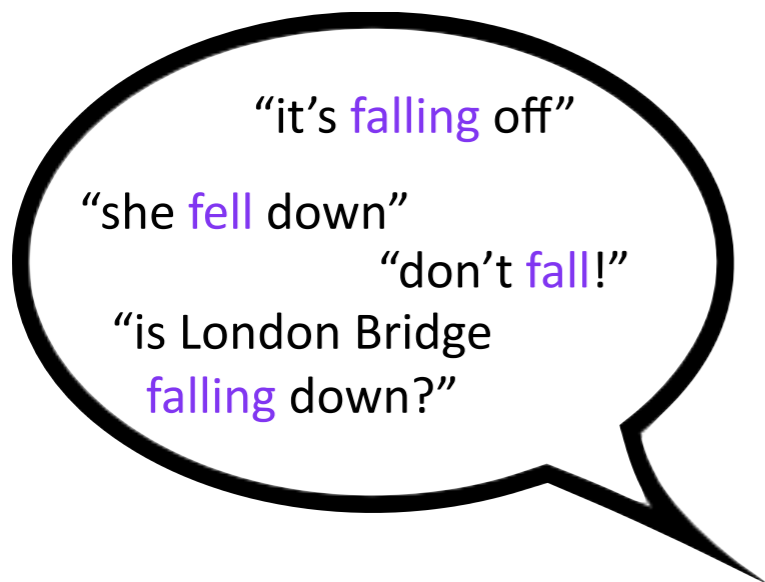


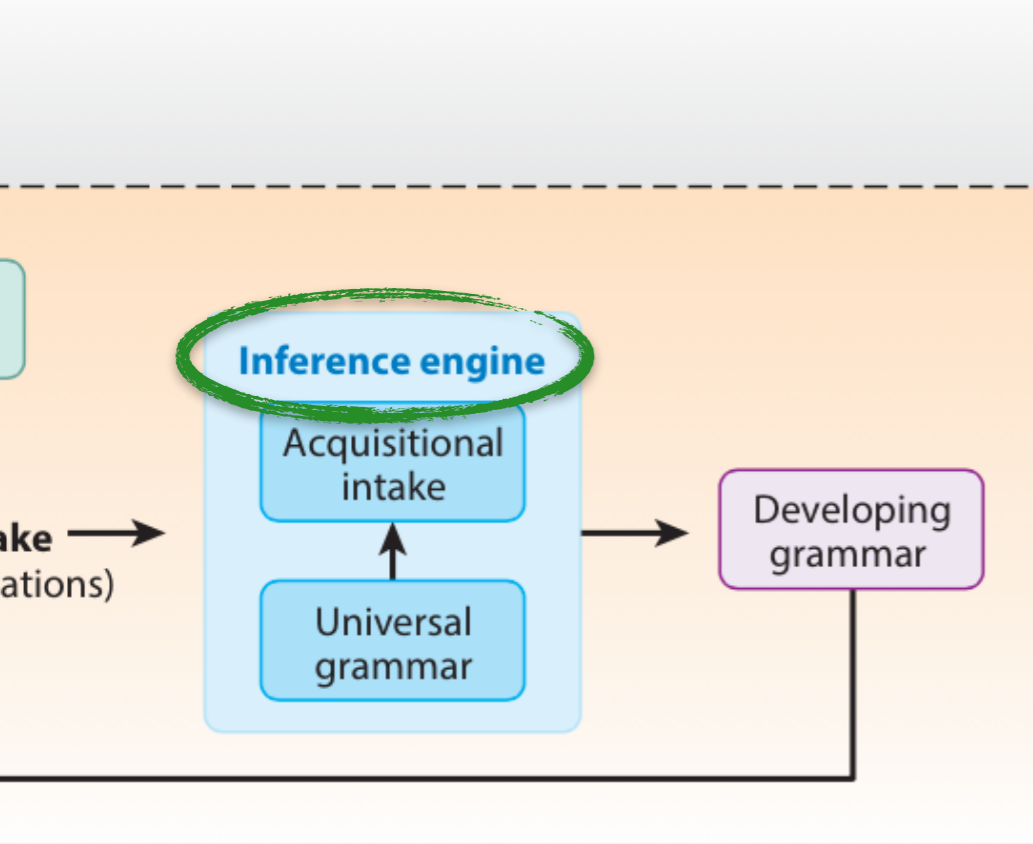
Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



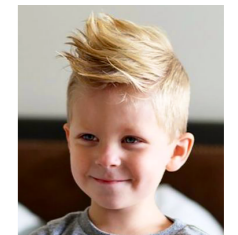
Each verb appears in a certain number of instances in the input.





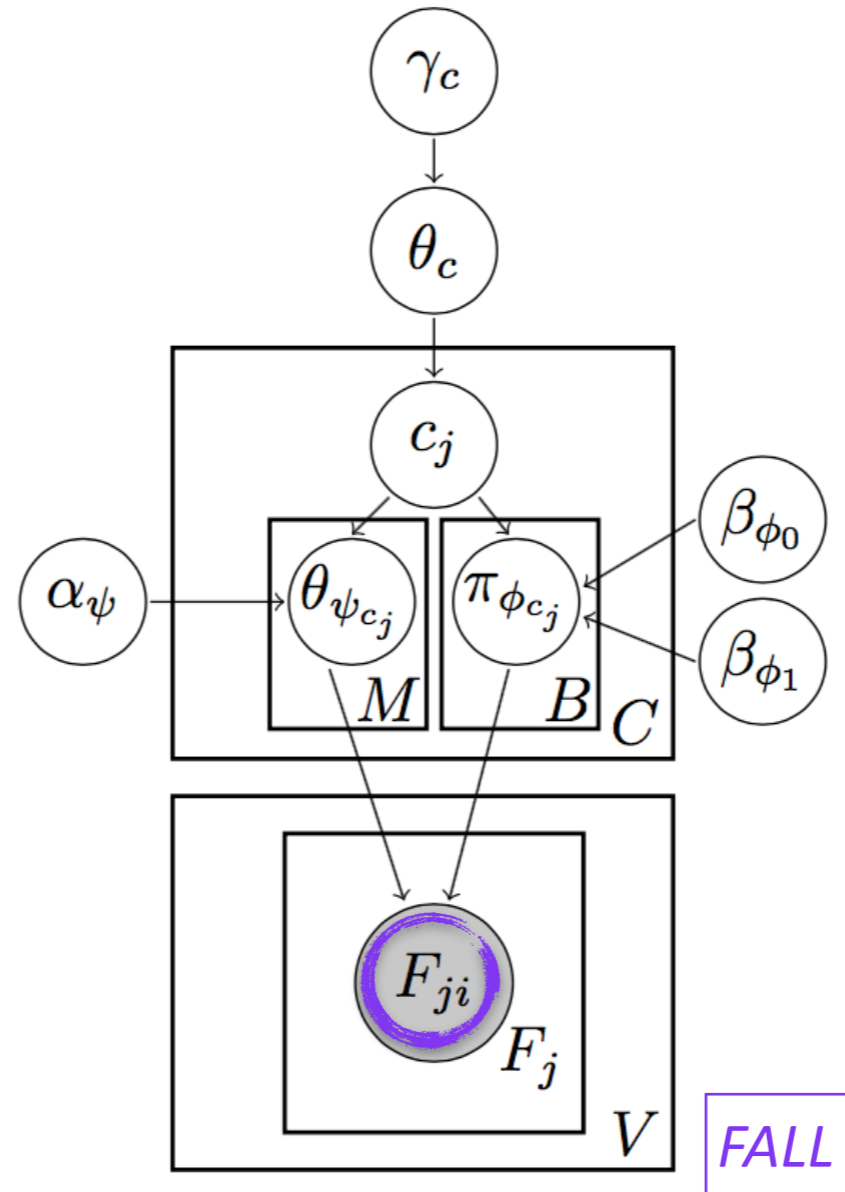
Goal: Model the developmental trajectory from 3 to 4 to 5 years old

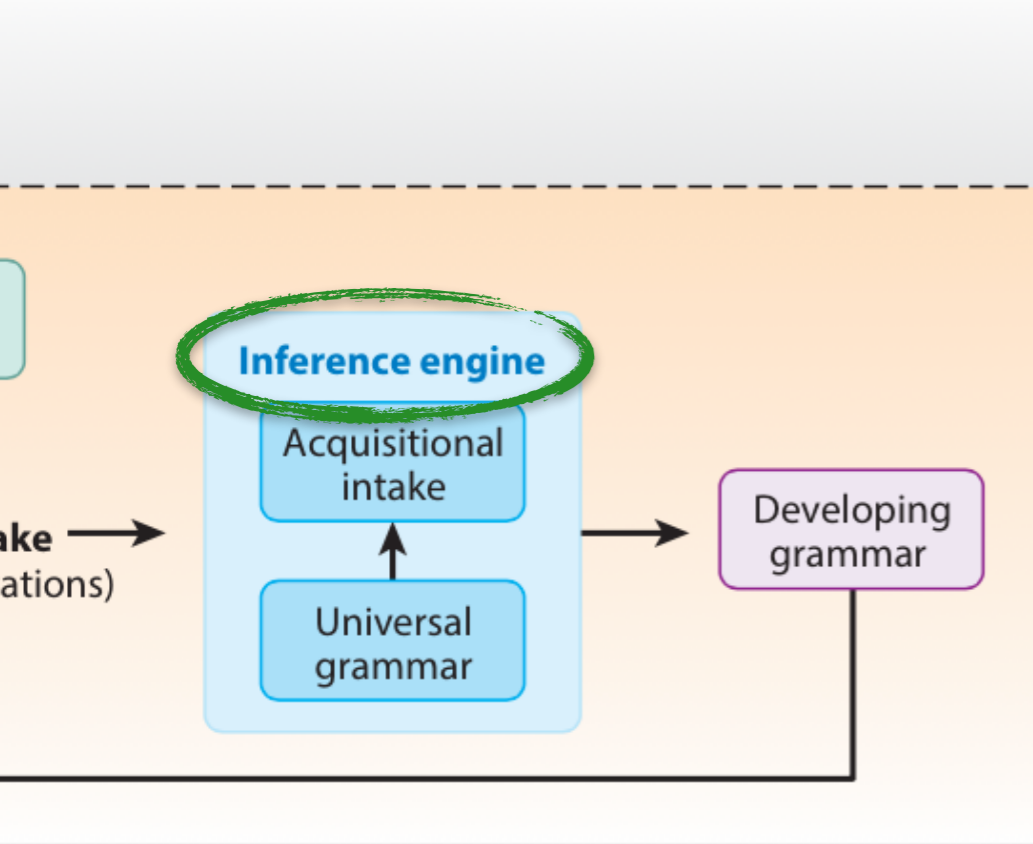
<3yrs <4yrs <5yrs



Each instance is observed some number of times.

“it’s falling off”
 (3x) “it’s falling off”
 “it’s falling off”





Goal: Model the developmental trajectory from 3 to 4 to 5 years old

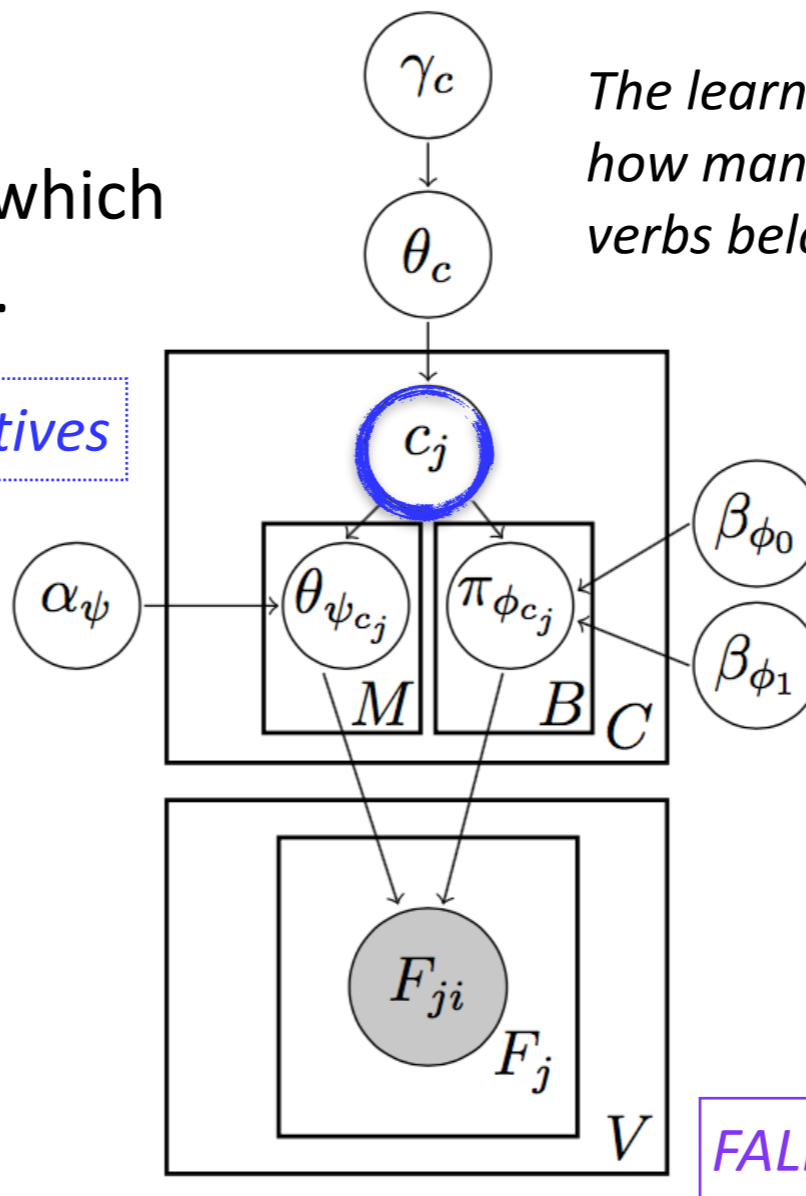


Each verb belongs to some class which determines its linguistic behavior.

The learner doesn't know beforehand how many classes there are or which verbs belong to which.

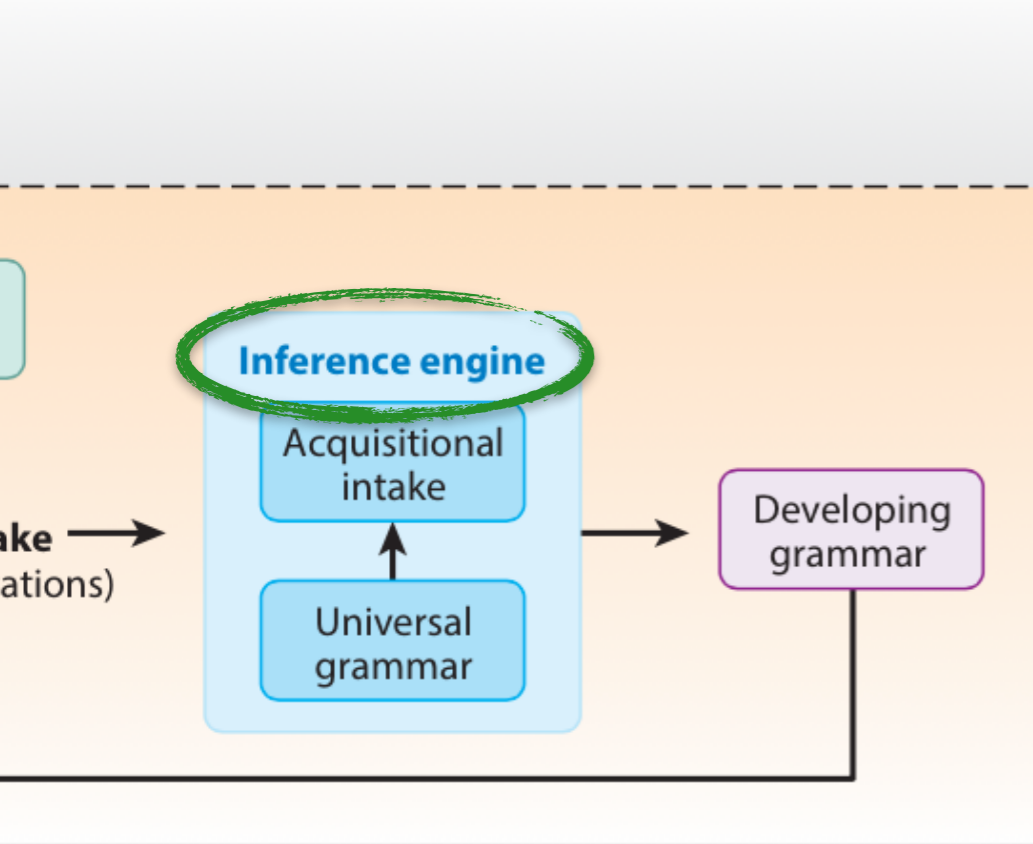
Objective: Infer verb class

unaccusatives



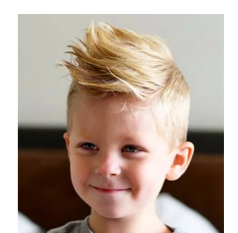
FALL

“it’s falling off”
 (3x) “it’s falling off”
 “it’s falling off”



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs

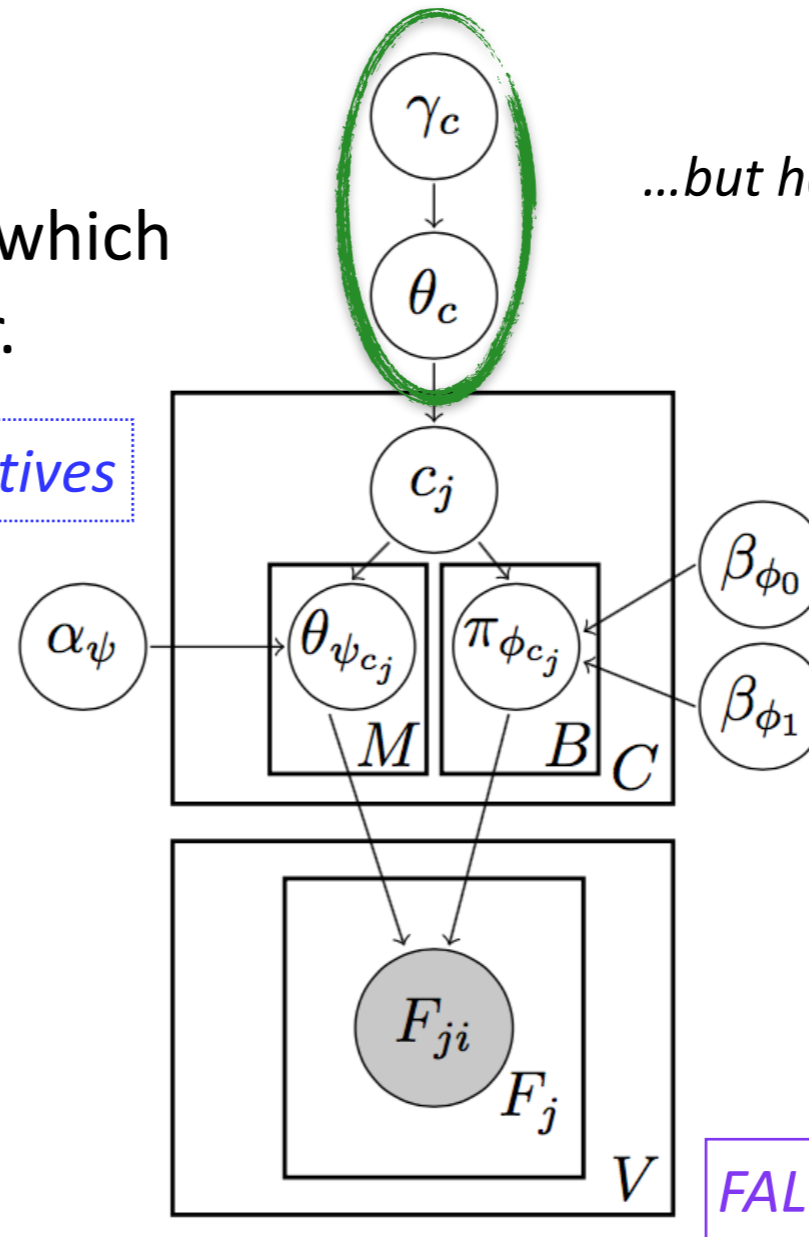


Each verb belongs to some class which determines its linguistic behavior.

...but has a bias for fewer classes.

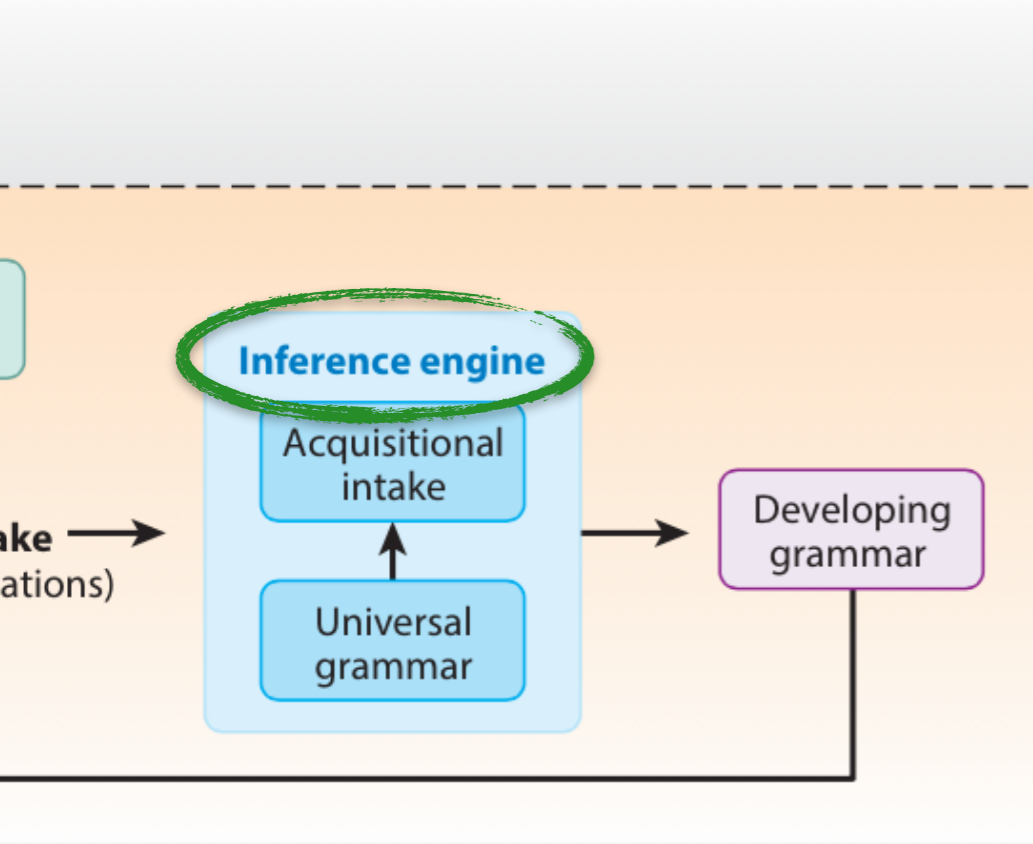
Objective: Infer verb class

unaccusatives



FALL

“it’s falling off”
 (3x) “it’s falling off”
 “it’s falling off”



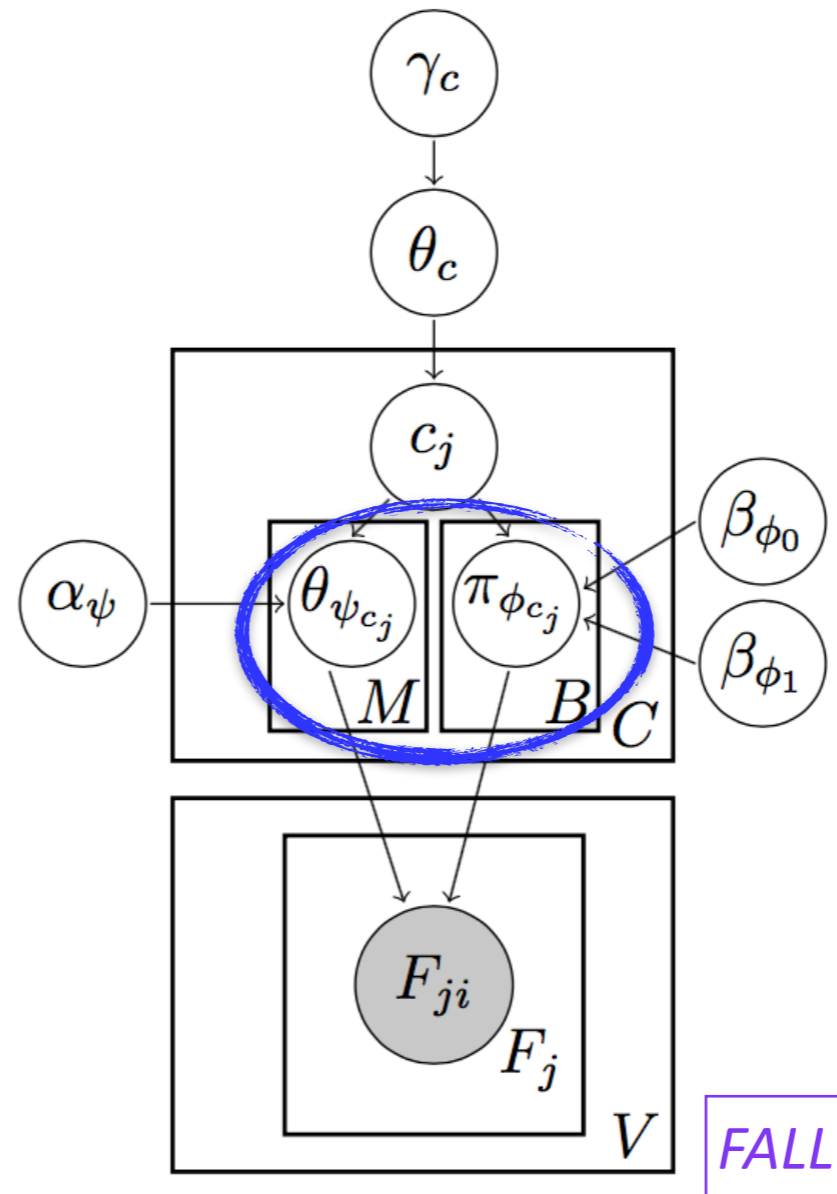
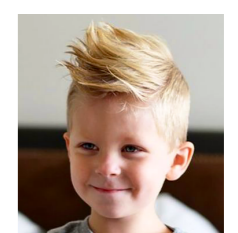
Depending on the verb **class**, the **observed usage** will have **certain characteristics**.

Goal: Model the **developmental trajectory** from 3 to 4 to 5 years old

<3yrs

<4yrs

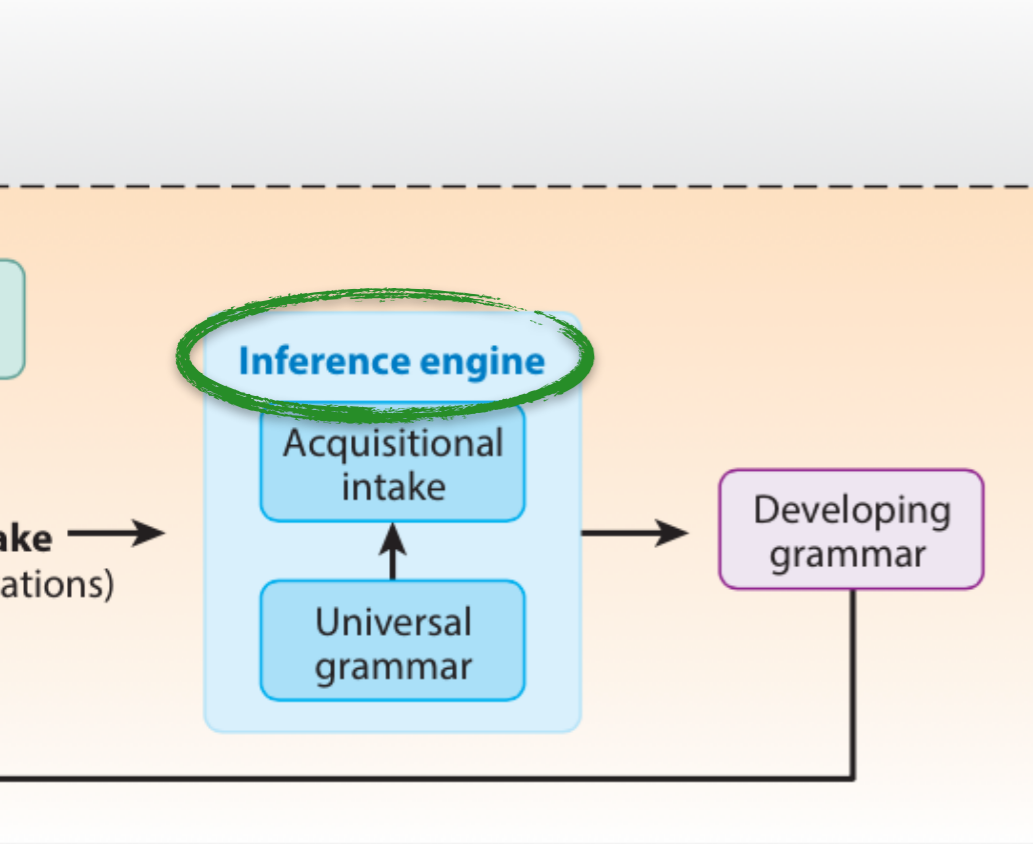
<5yrs



unaccusatives

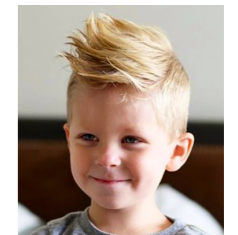
“it’s falling off”
 (3x) “it’s falling off”
 “it’s falling off”

FALL



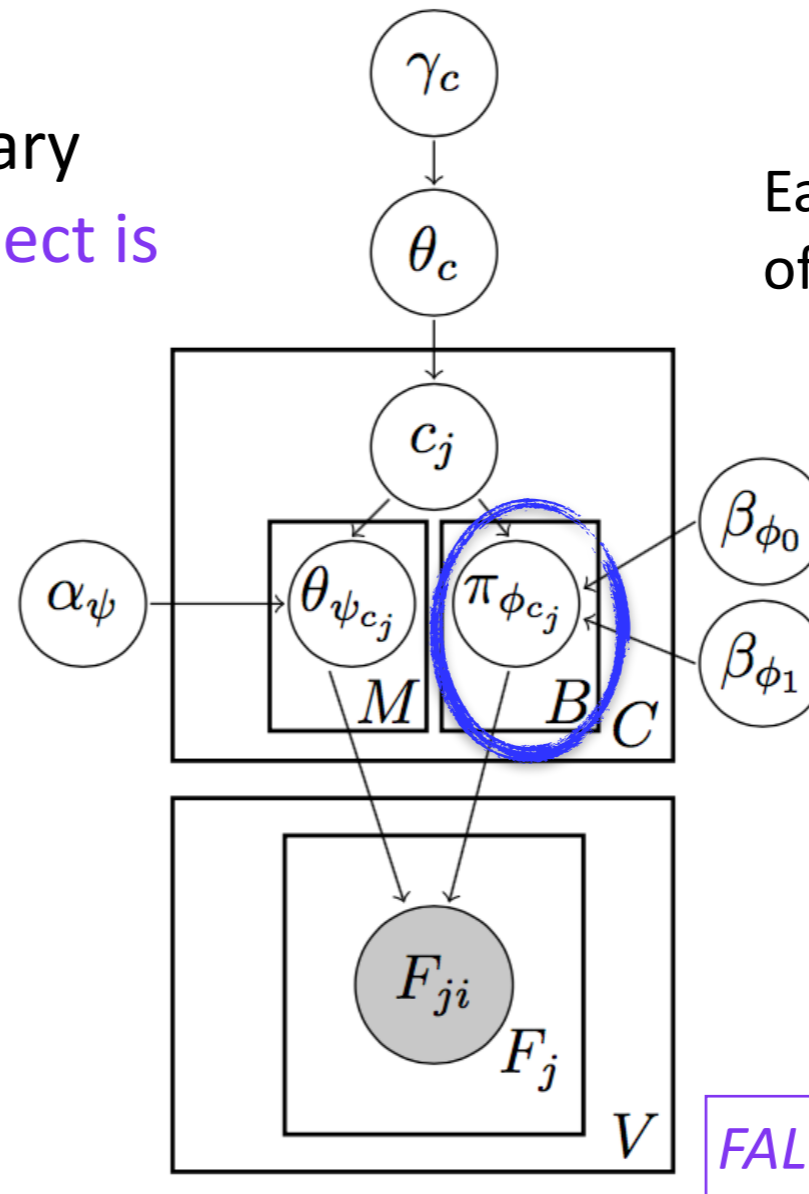
Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



These characteristics include binary choices such as whether the subject is animate or not.

Each class has a probability of preferring each option.

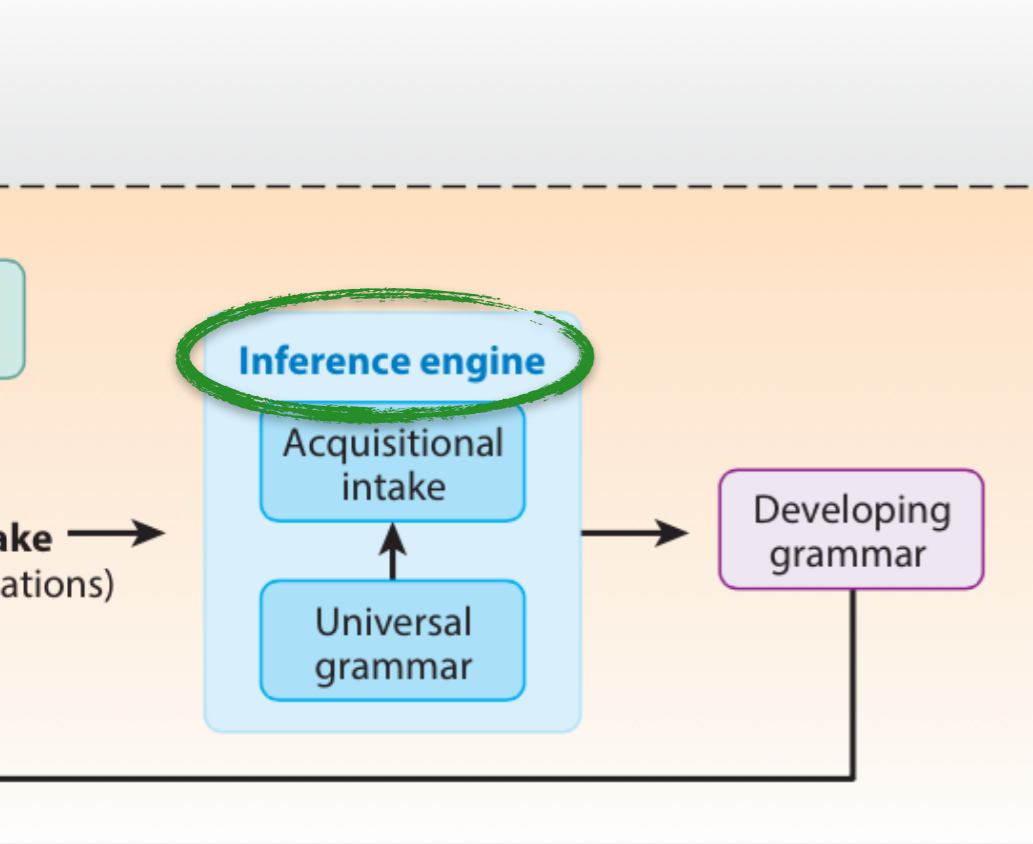


unaccusatives

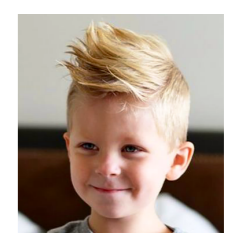
| +anim | Subject | -anim |
|-------|---------|-------|
| 0.3 | | 0.7 |

-anim
 "it's falling off"
 (3x) "it's falling off"
 "it's falling off"

FALL

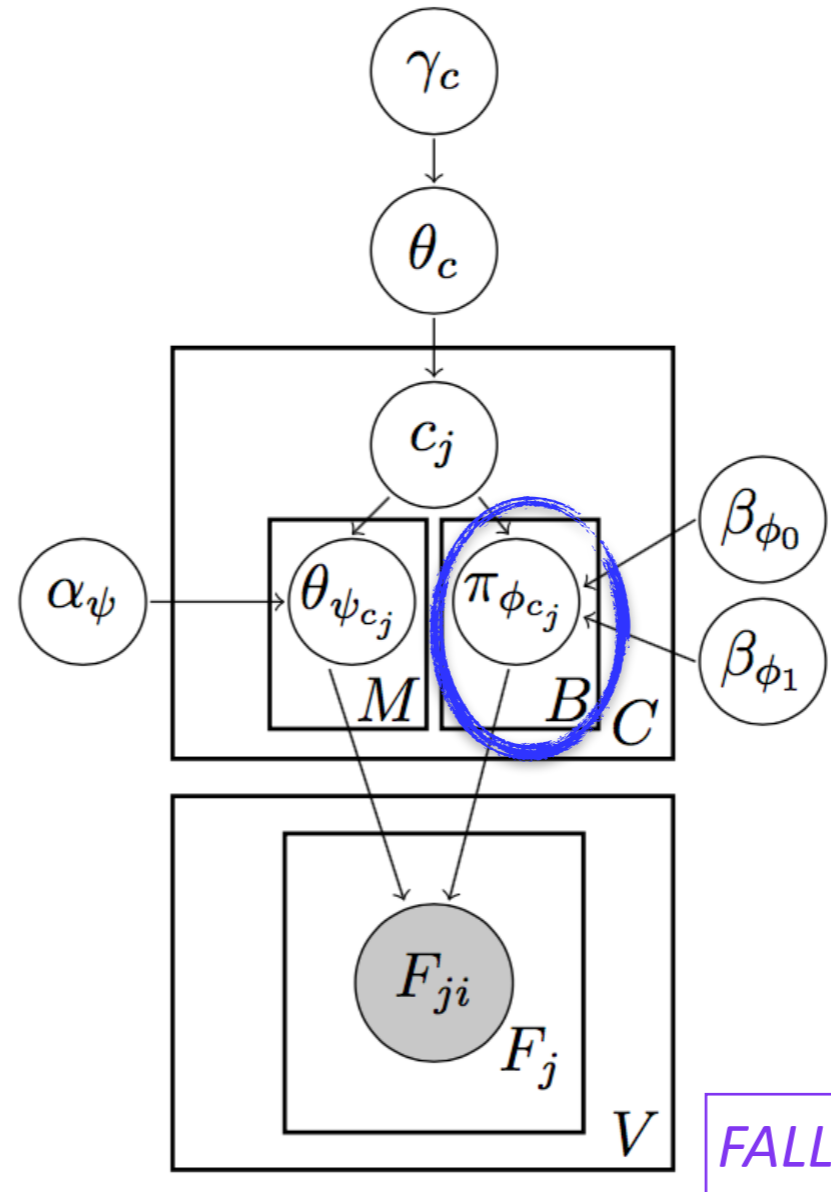
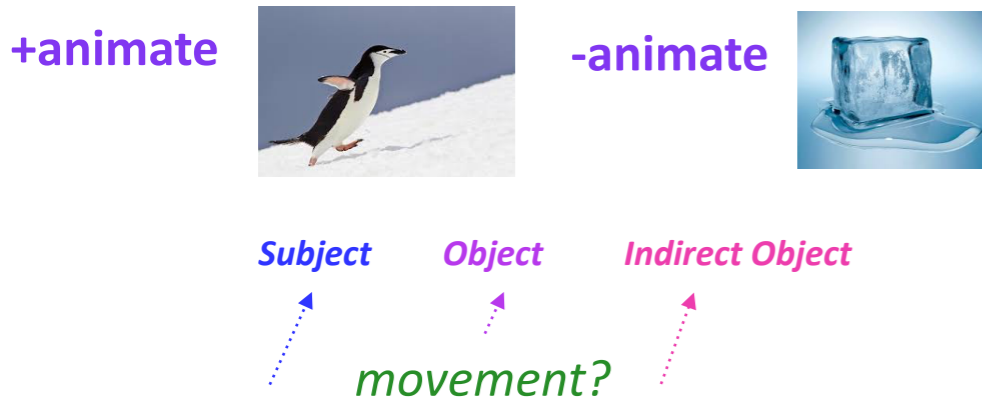


Goal: Model the developmental trajectory from 3 to 4 to 5 years old



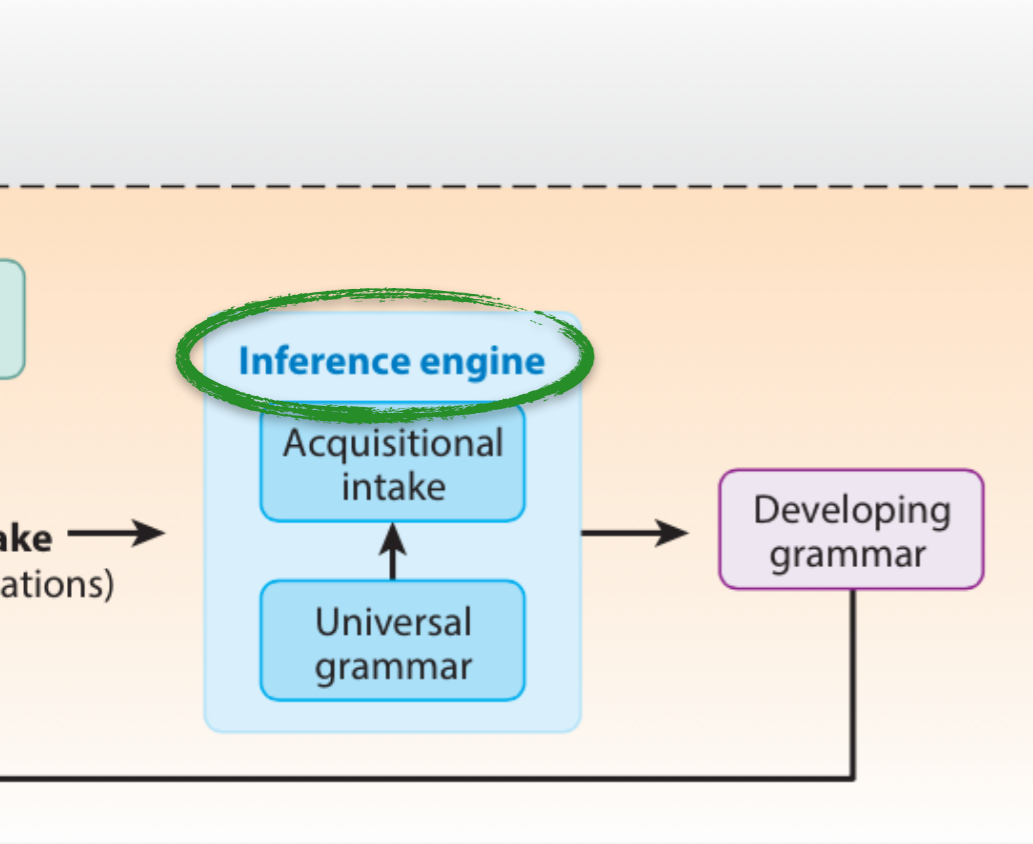
Binary choices:

- +/-animate subject
- +/-animate object
- +/-animate indirect object
- +/-movement (when +exp-mapping)

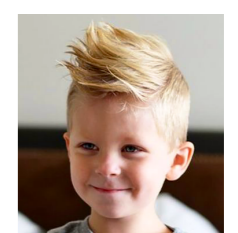


| | | |
|----------------------|----------------|--------------|
| <i>unaccusatives</i> | | |
| <i>+anim</i> | <i>Subject</i> | <i>-anim</i> |
| 0.3 | | 0.7 |

-anim
 "it's falling off"
 (3x) "it's falling off"
 "it's falling off"



Goal: Model the developmental trajectory from 3 to 4 to 5 years old



Binary choices:

+animate



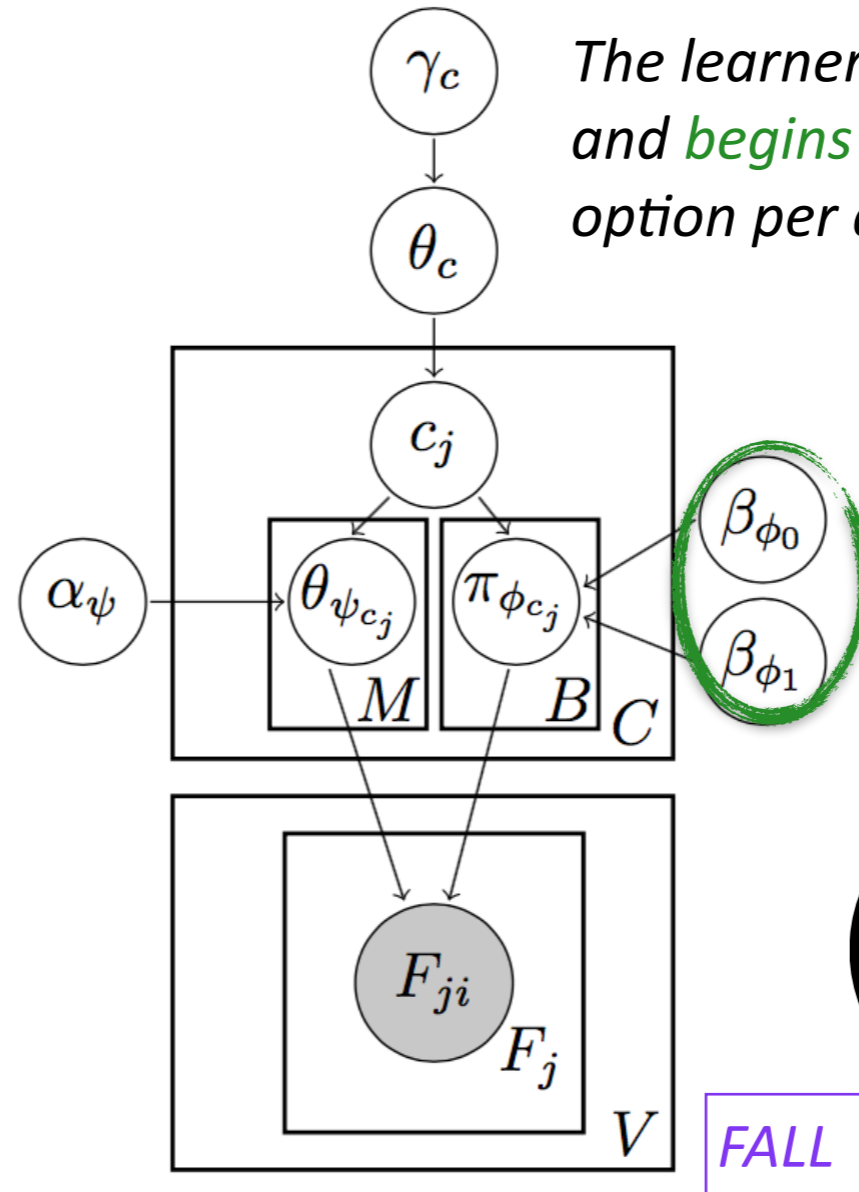
-animate



Subject Object Indirect Object

↑ ↑ ↑

movement?



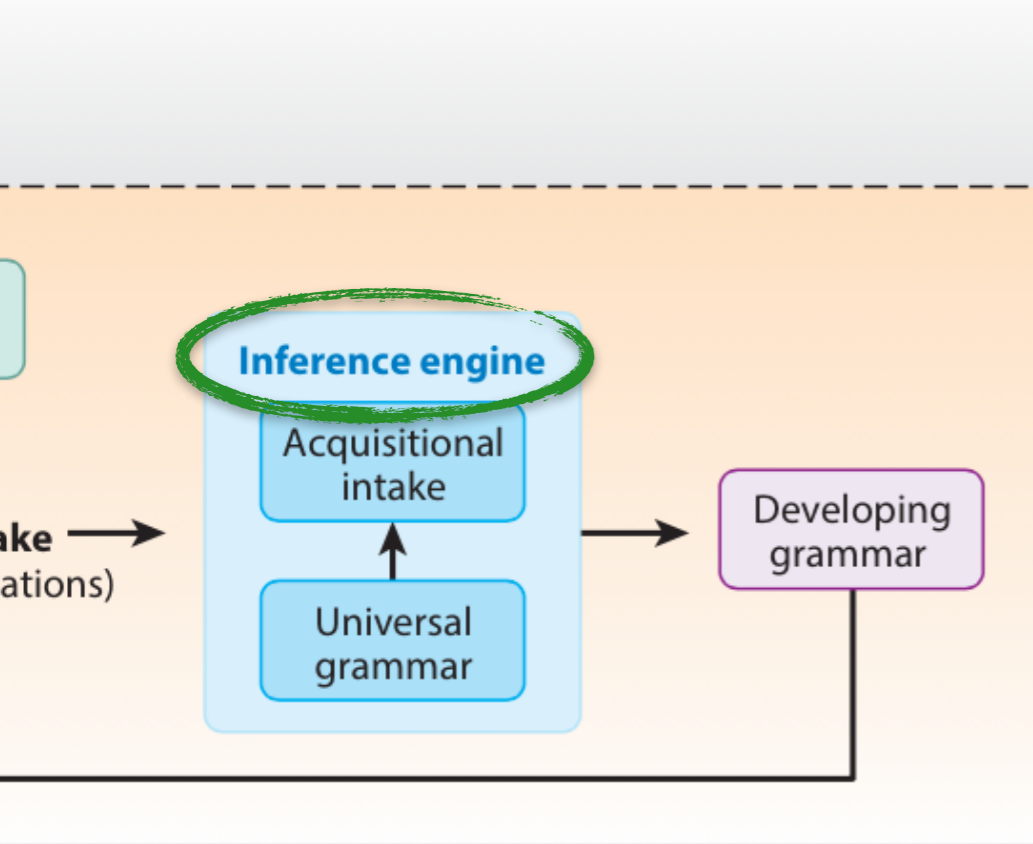
The learner infers these probabilities, and begins with no bias towards either option per class.

unaccusatives

| | | |
|-------|---------|-------|
| +anim | Subject | -anim |
| 0.3 | | 0.7 |

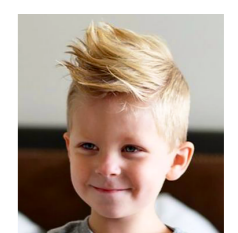
-anim
 "it's falling off"
 (3x) "it's falling off"
 "it's falling off"

FALL



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

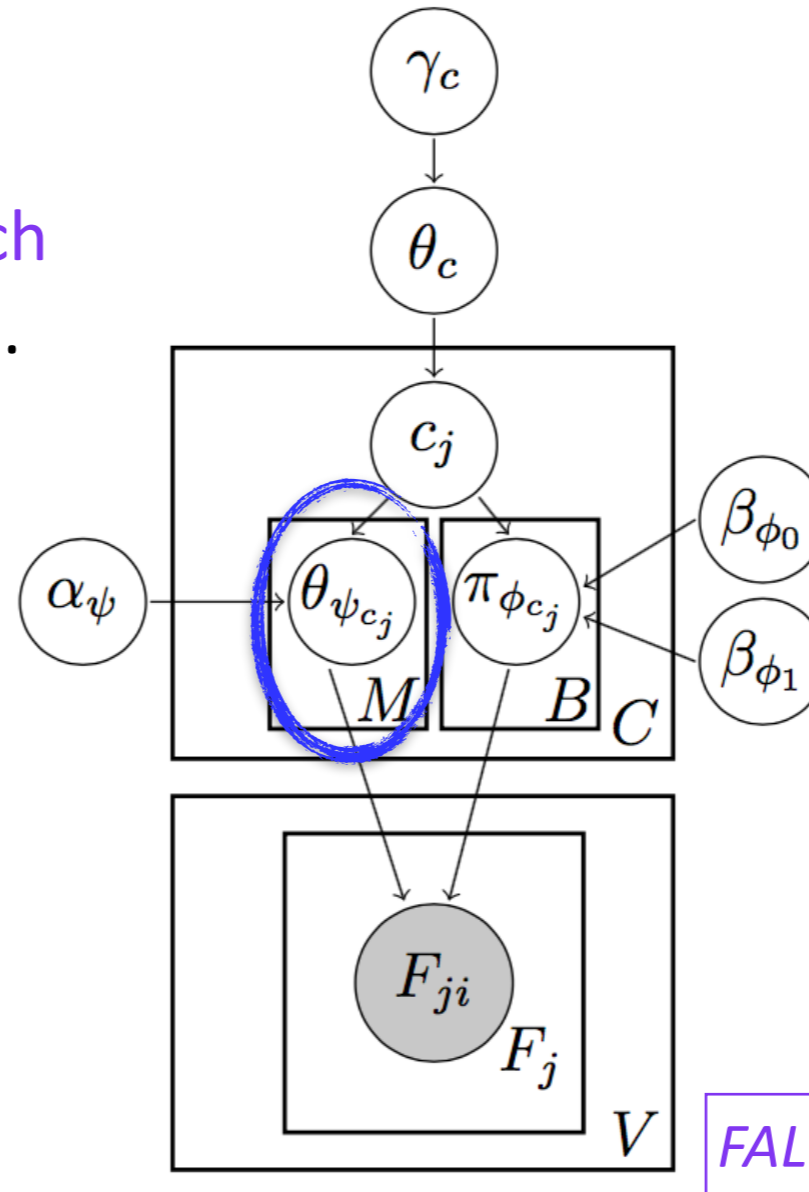
<3yrs <4yrs <5yrs



These characteristics include multinomial choices such as which syntactic frame a verb appears in.

Each class has a probability of preferring each option.

- NP V PRT* 0.3
- NP V* 0.25
- ...
- NP V S* 0

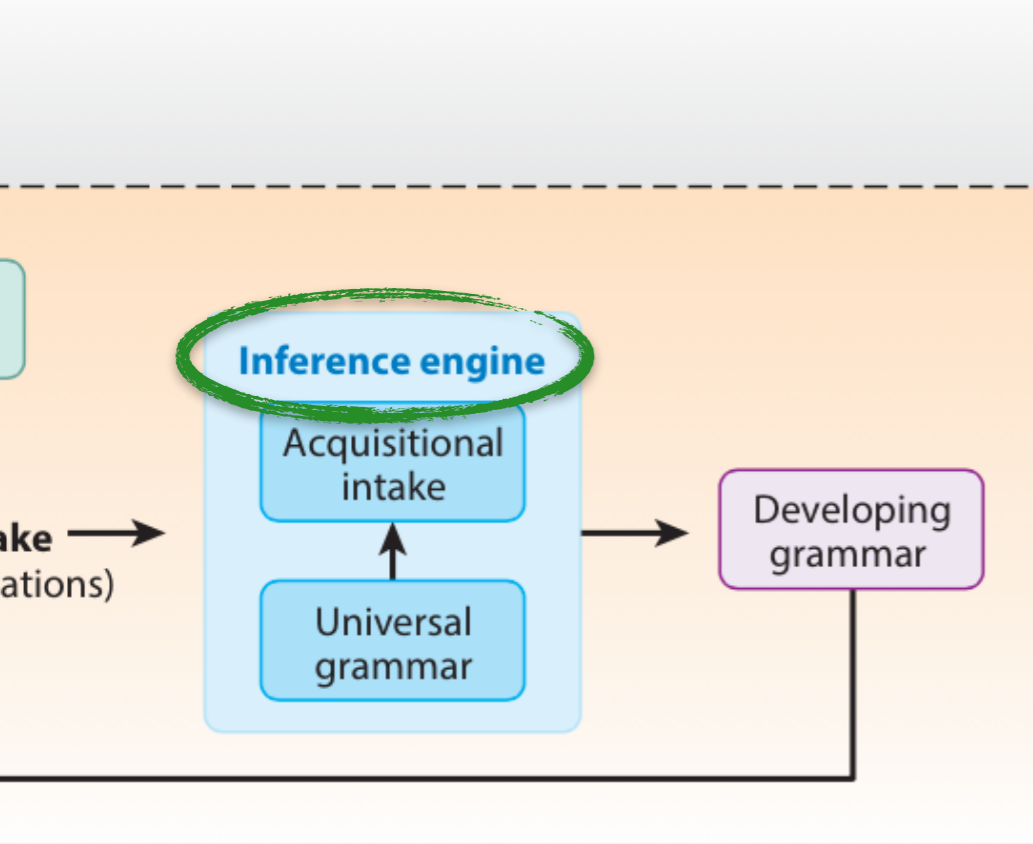


unaccusatives

| | | |
|--------------|----------------|--------------|
| <i>+anim</i> | <i>Subject</i> | <i>-anim</i> |
| 0.3 | | 0.7 |

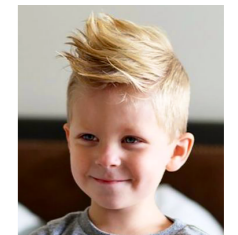
-anim
 "it's falling off"
 (3x) *NP V PRT*
 "it's falling off"
 "it's falling off"

FALL



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



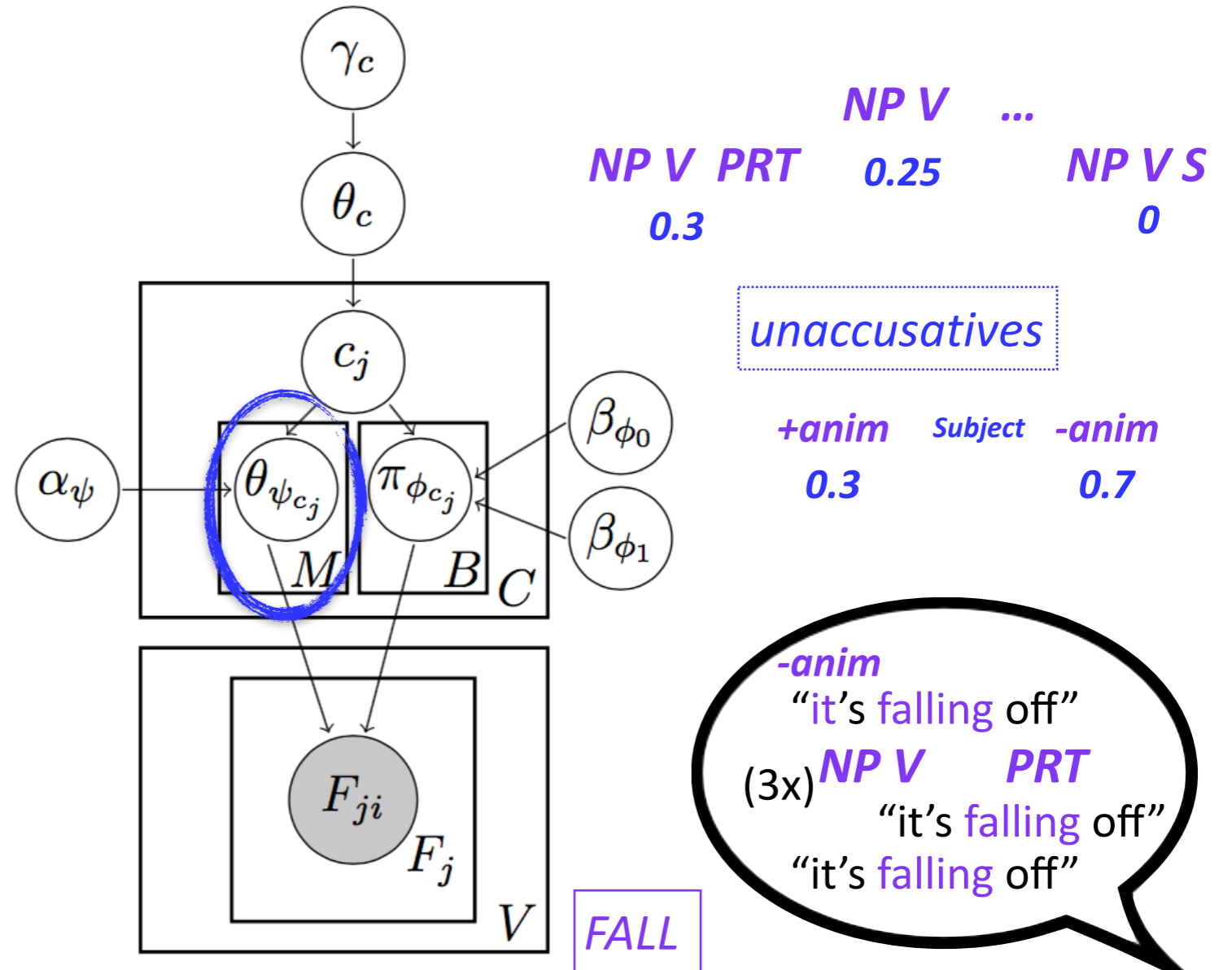
Multinomial choices:

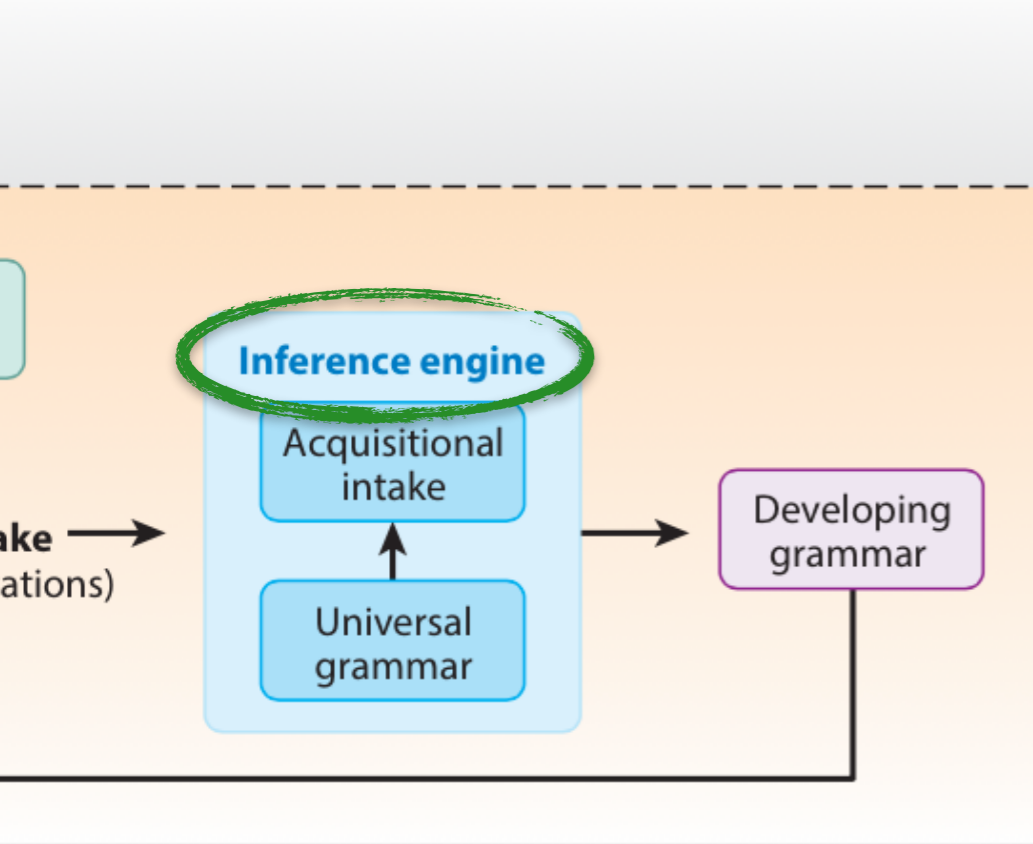
- which syntactic frame is used **NP V PRT**
- (if **-exp-mapping**)
- position of **doer/Highest** role
- position of **done-to/next-highest** role
- position of **done-by/third-highest** role



Agent > Experiencer >
 Theme > Patient >
 (Source, Goal, Instrument)

Subject Object Indirect Object





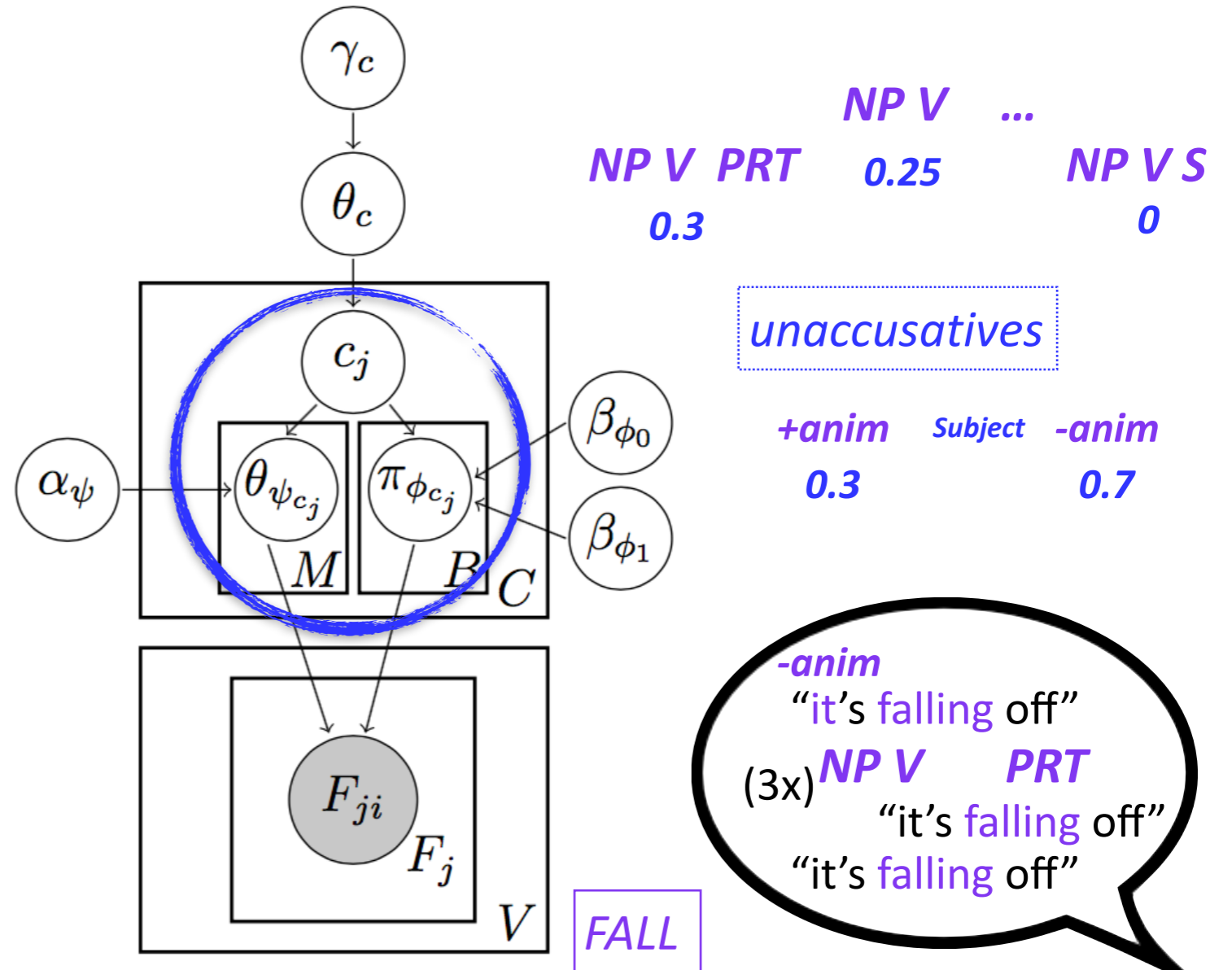
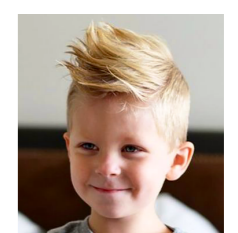
Inference: The learner forms different classes because **the characteristics are sufficiently different** for each class.

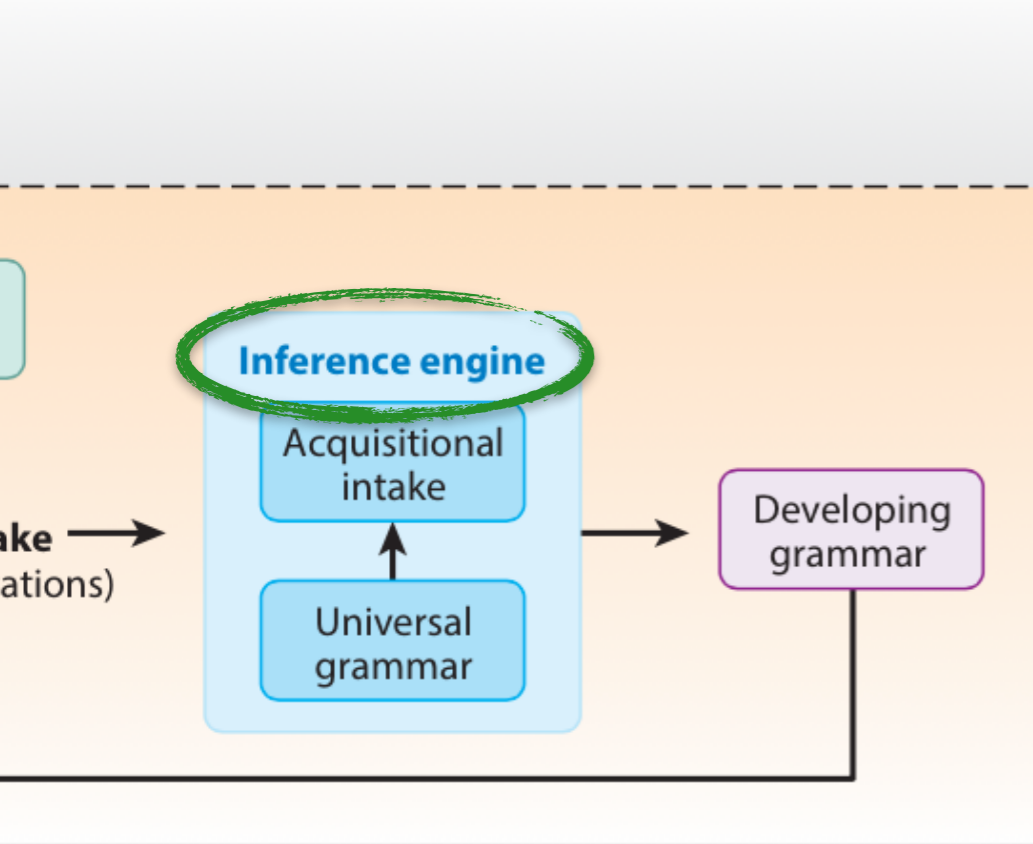
Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs

<5yrs



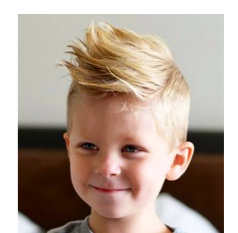


Goal: Model the developmental trajectory from 3 to 4 to 5 years old

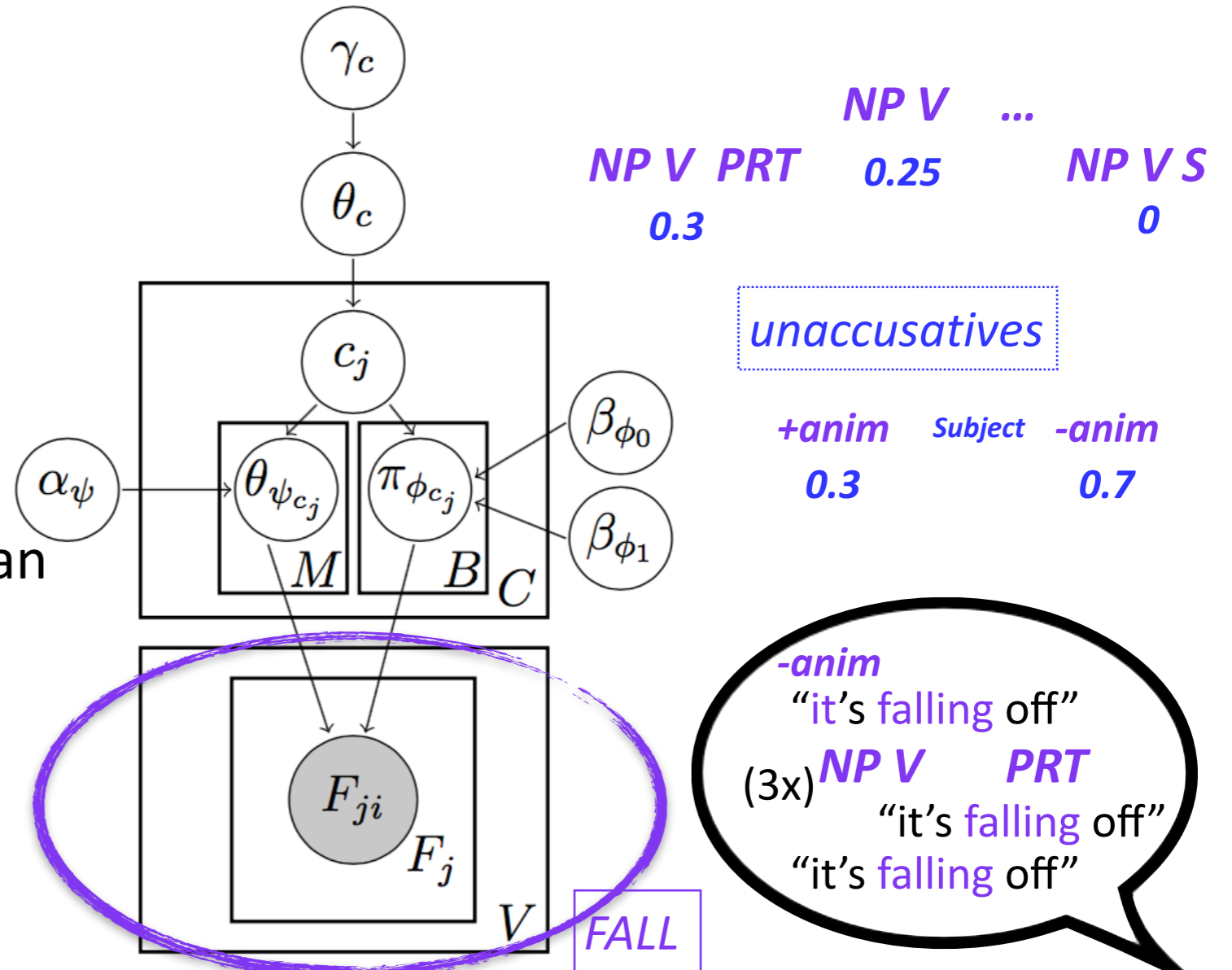
<3yrs

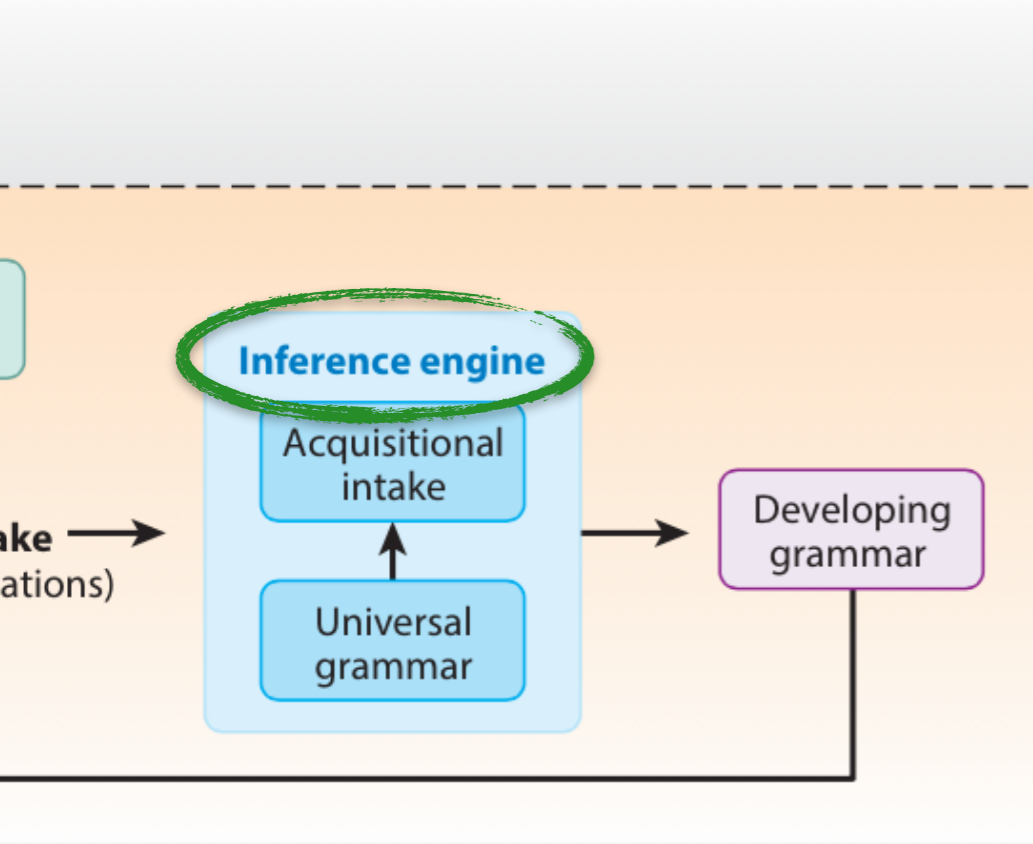
<4yrs

<5yrs



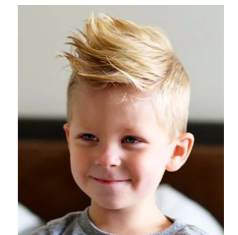
Using the observed instances of verb usage, Bayesian inference can be used to determine ...





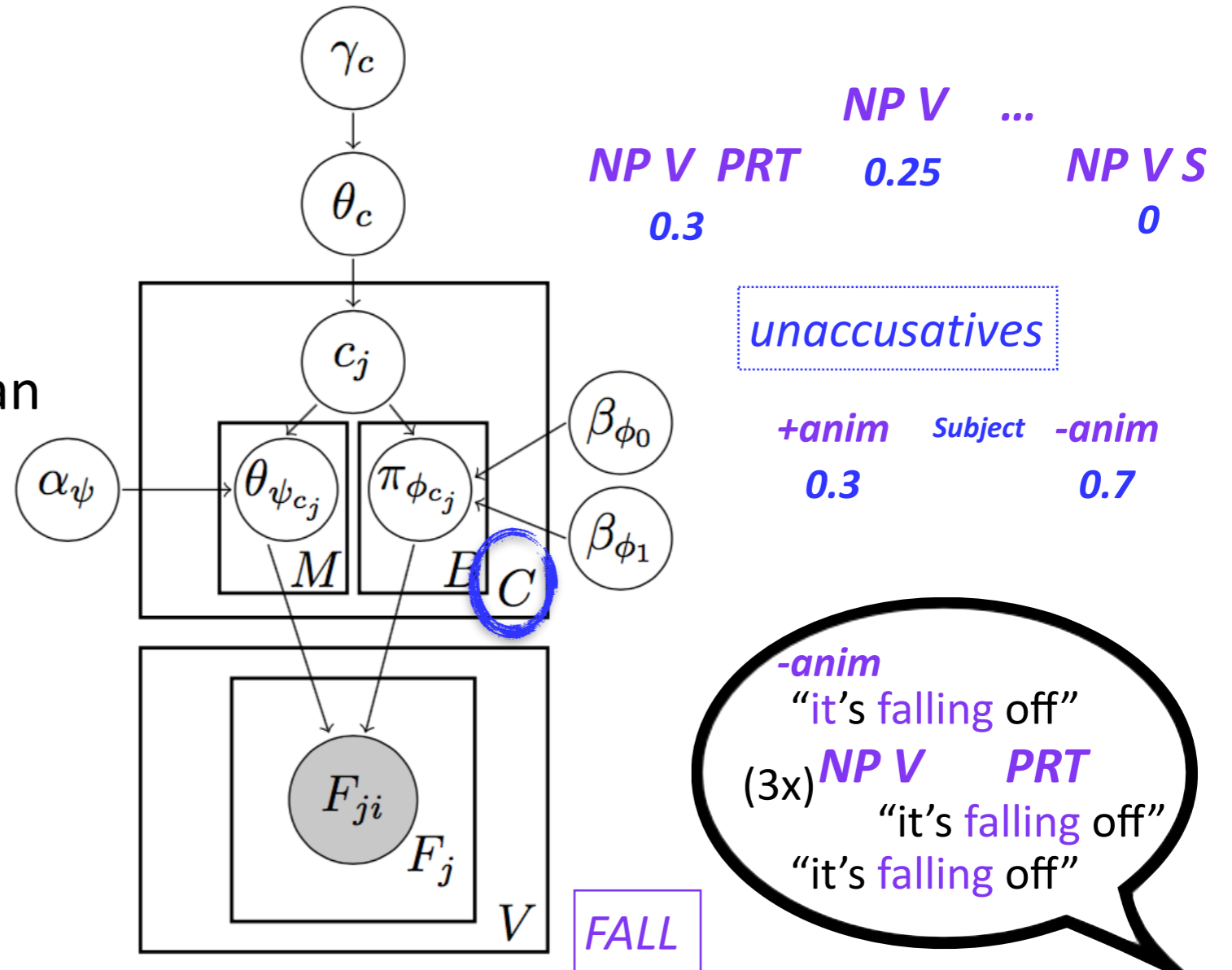
Goal: Model the developmental trajectory from 3 to 4 to 5 years old

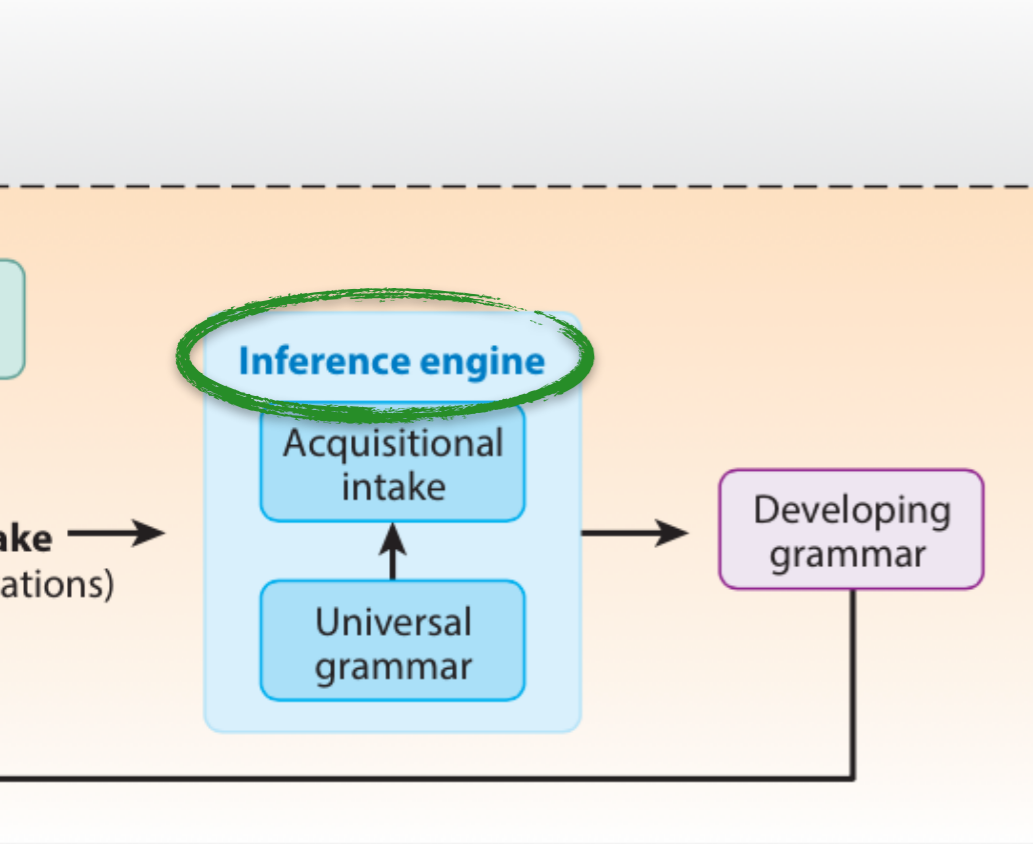
<3yrs <4yrs <5yrs



Using the observed instances of verb usage, Bayesian inference can be used to determine

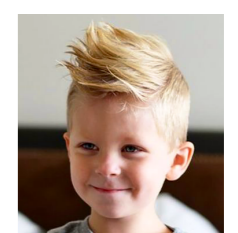
- how many classes there are





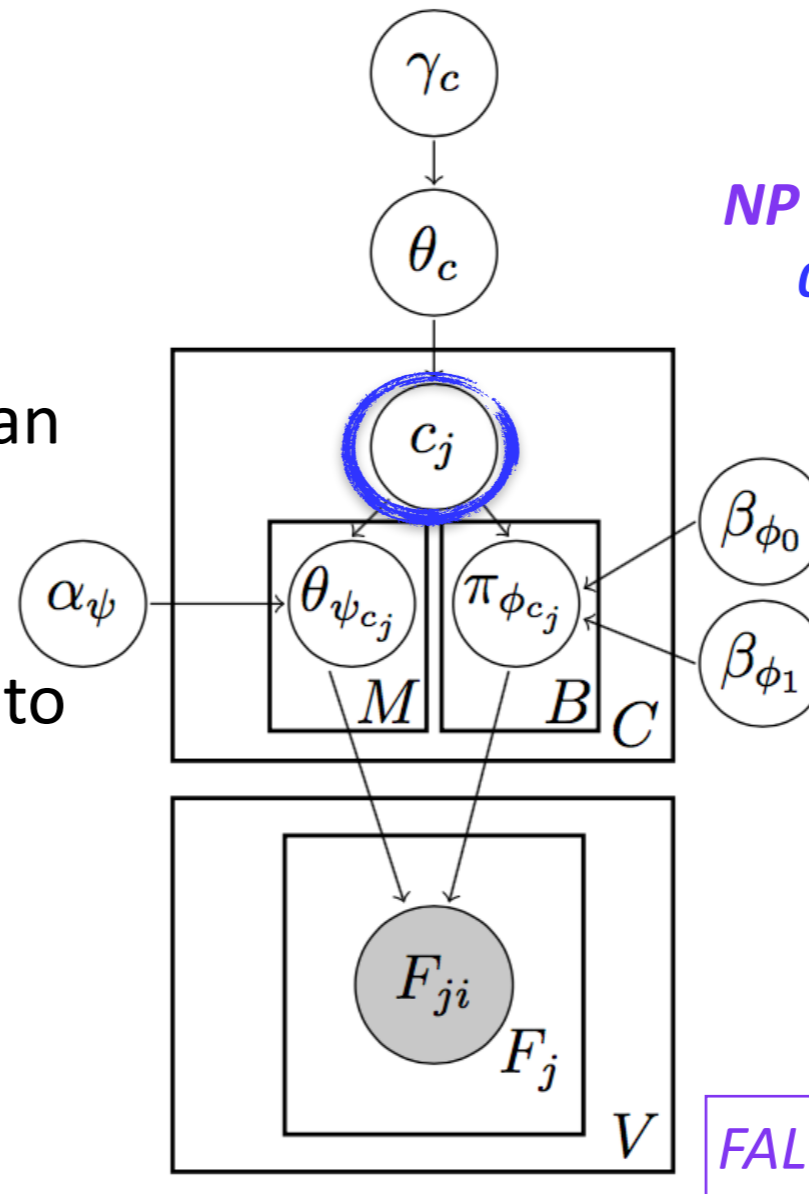
Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



Using the observed instances of verb usage, Bayesian inference can be used to determine

- how many classes there are
- which class each verb belongs to



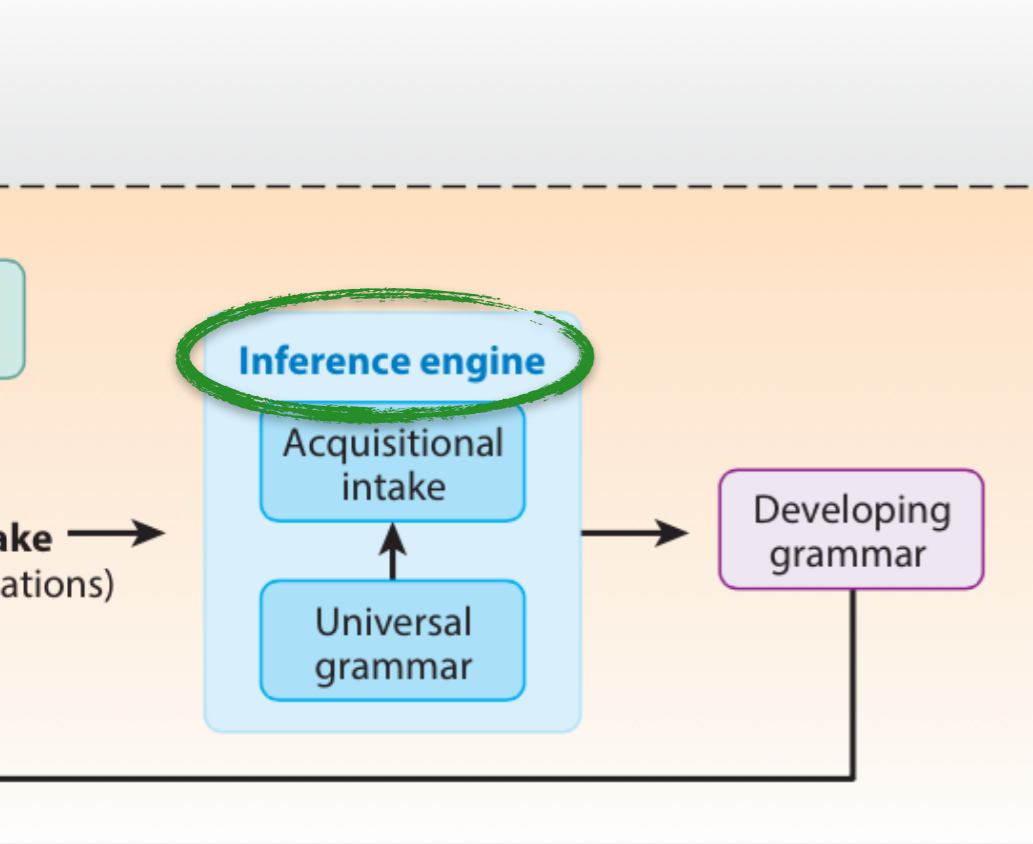
| | | | | |
|-----------------|--|-------------|-----|---------------|
| | | <i>NP V</i> | ... | |
| <i>NP V PRT</i> | | 0.25 | | <i>NP V S</i> |
| 0.3 | | | | 0 |

unaccusatives

| | | |
|--------------|----------------|--------------|
| <i>+anim</i> | <i>Subject</i> | <i>-anim</i> |
| 0.3 | | 0.7 |

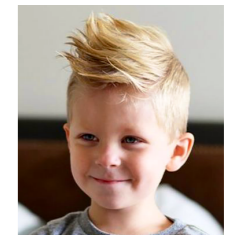
-anim
 "it's falling off"
 (3x) *NP V PRT*
 "it's falling off"
 "it's falling off"

FALL



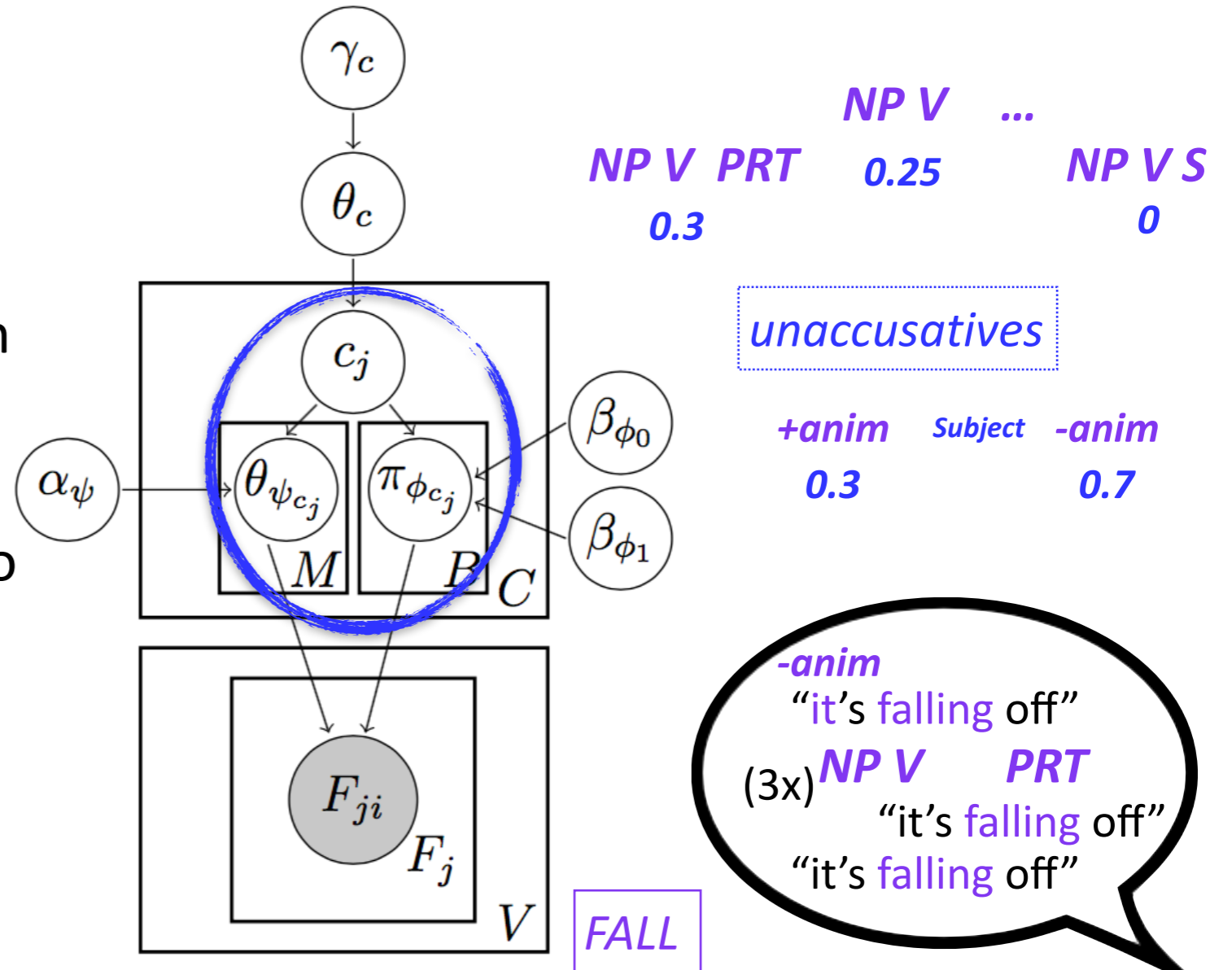
Goal: Model the developmental trajectory from 3 to 4 to 5 years old

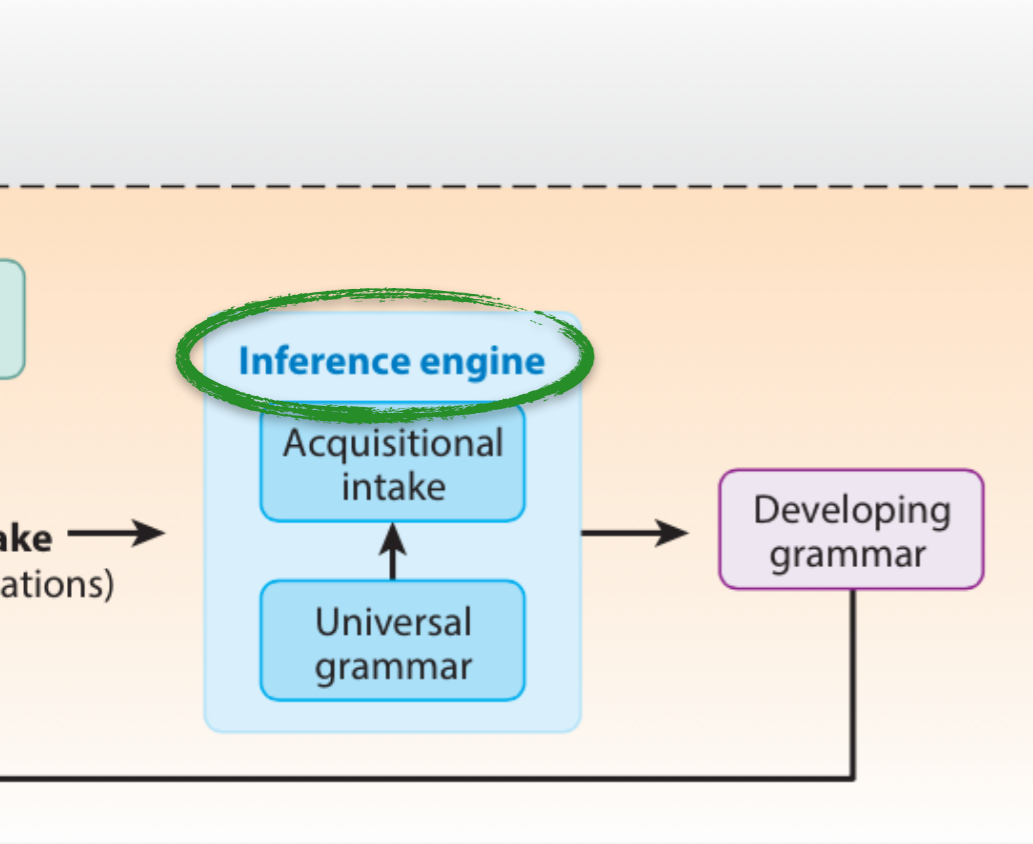
<3yrs <4yrs <5yrs



Using the observed instances of verb usage, Bayesian inference can be used to determine

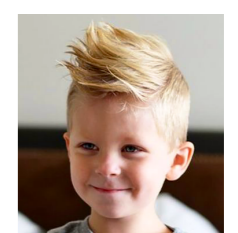
- how many classes there are
- which class each verb belongs to
- what the characteristics are of each class





Goal: Model the developmental trajectory from 3 to 4 to 5 years old

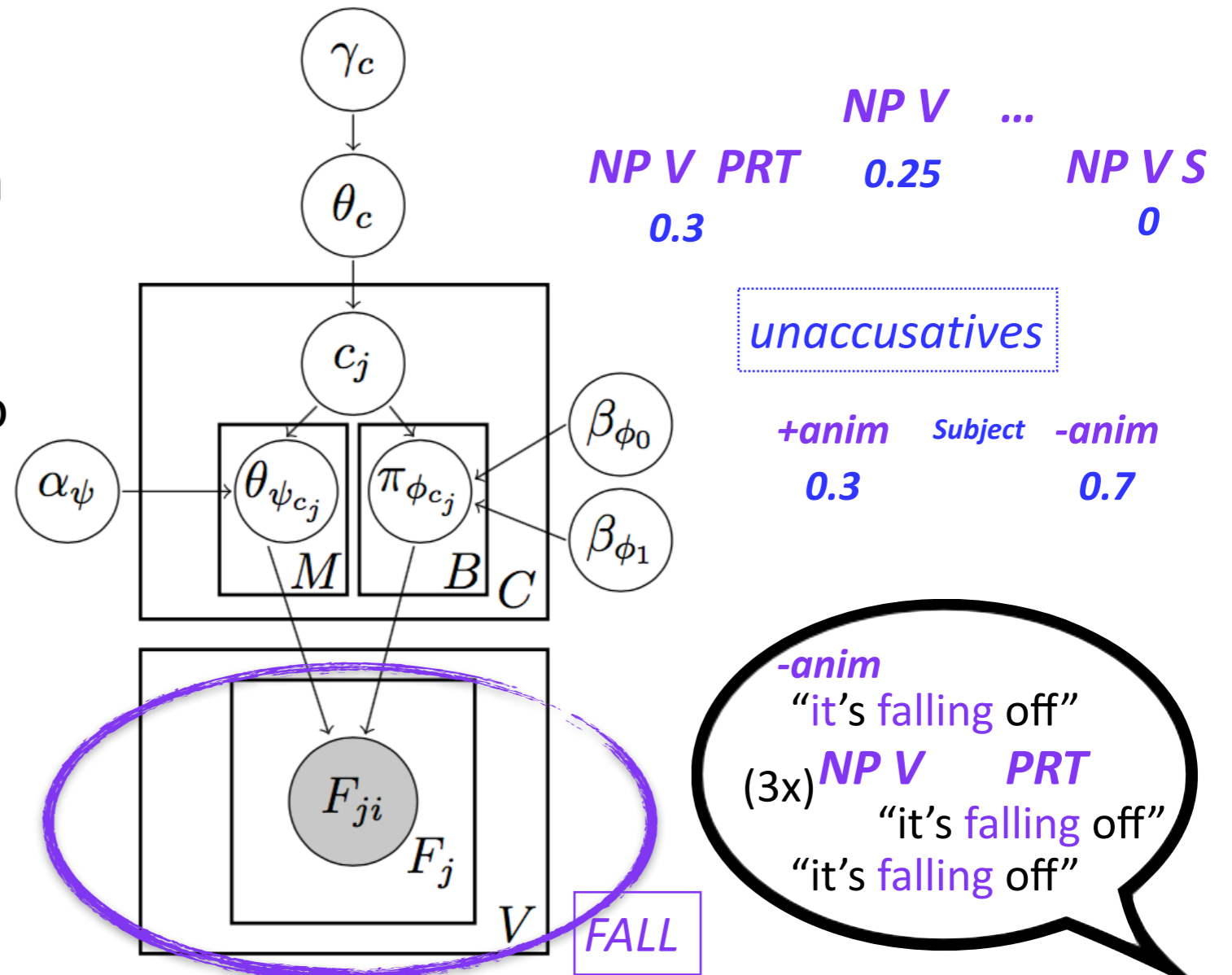
<3yrs <4yrs <5yrs

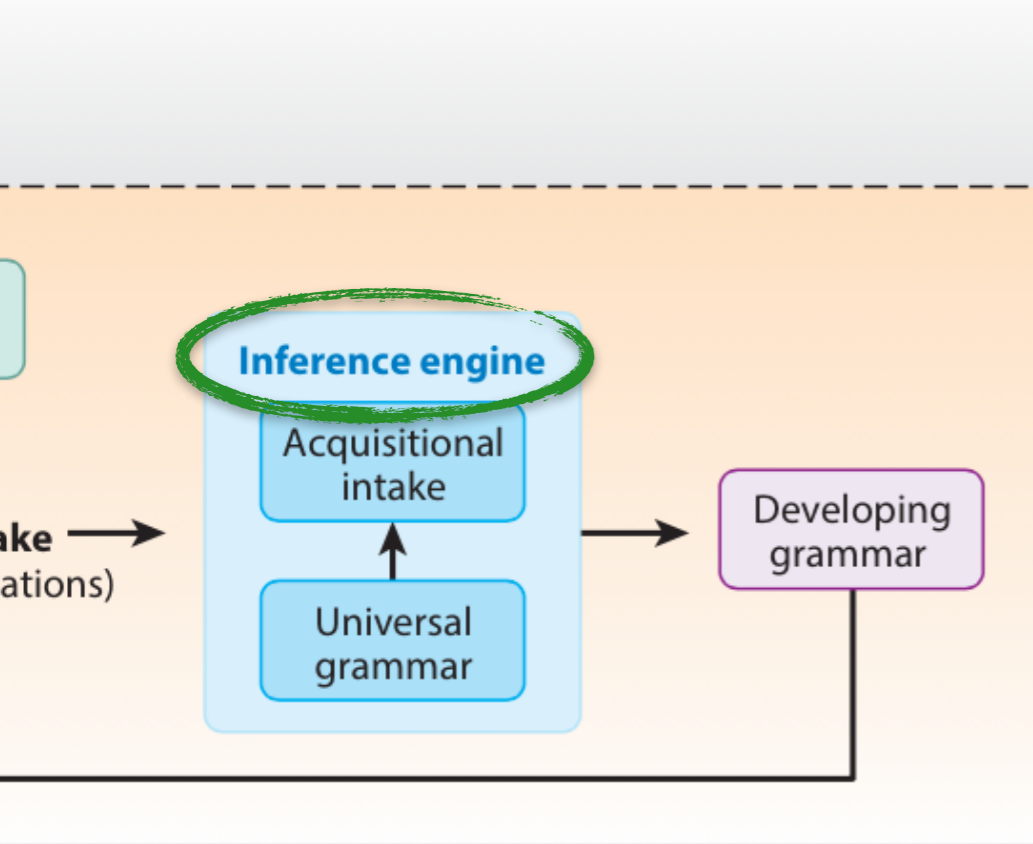


Using the observed instances of verb usage, Bayesian inference can be used to determine

- how many classes there are
- which class each verb belongs to
- what the characteristics are of each class

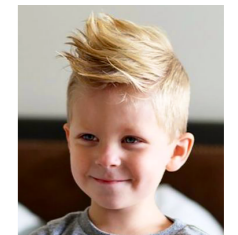
Best answer: maximizes the probability of the observed data.





Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs

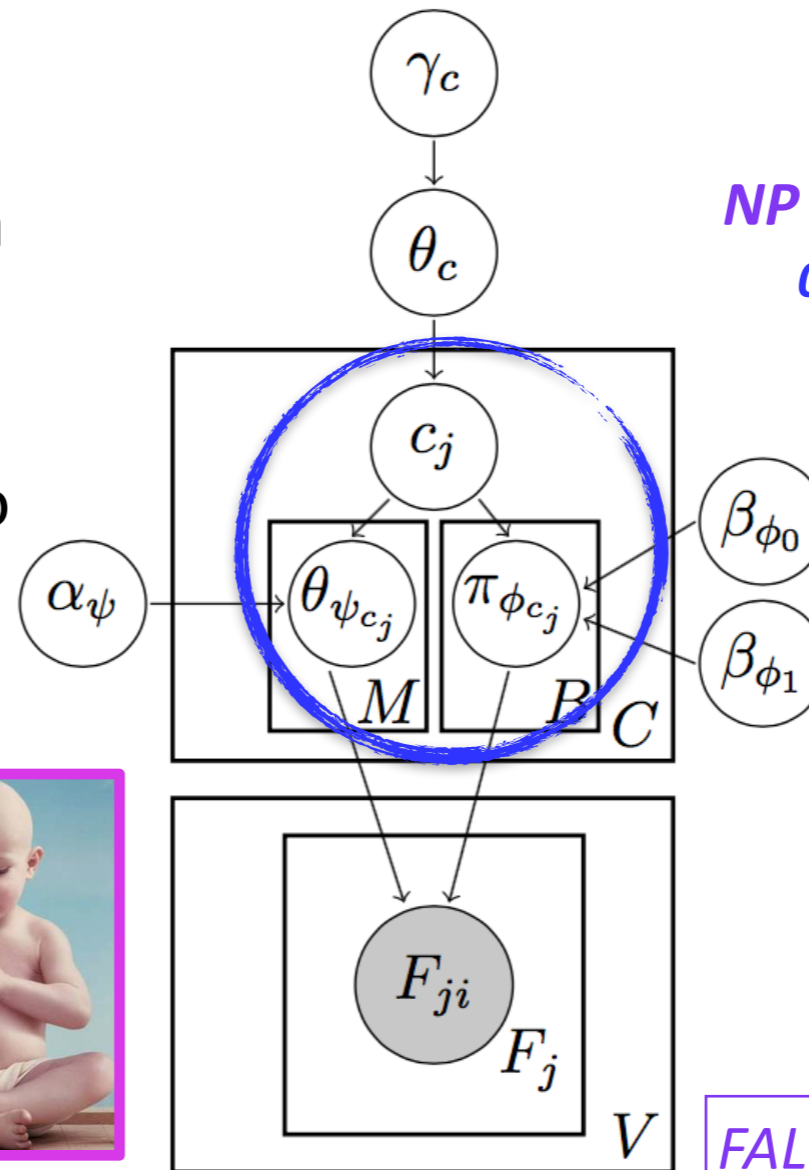


Using the observed instances of verb usage, Bayesian inference can be used to determine

- how many classes there are
- which class each verb belongs to
- what the characteristics are of each class

$$p_{c_j} = P(c_j | c_{-j}, \gamma_c, F_{-j}, \lambda) = p_{cat_j} * p_{binary_{c_j}} * p_{multinomial_{c_j}}$$

+ Gibbs sampling (method guaranteed to find optimal answer, given sufficient time to search the hypothesis space)



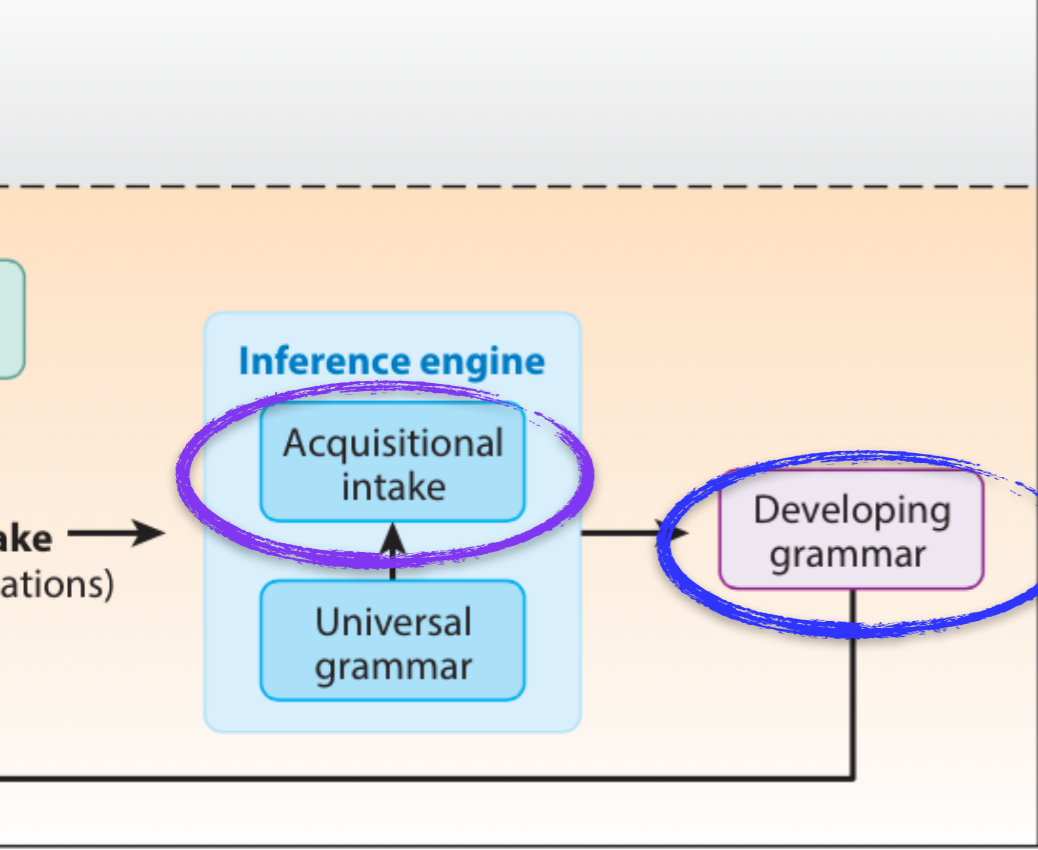
| | | | |
|-----------------|-------------|-----|---------------|
| | <i>NP V</i> | ... | |
| <i>NP V PRT</i> | 0.25 | | <i>NP V S</i> |
| 0.3 | | | 0 |

unaccusatives

| | | |
|--------------|----------------|--------------|
| <i>+anim</i> | <i>Subject</i> | <i>-anim</i> |
| 0.3 | | 0.7 |

-anim
 "it's falling off"
 (3x) *NP V PRT*
 "it's falling off"
 "it's falling off"

FALL



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



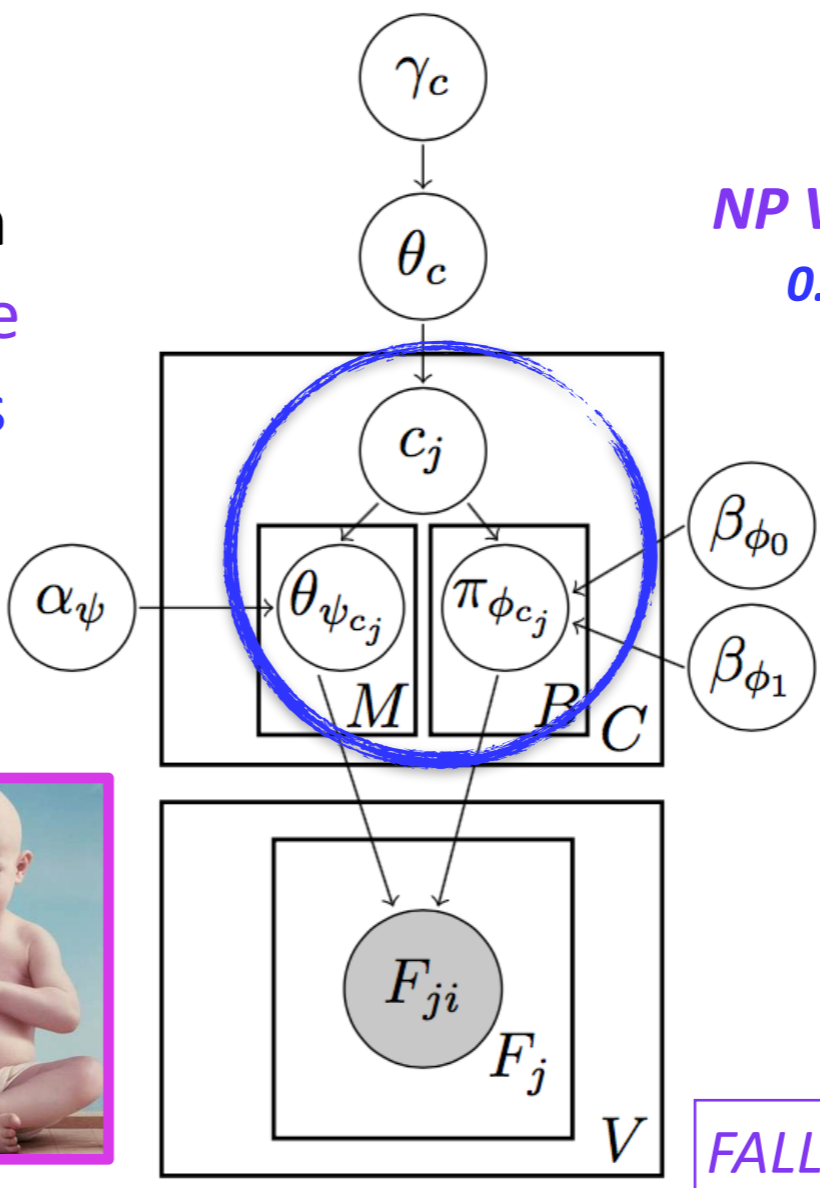
Goal: Determine if the information provided in the **acquisitional intake** is **sufficient** to identify **verb classes** this way.

+surfmorph -surfmorph

rUTAH UTAH

-expmap

+expmap



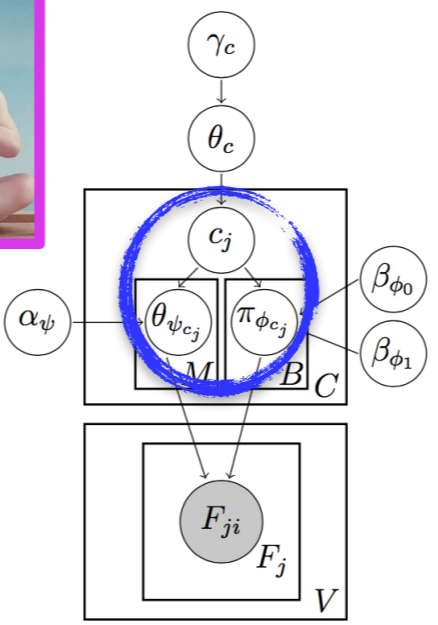
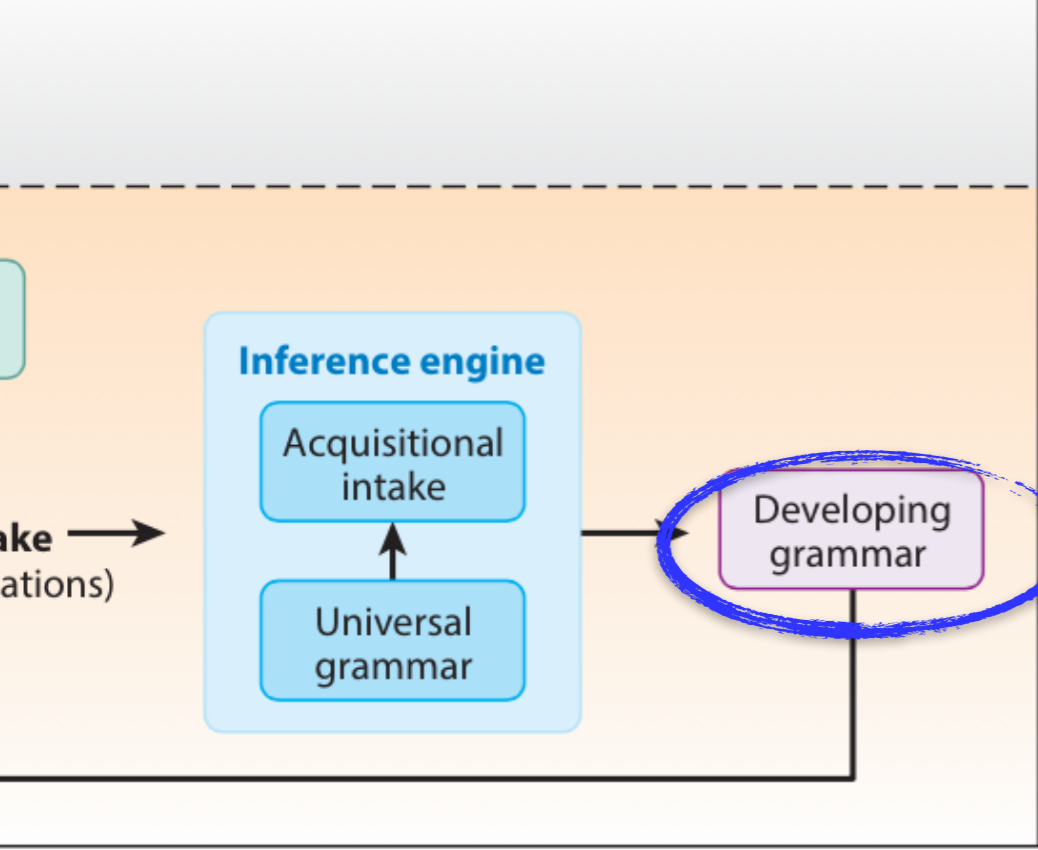
| | | | |
|-----------------|-------------|-----|---------------|
| | <i>NP V</i> | ... | |
| <i>NP V PRT</i> | 0.25 | | <i>NP V S</i> |
| 0.3 | | | 0 |

unaccusatives

| | | |
|-------|---------|-------|
| +anim | Subject | -anim |
| 0.3 | | 0.7 |

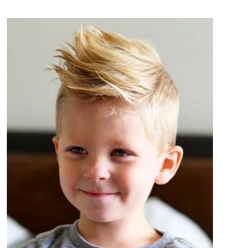
-anim
 "it's falling off"
 (3x) *NP V PRT*
 "it's falling off"
 "it's falling off"

FALL

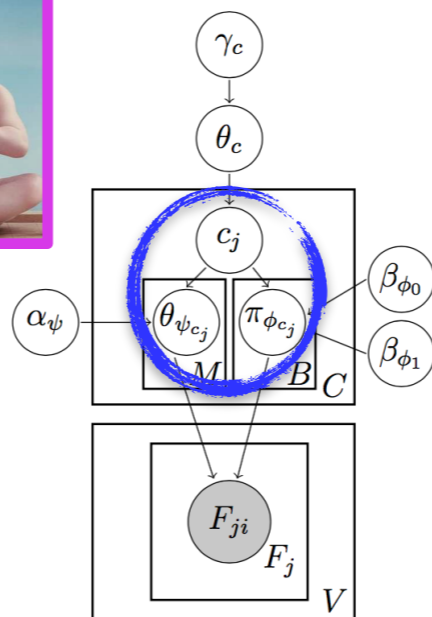
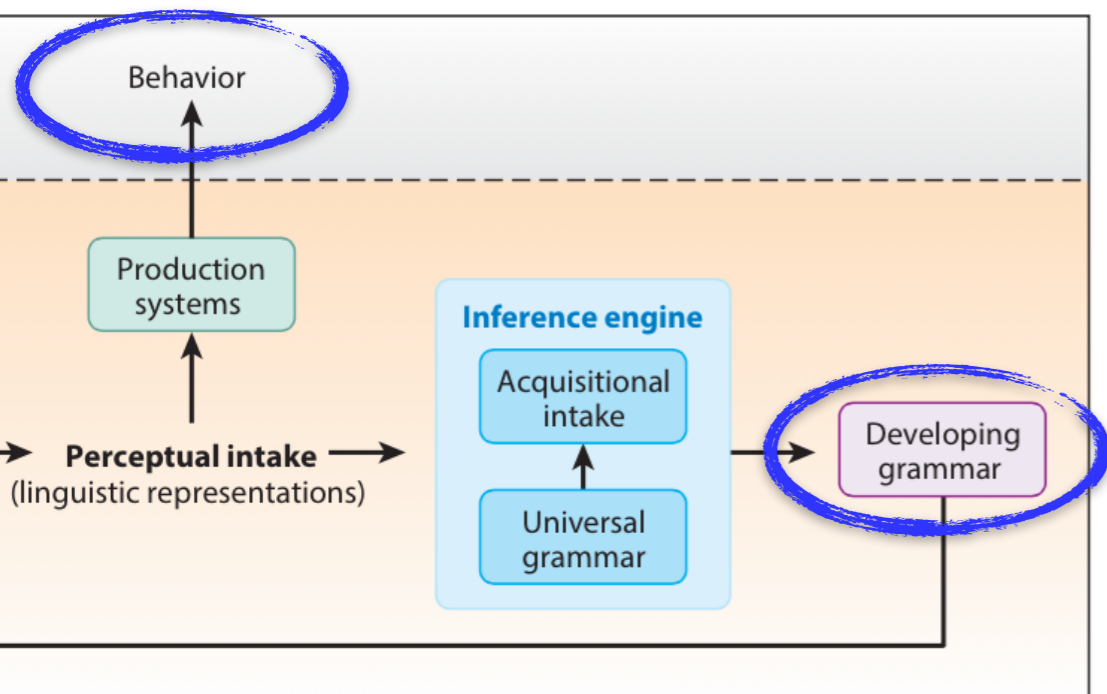


Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



verb classes

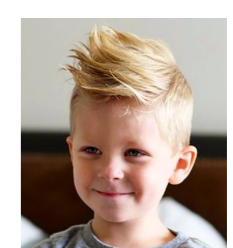


Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs

<5yrs

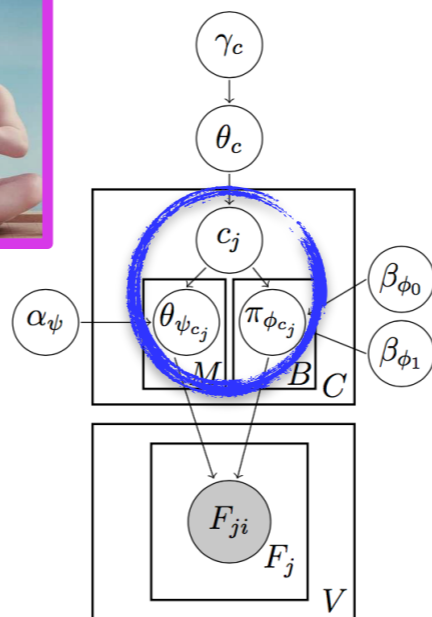
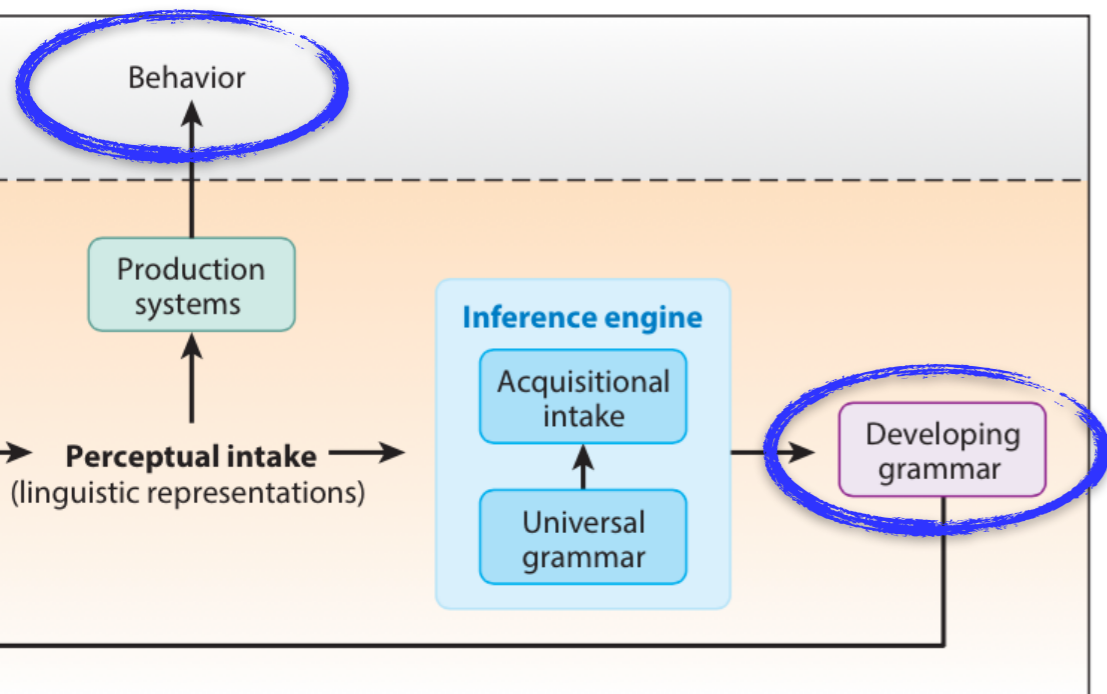


verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs

Yields 12 verb behaviors





Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



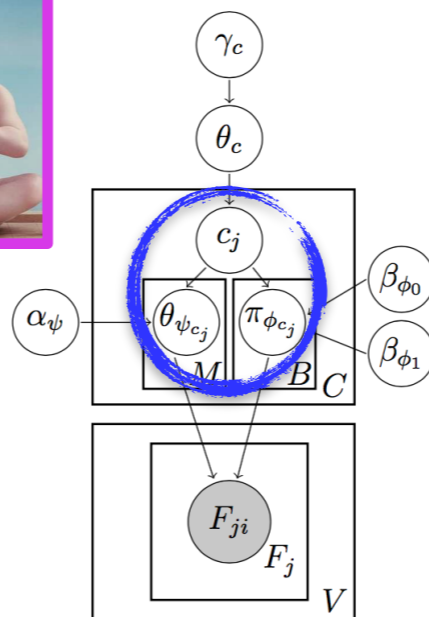
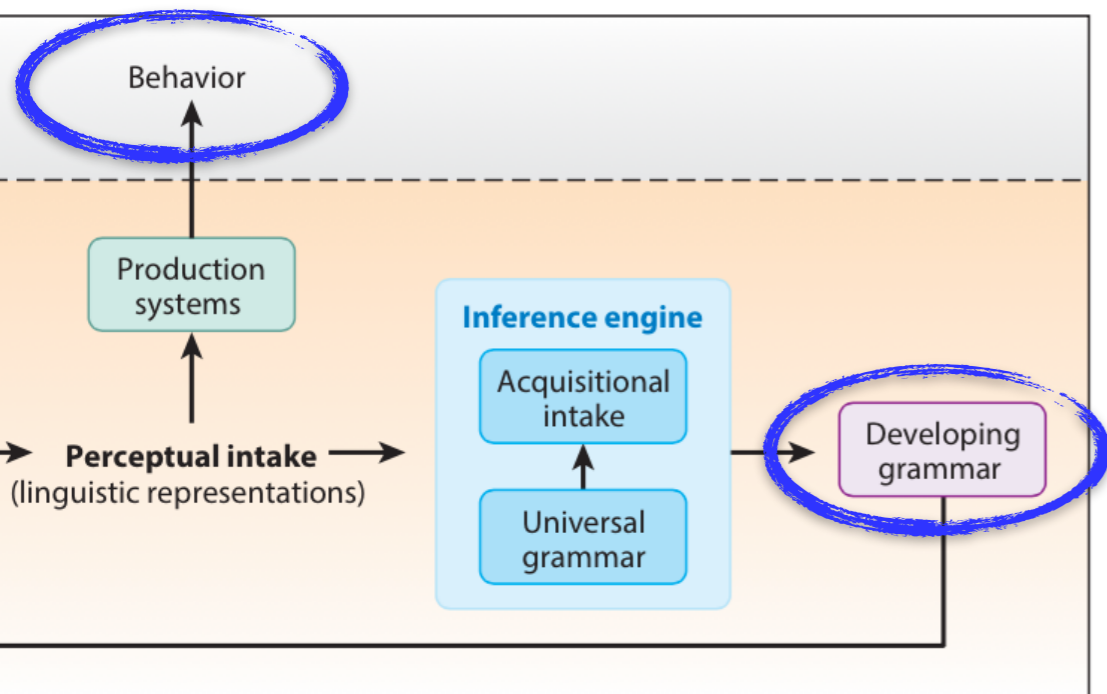
verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



Passives: Maratsos 1974, Maratsos et al. 1985, Gordon & Chafetz 1990, O'Brien et al. 2006, Crain et al. 2009, Messenger et al. 2009, Nguyen et al. 2016

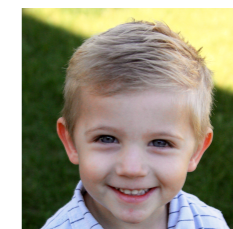
"It was ___-en."
done-to



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<4yrs

<5yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



Passives: Maratsos 1974, Maratsos et al. 1985, Gordon & Chafetz 1990, O'Brien et al. 2006, Crain et al. 2009, Messenger et al. 2009, Nguyen et al. 2016

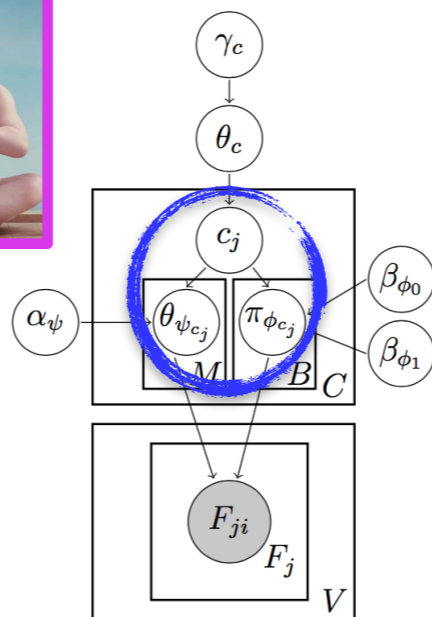
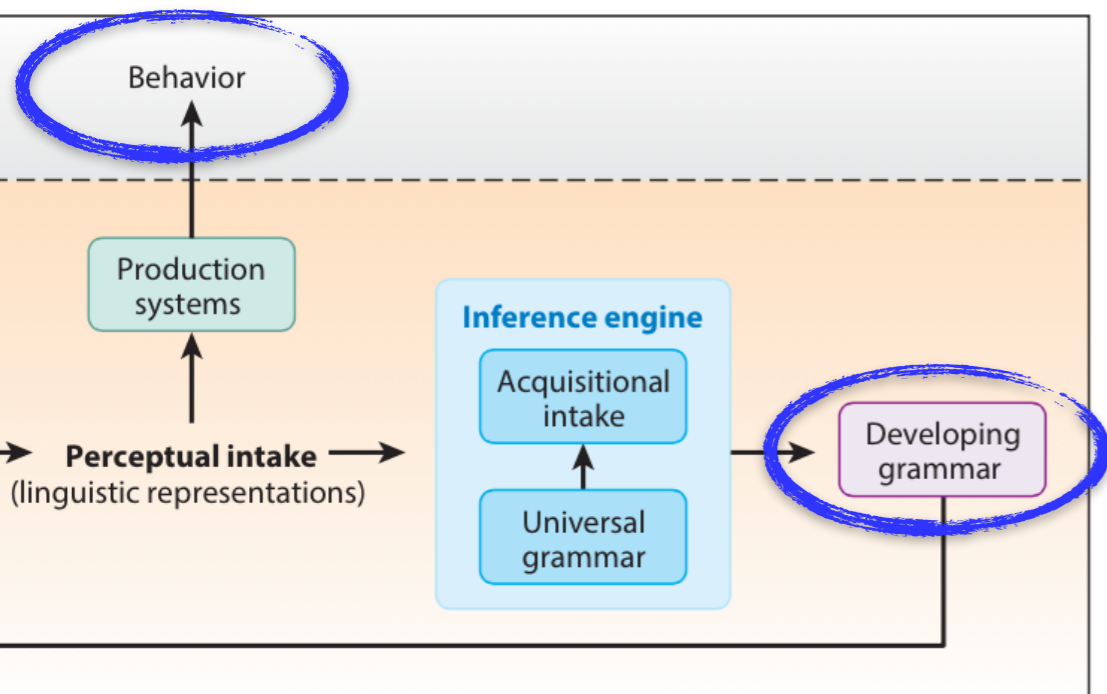
"It was ___-en."
done-to

3yrs



+ = hit, see, ...

- = know, remember, ...



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<5yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



Passives: Maratsos 1974, Maratsos et al. 1985, Gordon & Chafetz 1990, O'Brien et al. 2006, Crain et al. 2009, Messenger et al. 2009, Nguyen et al. 2016

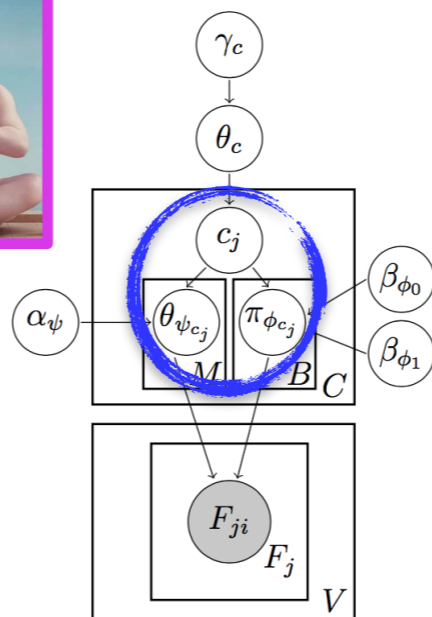
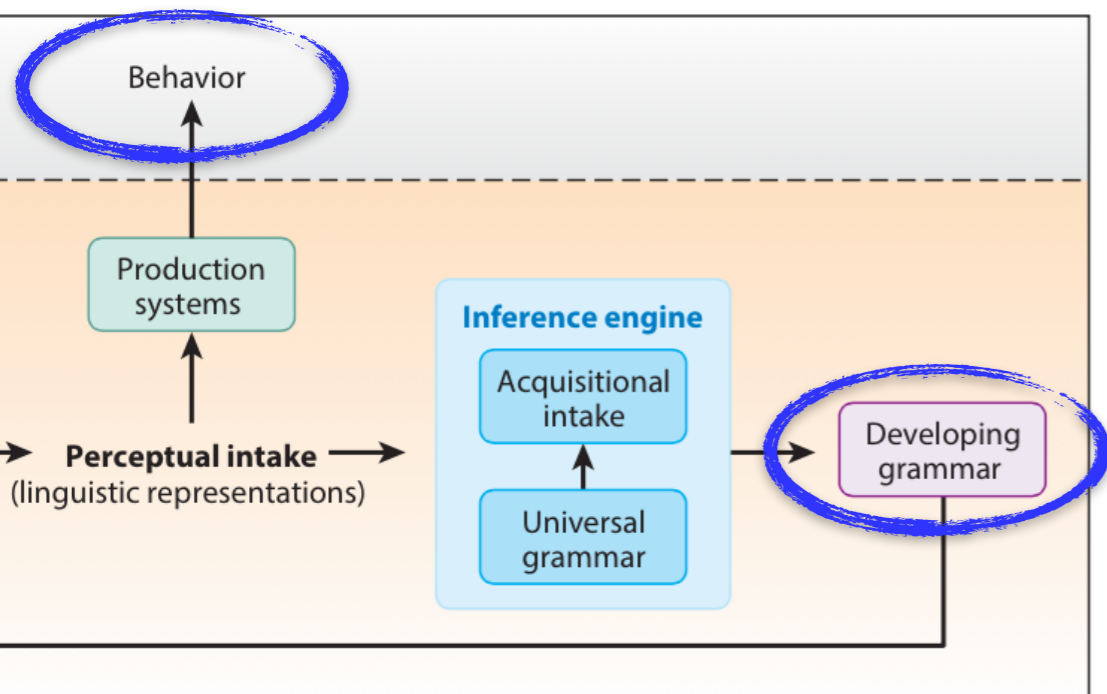
"It was ___-en."
done-to

4yrs



+ = hit, scare, see, ...

- = know, love, remember, ...



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



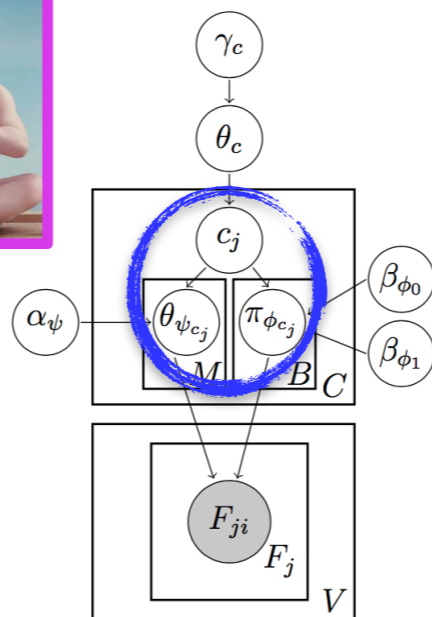
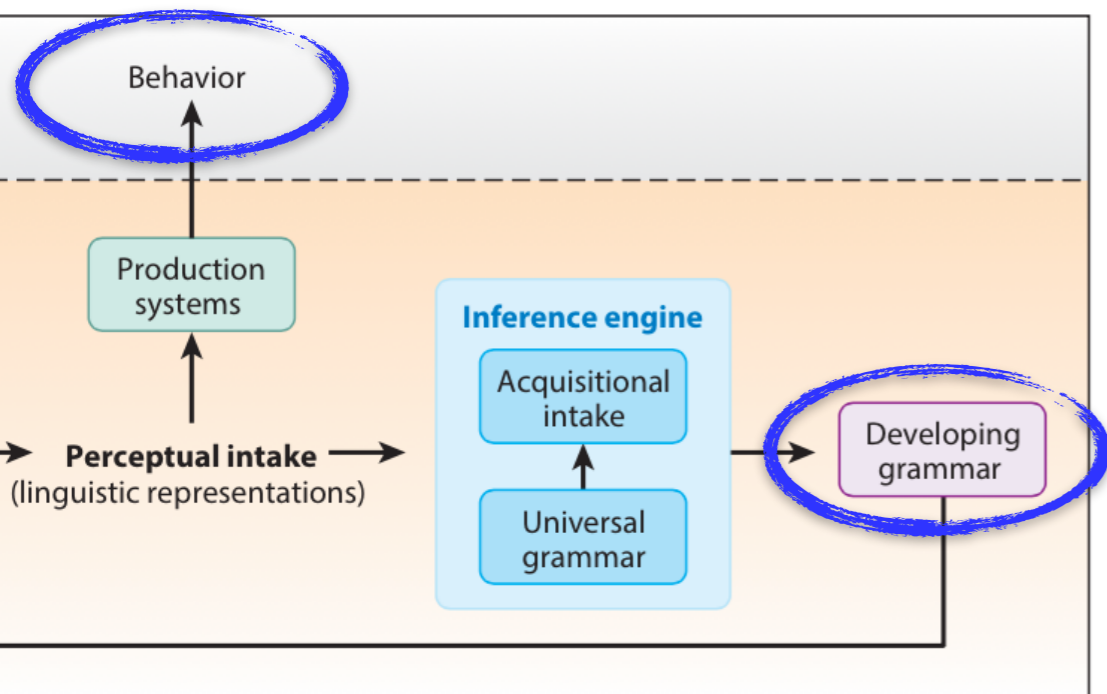
Passives: Maratsos 1974, Maratsos et al. 1985, Gordon & Chafetz 1990, O'Brien et al. 2006, Crain et al. 2009, Messenger et al. 2009, Nguyen et al. 2016

"It was ___-en."
done-to

5yrs



+ = hit, love, scare, see, ...
- = know, remember, ...



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



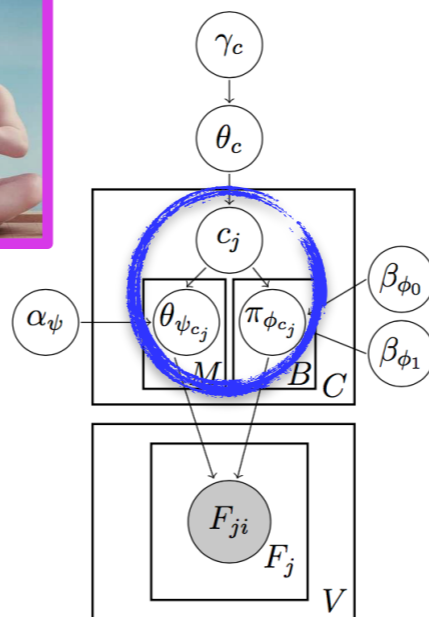
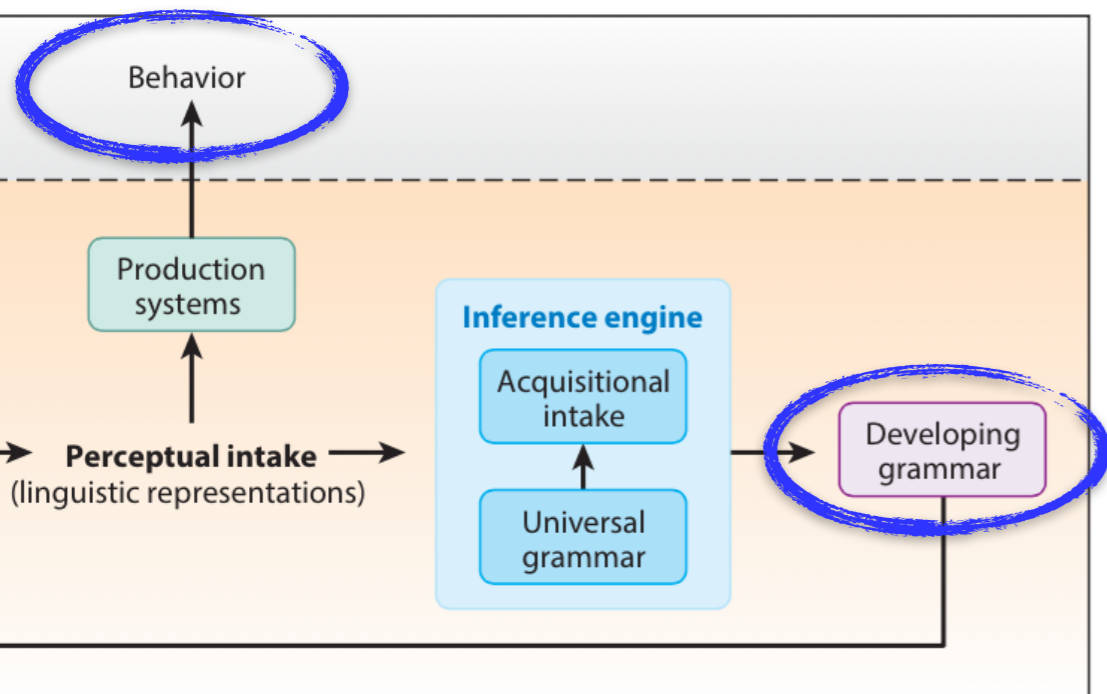
verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



Ditransitives: Gropen et al. 1989, Snedeker & Huang in press, Campbell & Tomasello 2001, Huttenlocher et al. 2004, Conwell & Demuth 2007, Thothathiri & Snedeker 2008

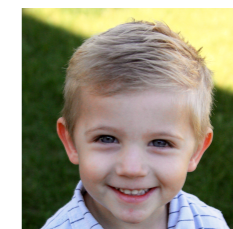
"Jack ___ Lily the thing."



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<4yrs

<5yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



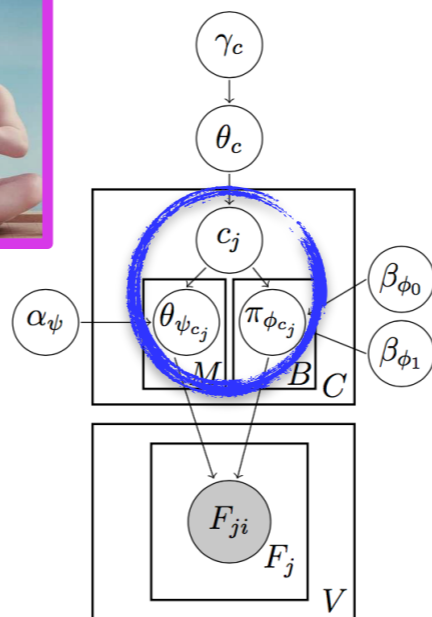
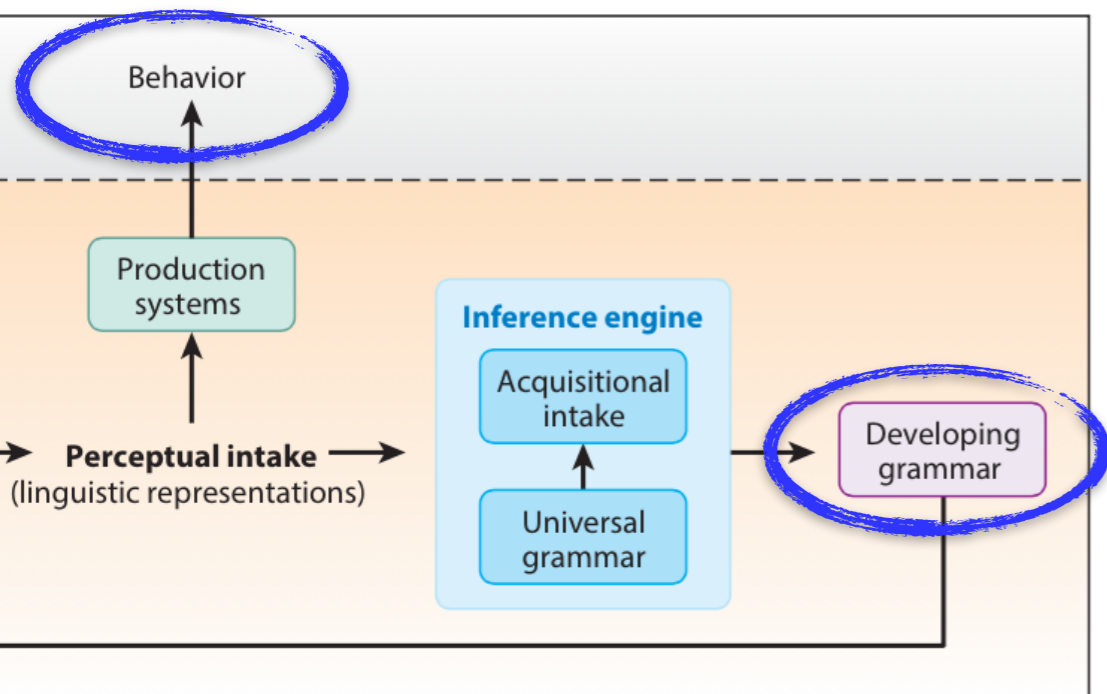
Ditransitives: Gropen et al. 1989, Snedeker & Huang in press, Campbell & Tomasello 2001, Huttenlocher et al. 2004, Conwell & Demuth 2007, Thothathiri & Snedeker 2008

"Jack ___ Lily the thing."

3yrs



+ = give, read, *say, ...



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<5yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



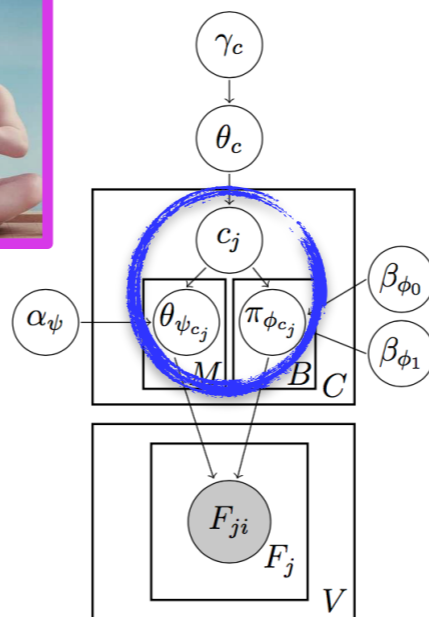
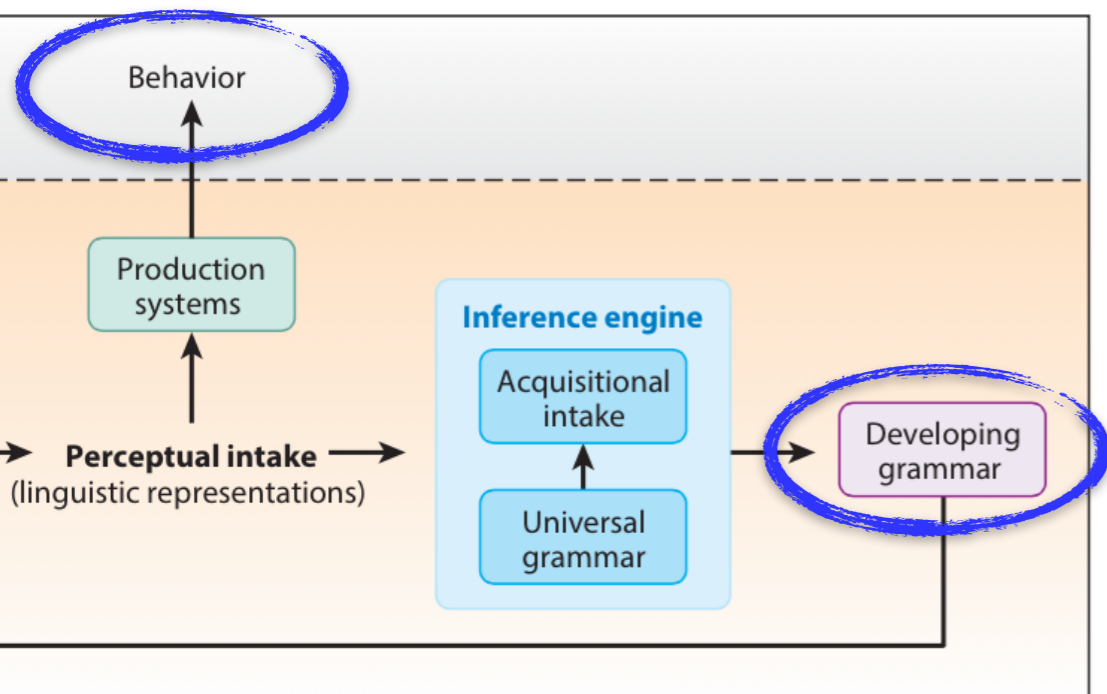
Ditransitives: Gropen et al. 1989, Snedeker & Huang in press, Campbell & Tomasello 2001, Huttenlocher et al. 2004, Conwell & Demuth 2007, Thothathiri & Snedeker 2008

"Jack ___ Lily the thing."

4yrs



+ = give, read, *say, teach, ...



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



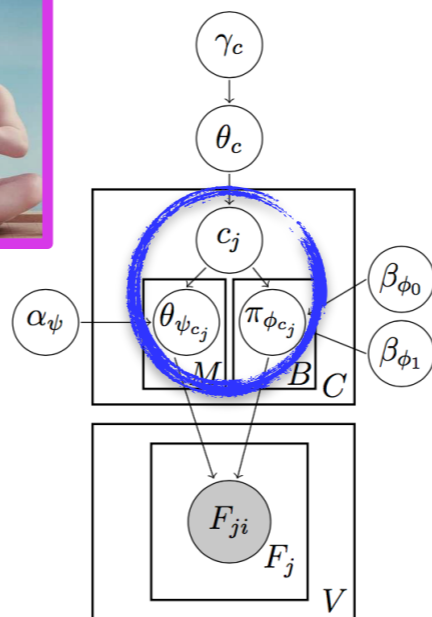
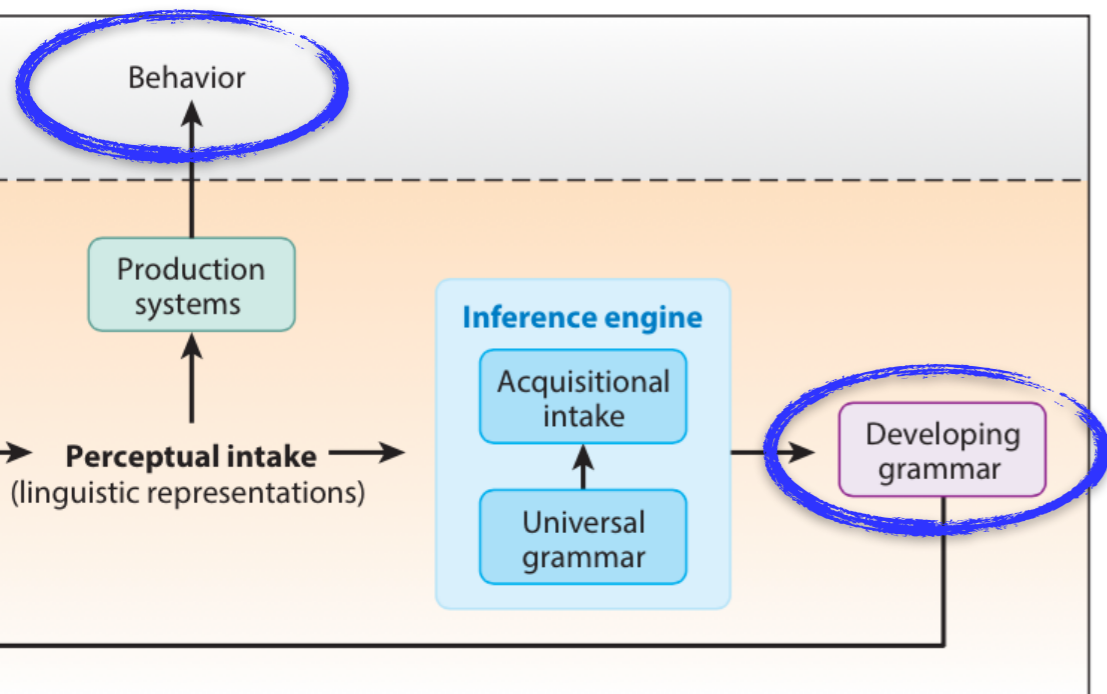
Ditransitives: Gropen et al. 1989, Snedeker & Huang in press, Campbell & Tomasello 2001, Huttenlocher et al. 2004, Conwell & Demuth 2007, Thothathiri & Snedeker 2008

"Jack ___ Lily the thing."

5yrs

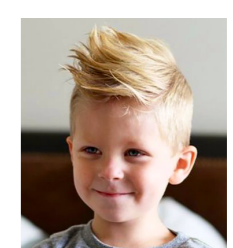


+ = ask, give, read, *say, teach, ...



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



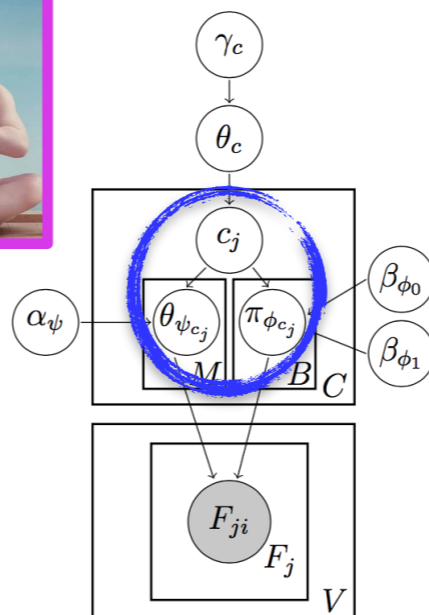
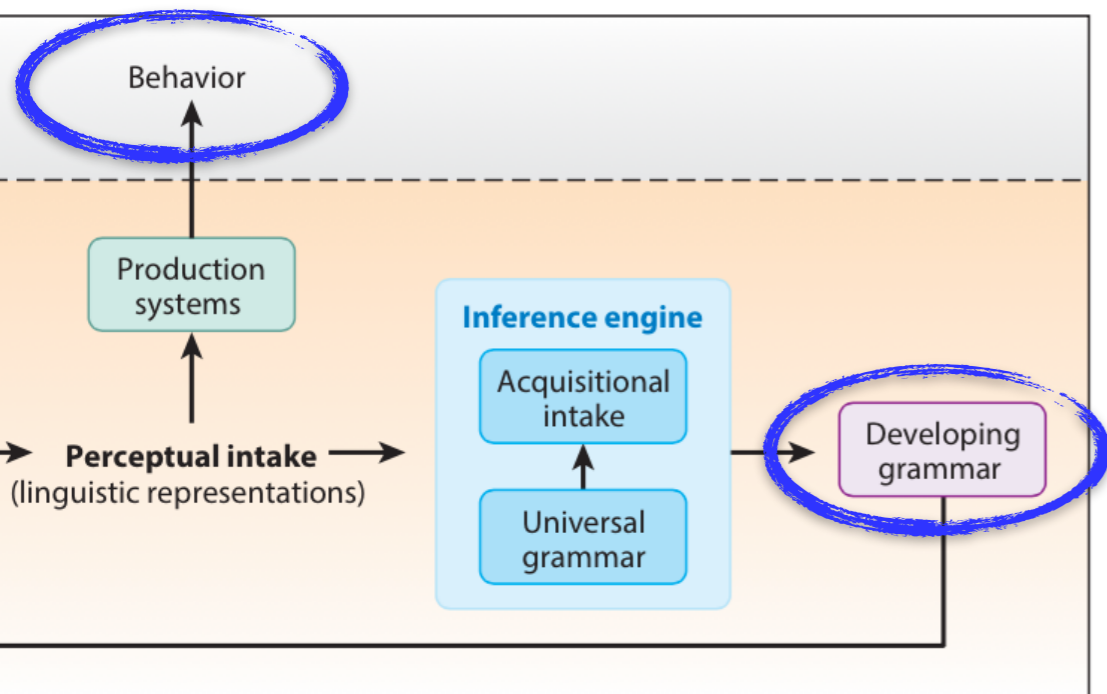
verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



Unaccusatives: Déprez & Pierce 1993, Snyder & Stromwold 1997, Gelman & Koenig 2001, Bungler & Lidz 2004, Bungler & Lidz 2008

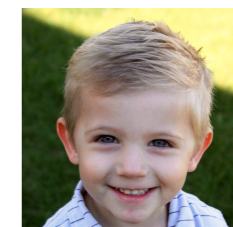
"It ____."
done-to



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<4yrs

<5yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



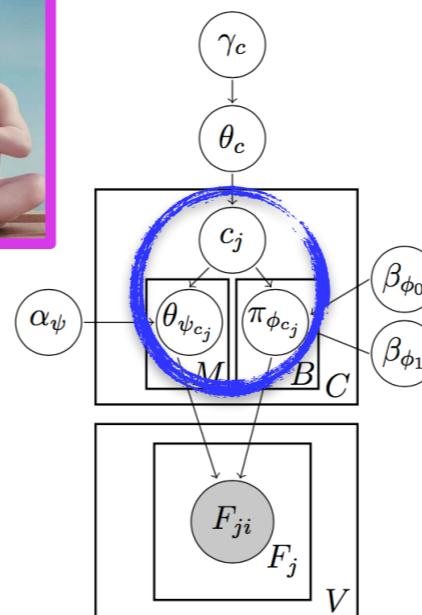
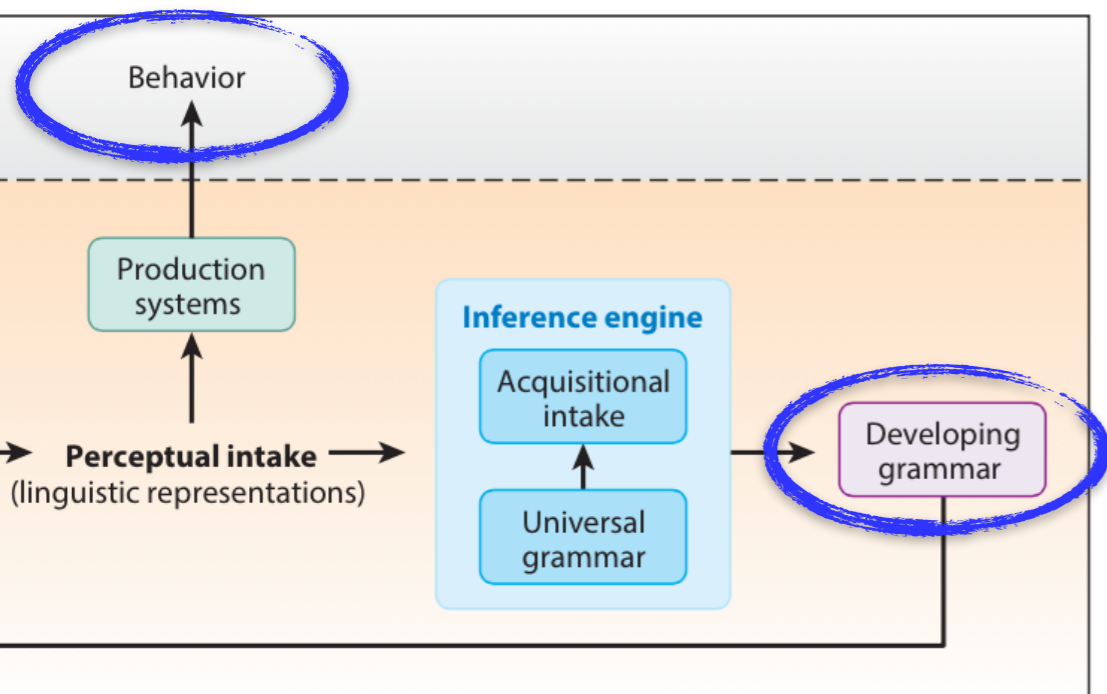
Unaccusatives: Déprez & Pierce 1993, Snyder & Stromwold 1997, Gelman & Koenig 2001, Bungler & Lidz 2004, Bungler & Lidz 2008

"It ____."
done-to

3yrs

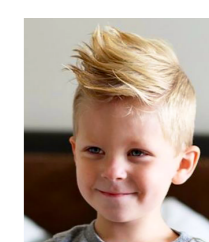


+ = break, fall, ...



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



verb classes

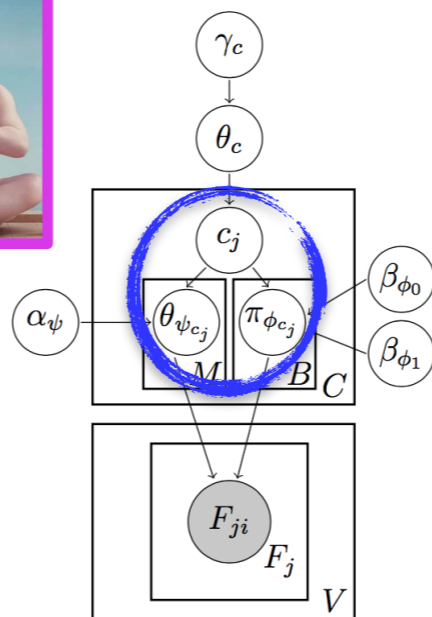
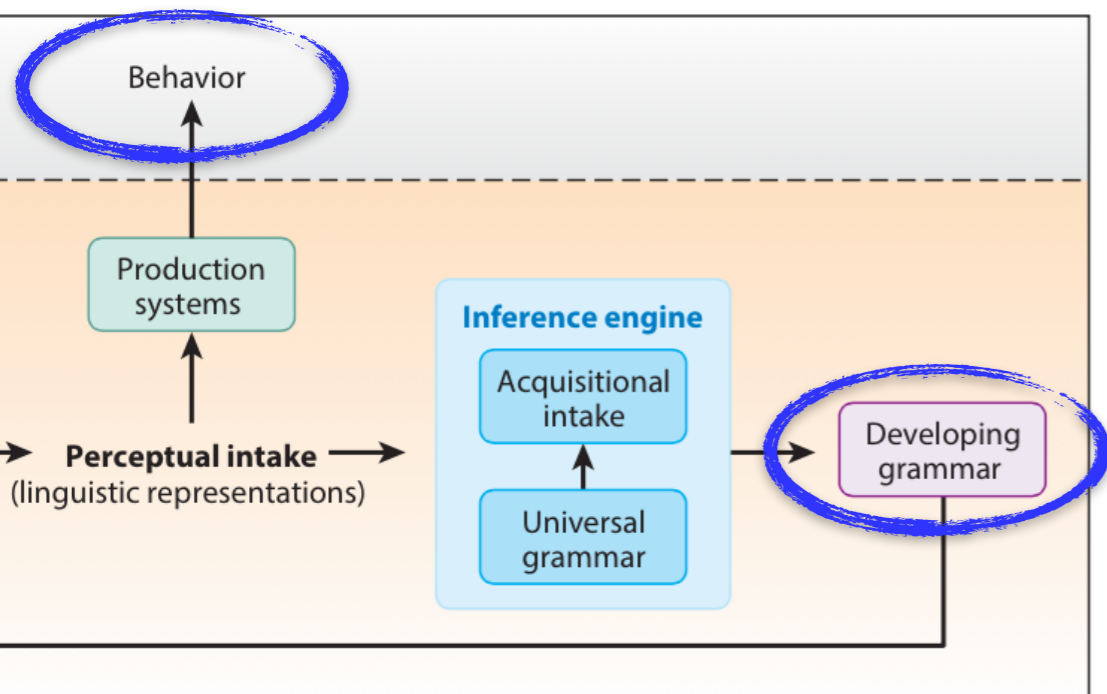
Survey of 32 experimental studies on children's production and comprehension of specific verbs



Control object & Raising object: Kirby 2009a, Kirby 2009b, Kirby 2010, Becker 2014

Control object

"I ___ him to leave."
done-recipient (main)
doer (embedded)



Goal: Model the developmental trajectory from 3 to 4 to 5 years old <3yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



Control object & Raising object: Kirby 2009a, Kirby 2009b, Kirby 2010, Becker 2014

Control object

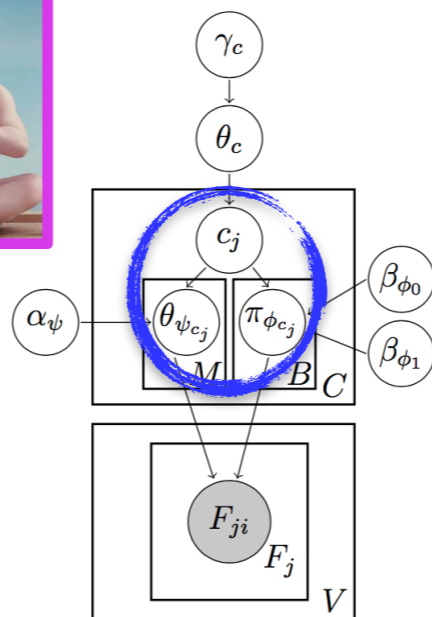
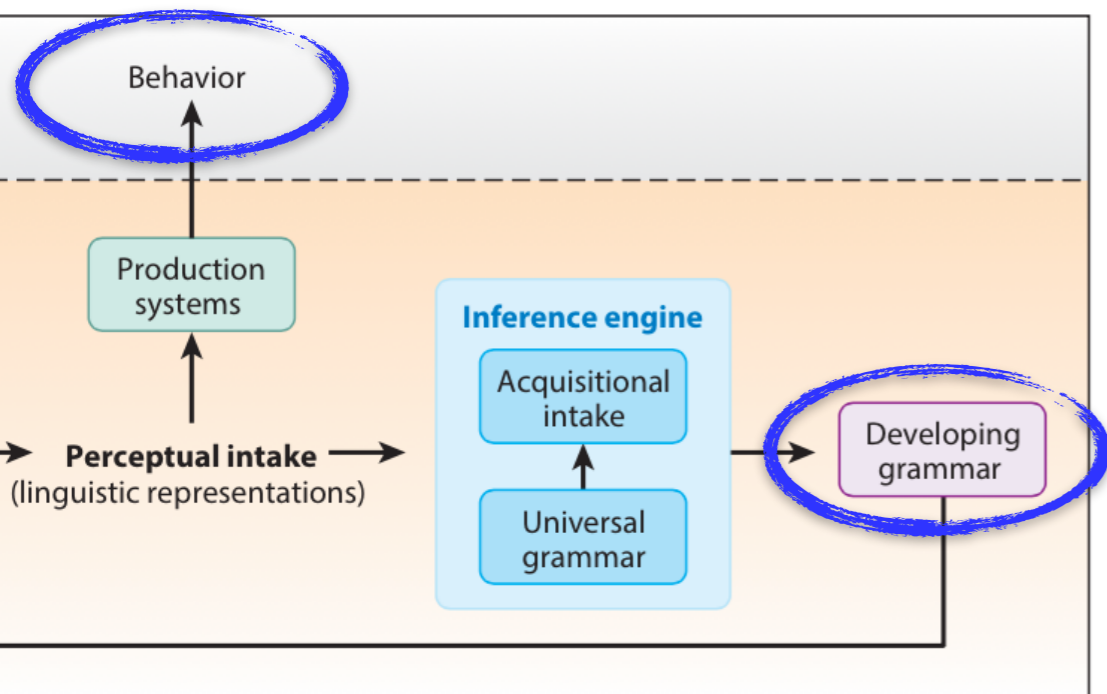
"I ___ him to leave."
done-recipient (main)
doer (embedded)

4yrs

5yrs



+= ask, tell



Goal: Model the developmental trajectory from 3 to 4 to 5 years old <3yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



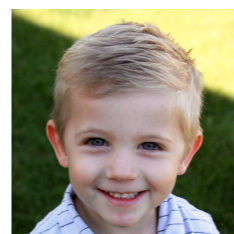
Control object & Raising object: Kirby 2009a, Kirby 2009b, Kirby 2010, Becker 2014

Raising object

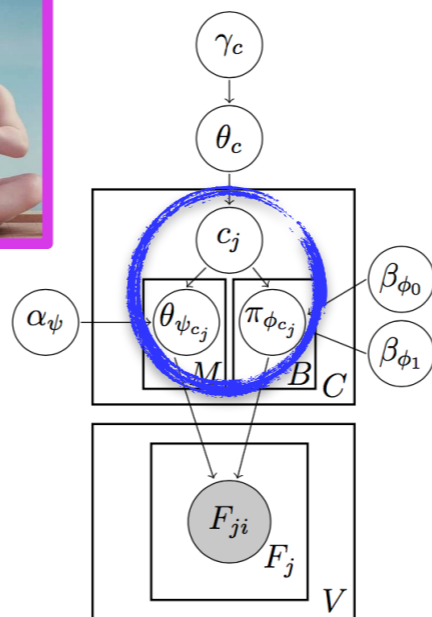
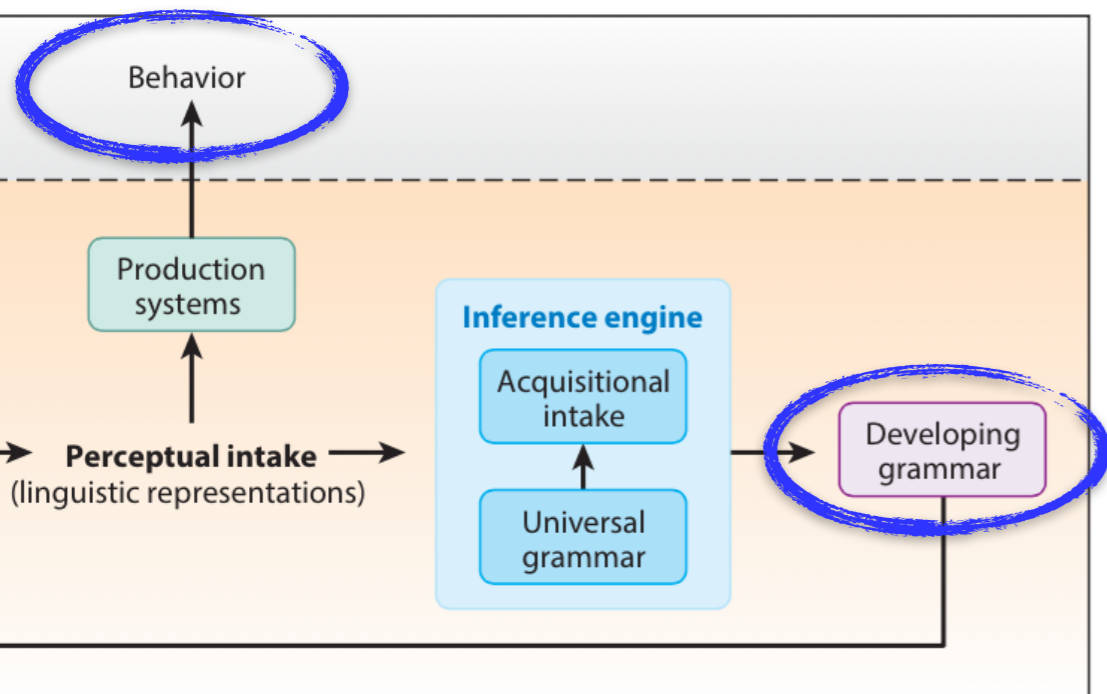
"I ___ him to leave."
doer (embedded)

4yrs

5yrs



+= need, want

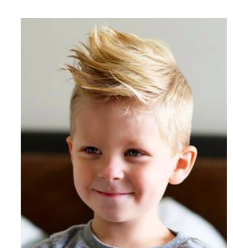


Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs

<5yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



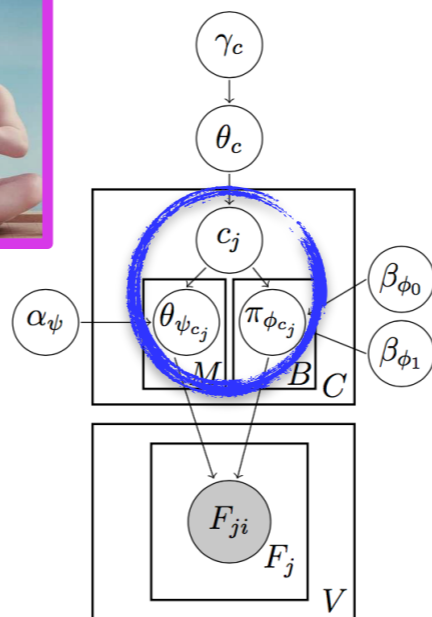
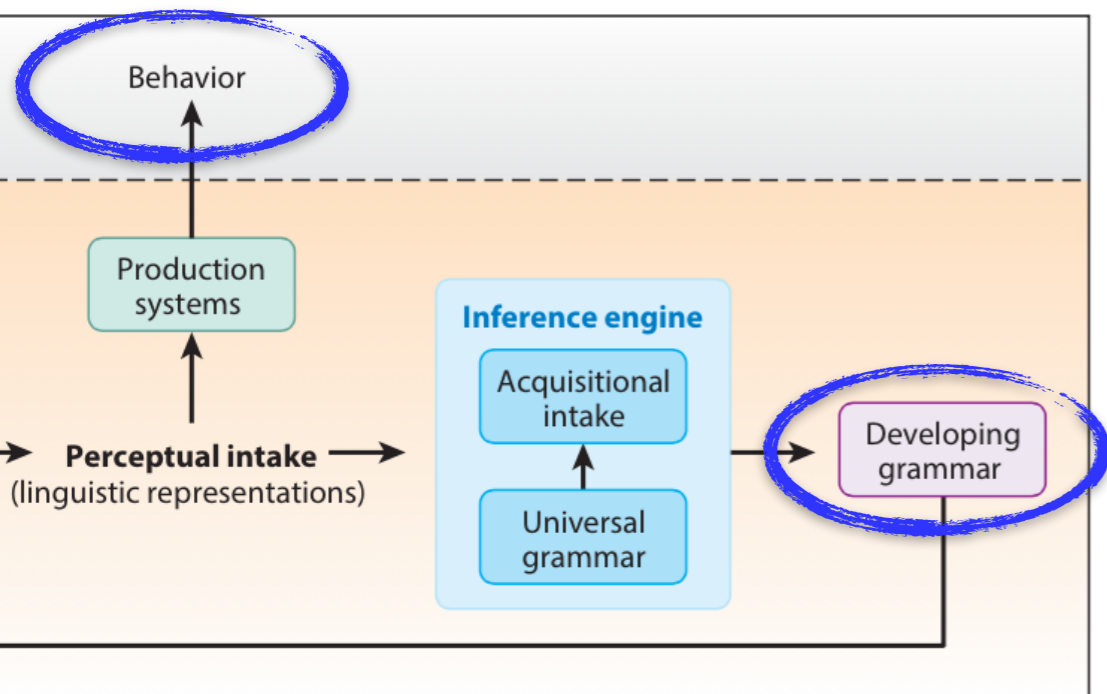
Control subject & Raising subject: Becker 2006, Becker 2007, Becker 2009, Becker 2014

Control subject

"I ___ to leave."

doer (main)

doer (embedded)



Goal: Model the developmental trajectory from 3 to 4 to 5 years old <3yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



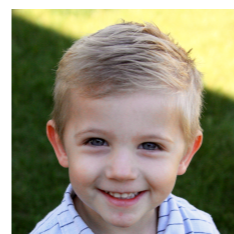
Control subject & Raising subject: Becker 2006, Becker 2007, Becker 2009, Becker 2014

Control subject

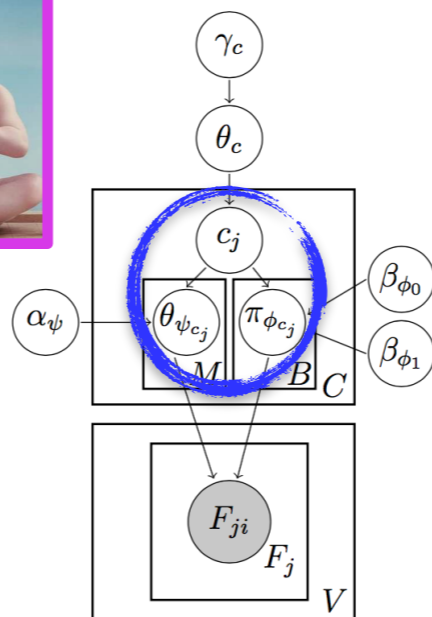
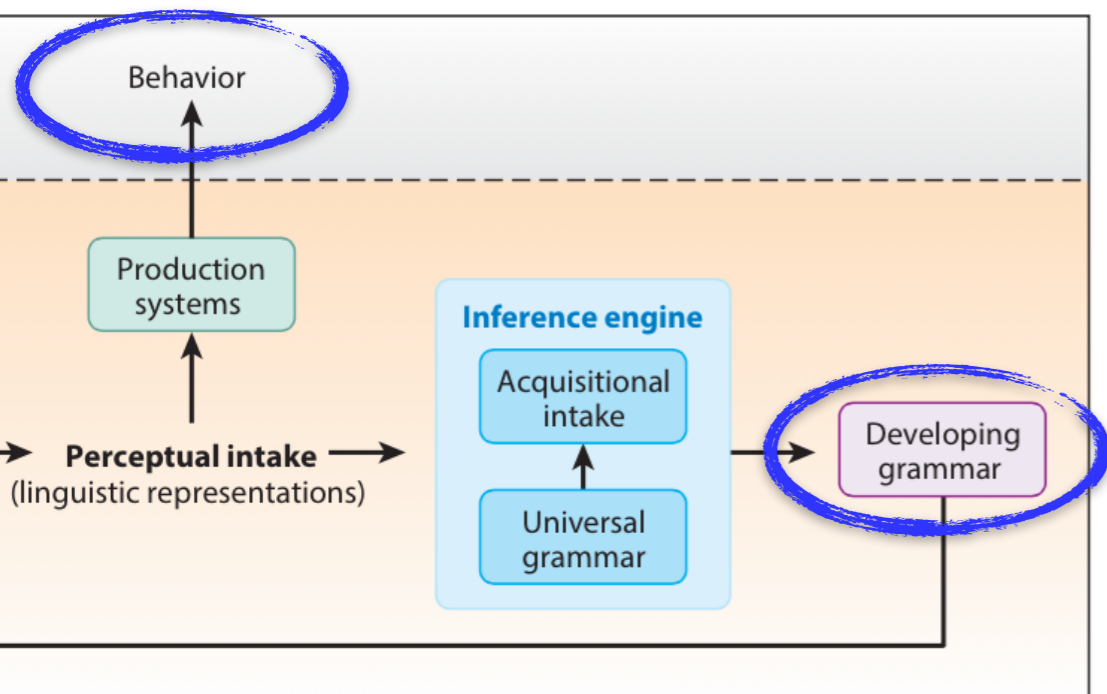
"I ___ to leave."
doer (main)
doer (embedded)

4yrs

5yrs



+= try, want



Goal: Model the developmental trajectory from 3 to 4 to 5 years old <3yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



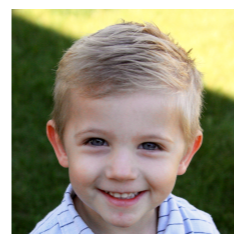
Control subject & Raising subject: Becker 2006, Becker 2007, Becker 2009, Becker 2014

Raising subject

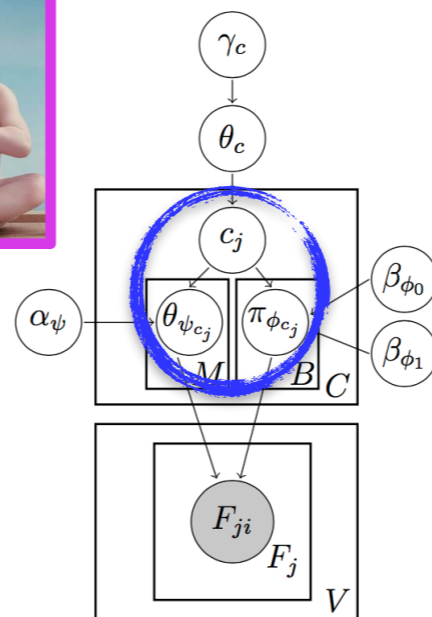
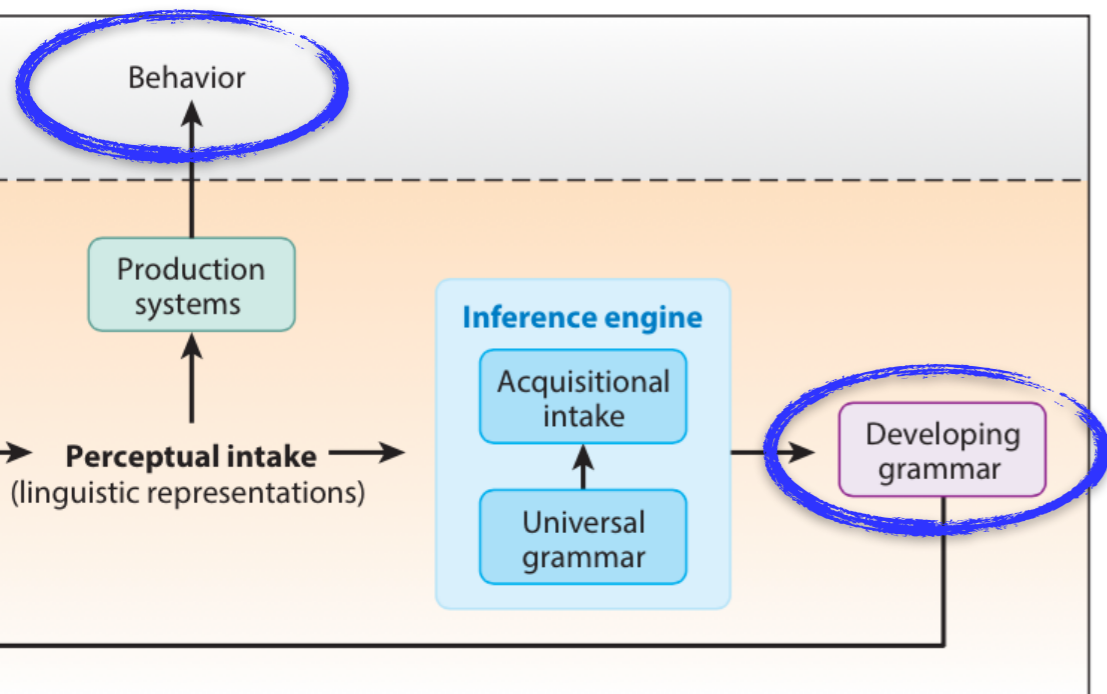
"I ___ to leave."
doer (embedded)

4yrs

5yrs



+= seem



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



verb classes

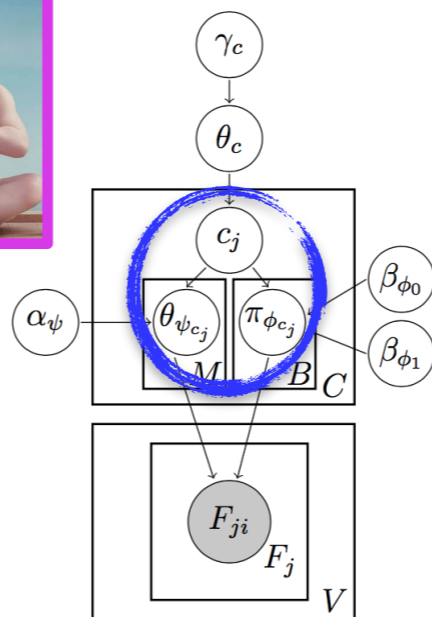
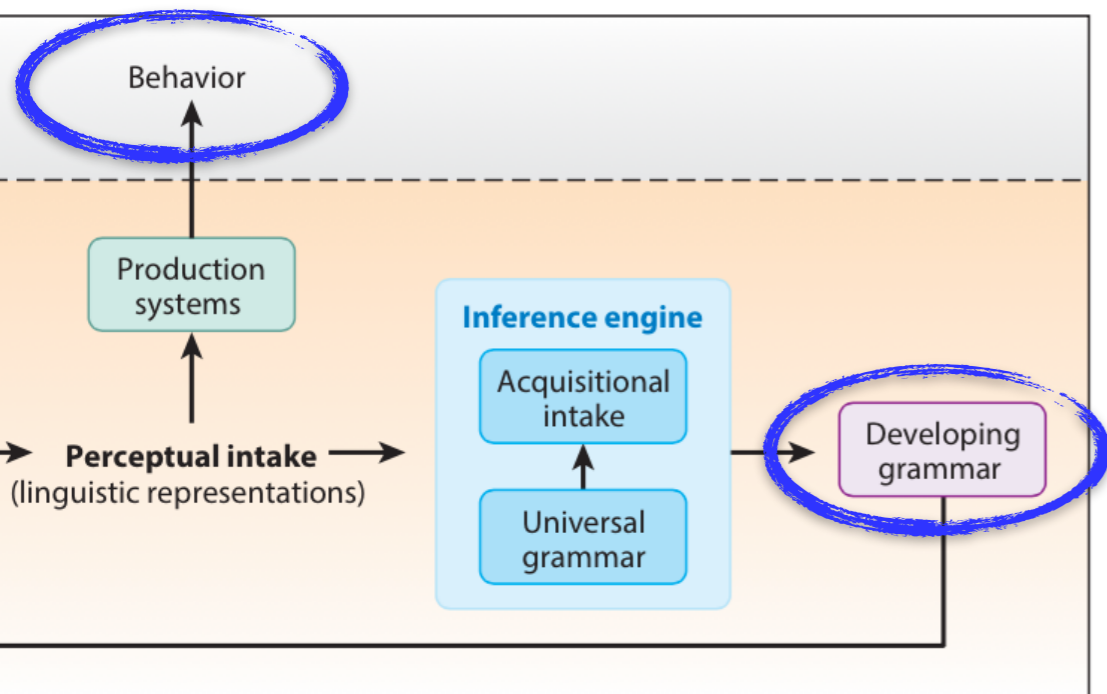
Survey of 32 experimental studies on children's production and comprehension of specific verbs



Subject-experienter and Object-experienter psych verbs: Hartshorne et al. 2015

Subject-experienter

"Jack ___ Lily."
Experienter



Goal: Model the developmental trajectory from 3 to 4 to 5 years old <3yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs

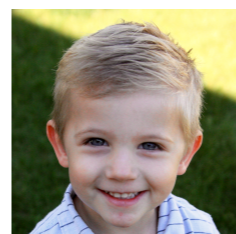


Subject-experienter and Object-experienter psych verbs: Hartshorne et al. 2015

Subject-experienter

"Jack ___ Lily."
Experienter

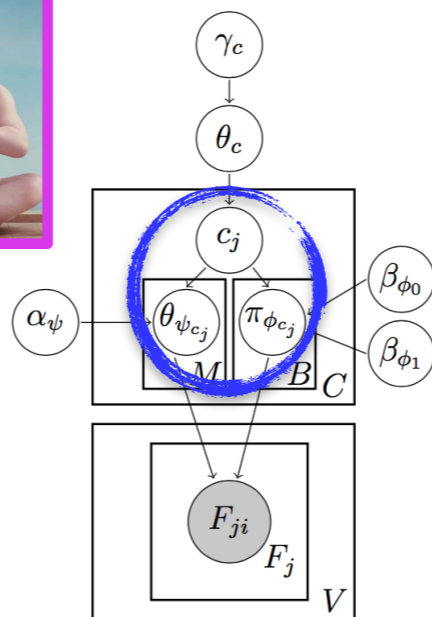
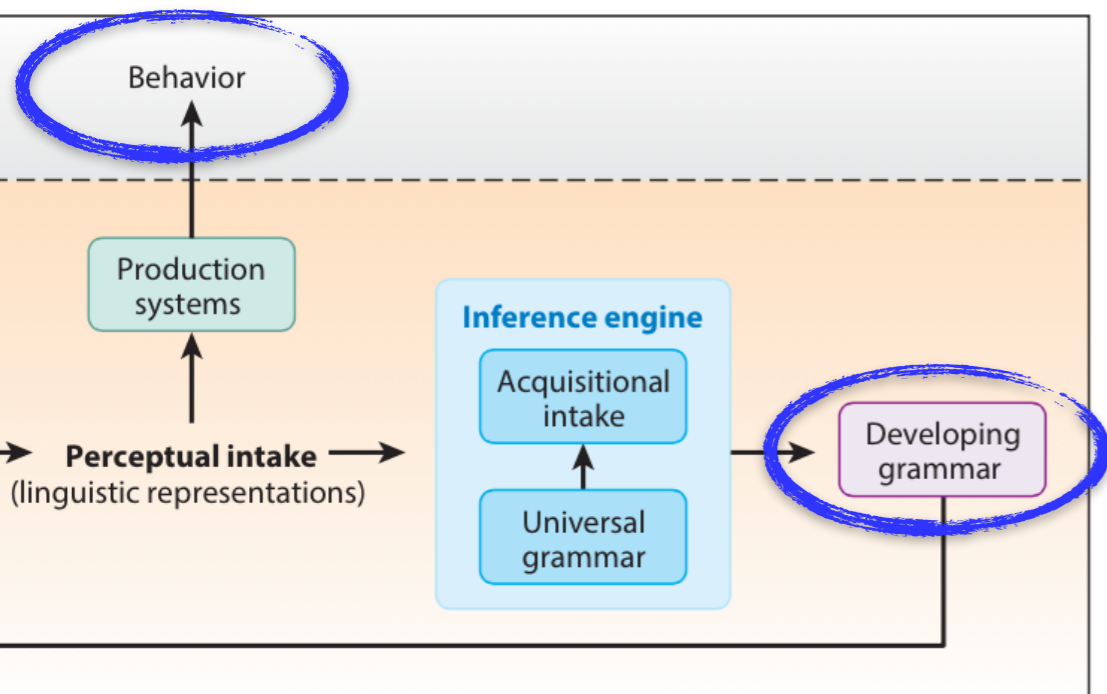
4yrs



5yrs



+ = like, love



Goal: Model the developmental trajectory from 3 to 4 to 5 years old <math><3\text{yrs}</math>



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



Subject-experiencer and Object-experiencer psych verbs: Hartshorne et al. 2015

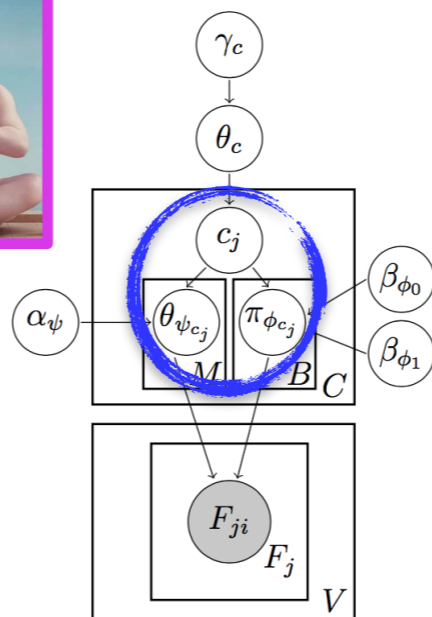
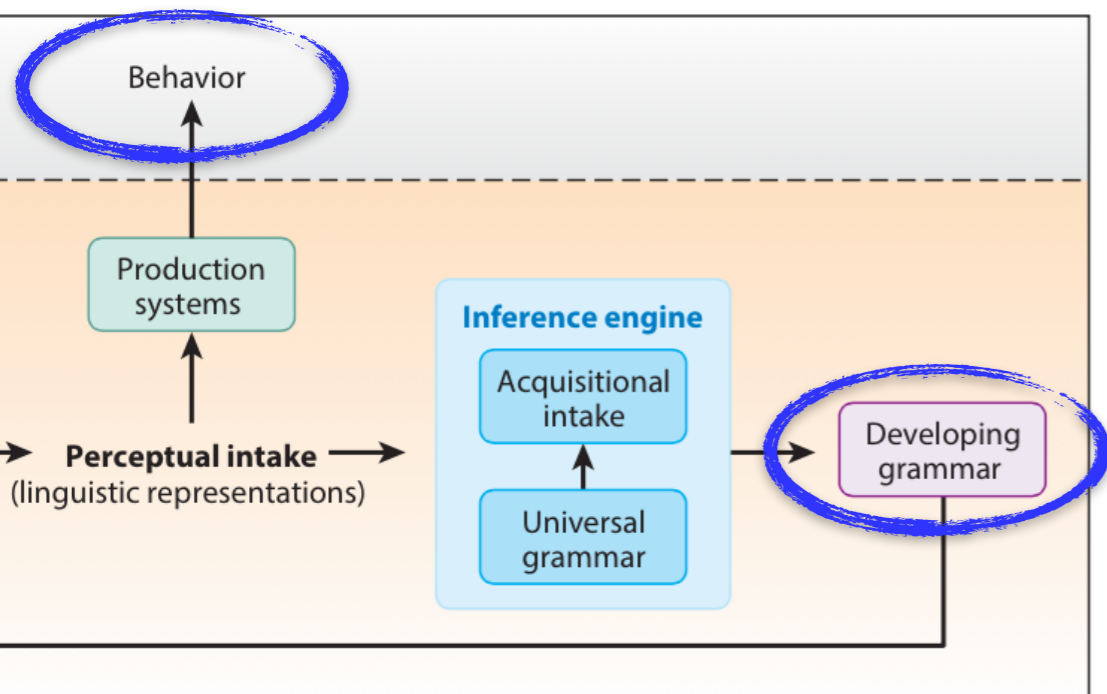
Object-experiencer
 "Jack _____ Lily."
Experiencer

4yrs

5yrs



+ = frighten, scare, surprise



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



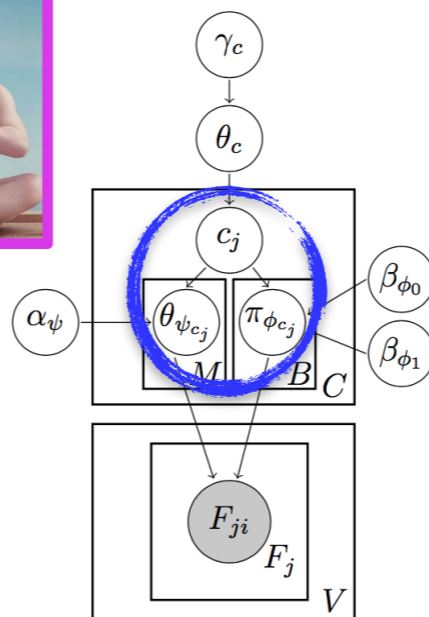
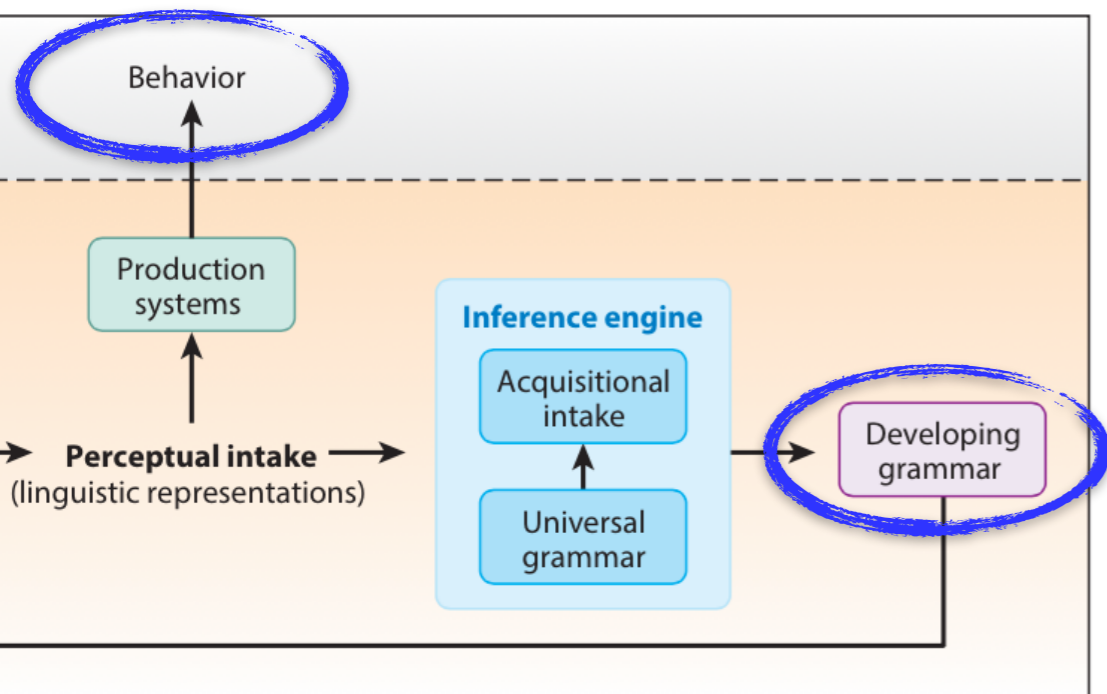
verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



Complement-taking verbs [non-finite *to*, *that*, *whether/if*]: Bloom et al. 1984, Bloom et al. 1989, Diessel & Tomasello 2001, Papafragou et al. 2007, Kidd et al, 2006, Kidd et al. 2010

Non-finite *to*
"Jack ___ to go."



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<4yrs

<5yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



Complement-taking verbs [non-finite *to*, *that*, *whether/if*]: Bloom et al. 1984, Bloom et al. 1989, Diessel & Tomasello 2001, Papafragou et al. 2007, Kidd et al, 2006, Kidd et al. 2010

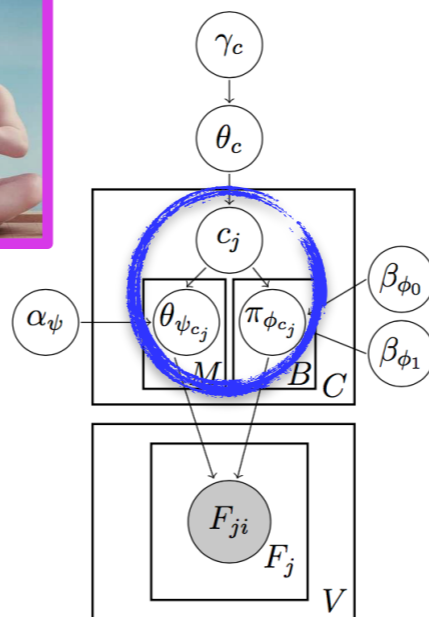
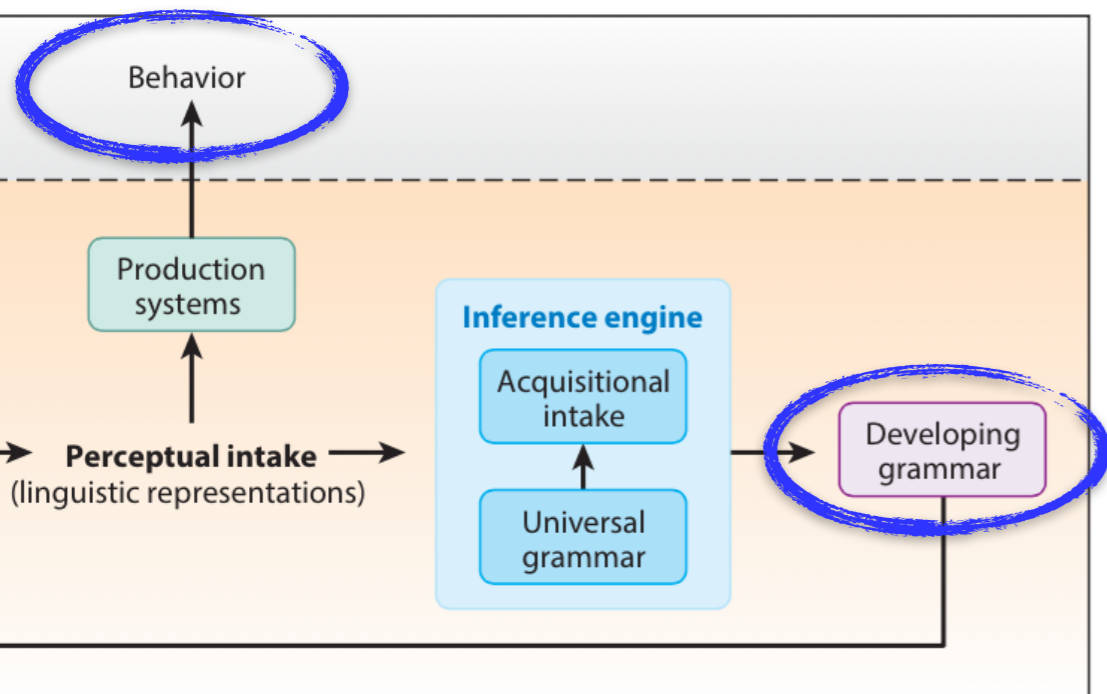
Non-finite *to*

"Jack ___ to go."

3yrs



+ = get, start, suppose, ...



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs

<5yrs



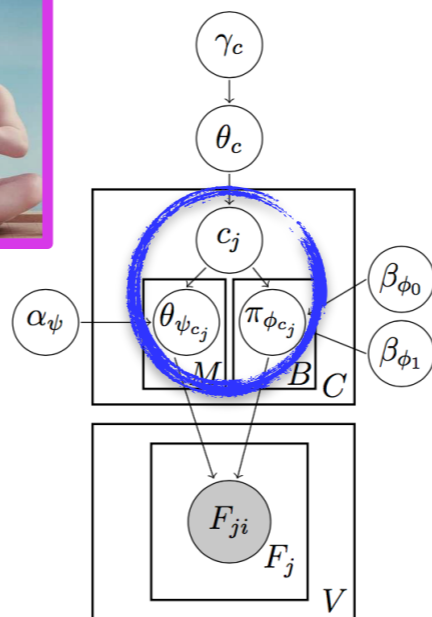
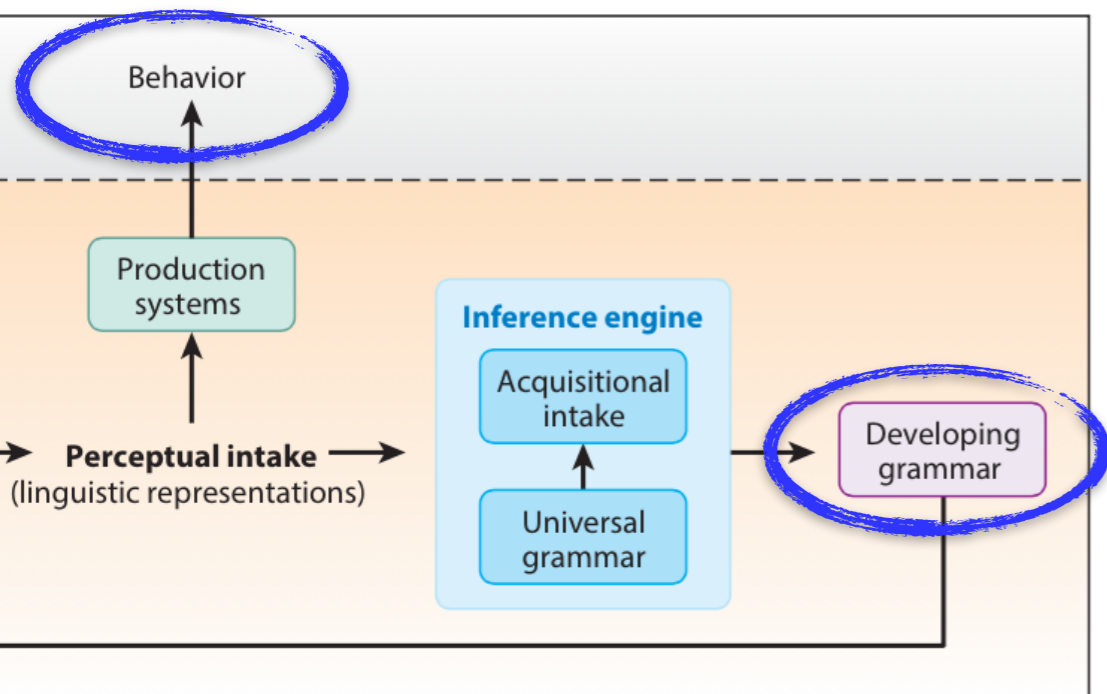
verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



Complement-taking verbs [non-finite *to*, *that*, *whether/if*]: Bloom et al. 1984, Bloom et al. 1989, Diessel & Tomasello 2001, Papafragou et al. 2007, Kidd et al, 2006, Kidd et al. 2010

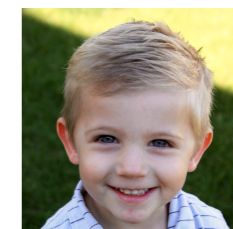
that
"Jack ___ that he can go."



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<4yrs

<5yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



Complement-taking verbs [non-finite *to*, *that*, *whether/if*]: Bloom et al. 1984, Bloom et al. 1989, Diessel & Tomasello 2001, Papafragou et al. 2007, Kidd et al, 2006, Kidd et al. 2010

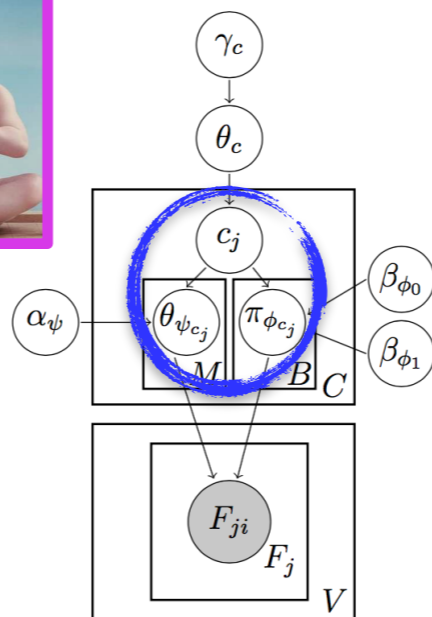
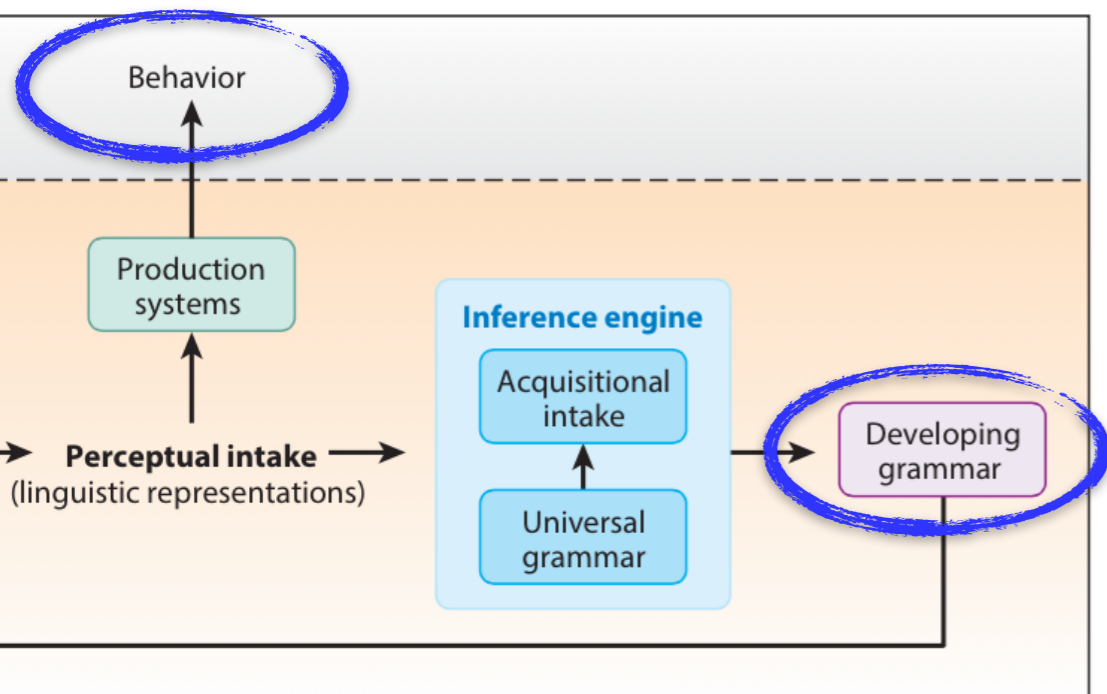
that

"Jack ___ that he can go."

3yrs



+= hope, know, say, ...



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



Complement-taking verbs [non-finite *to*, *that*, *whether/if*]: Bloom et al. 1984, Bloom et al. 1989, Diessel & Tomasello 2001, Papafragou et al. 2007, Kidd et al, 2006, Kidd et al. 2010

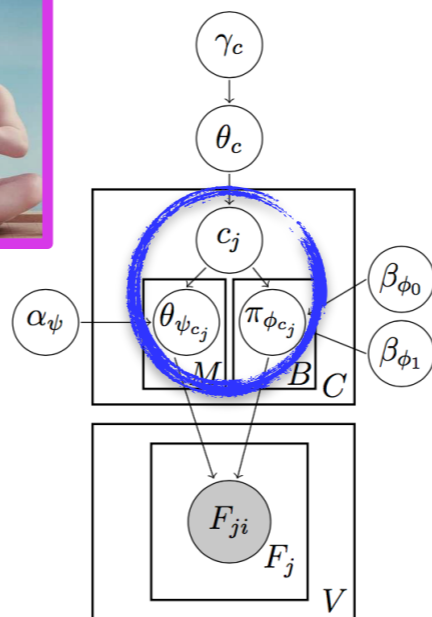
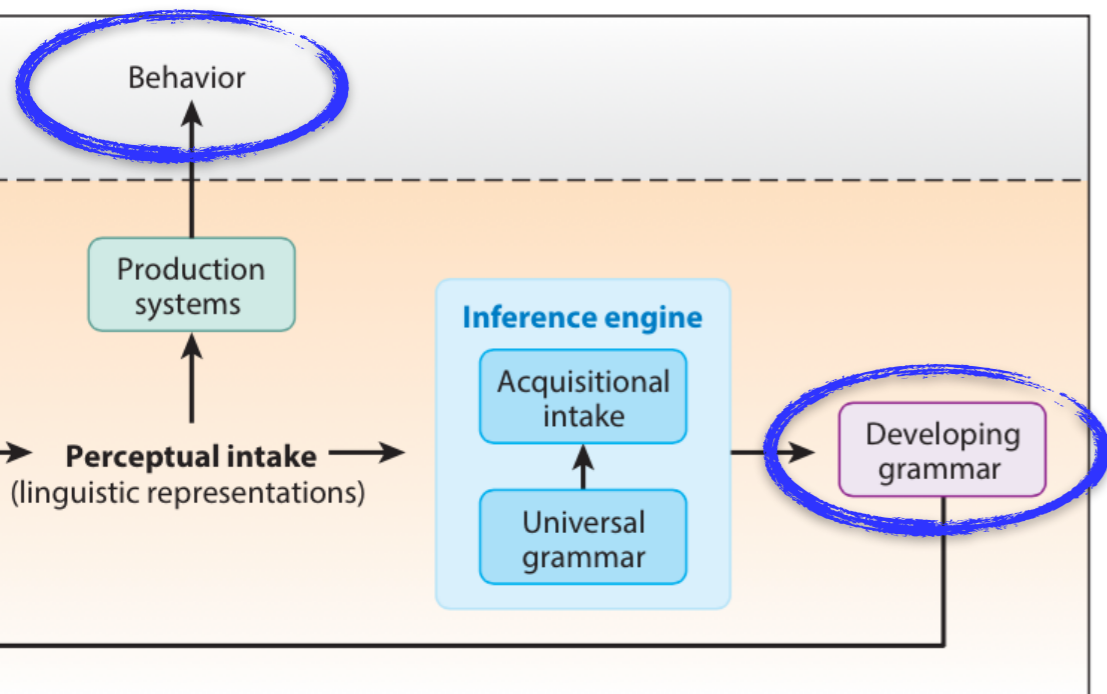
that

"Jack ___ that he can go."

5yrs



+ = guess, hope, know, pretend, say, ...



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



verb classes

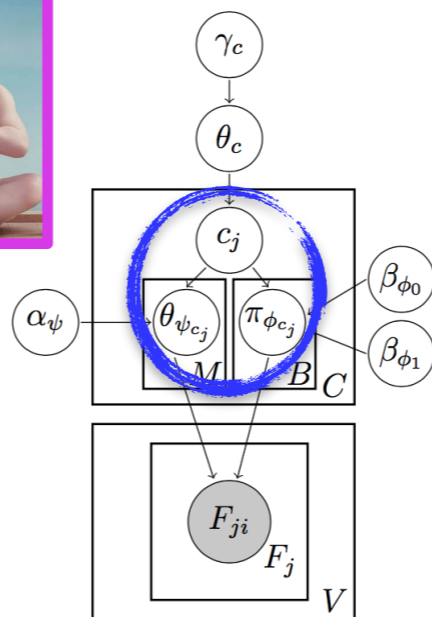
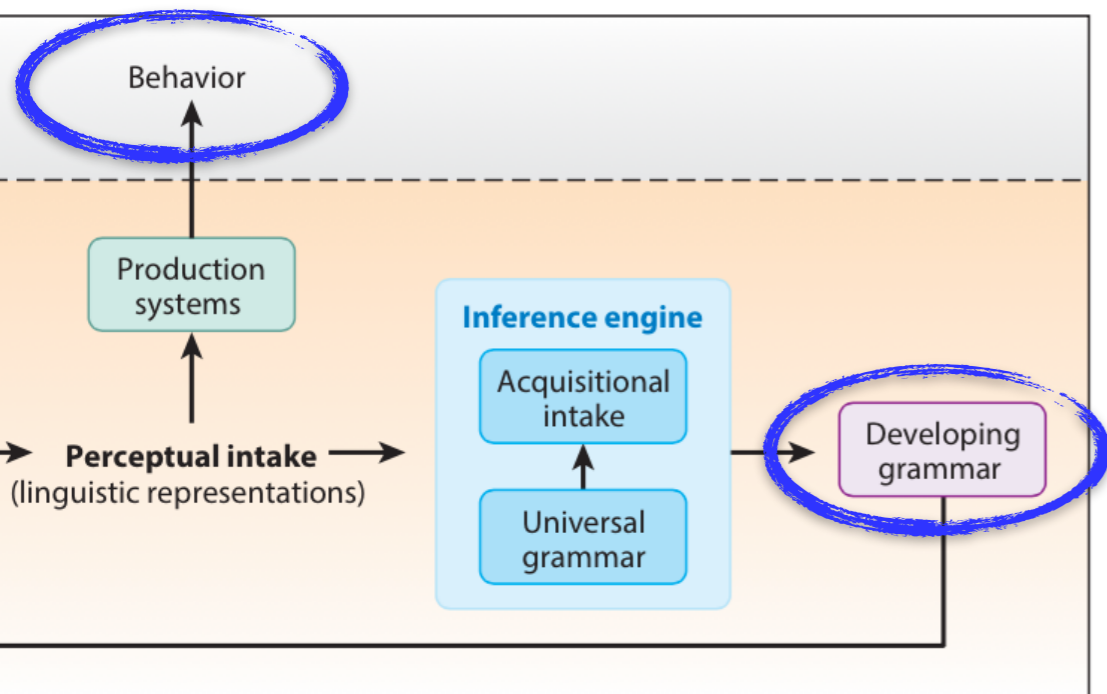
Survey of 32 experimental studies on children's production and comprehension of specific verbs



Complement-taking verbs [non-finite *to*, *that*, *whether/if*]: Bloom et al. 1984, Bloom et al. 1989, Diessel & Tomasello 2001, Papafragou et al. 2007, Kidd et al, 2006, Kidd et al. 2010

whether/if

"Jack ___ *whether/if* he can go."



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs



verb classes

Survey of 32 experimental studies on children's production and comprehension of specific verbs



Complement-taking verbs [non-finite *to*, *that*, *whether/if*]: Bloom et al. 1984, Bloom et al. 1989, Diessel & Tomasello 2001, Papafragou et al. 2007, Kidd et al, 2006, Kidd et al. 2010

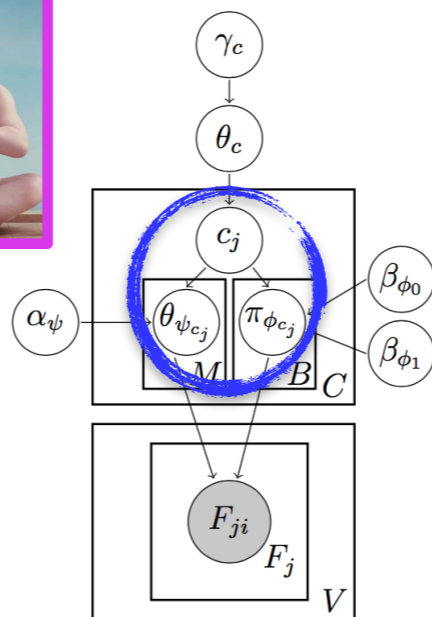
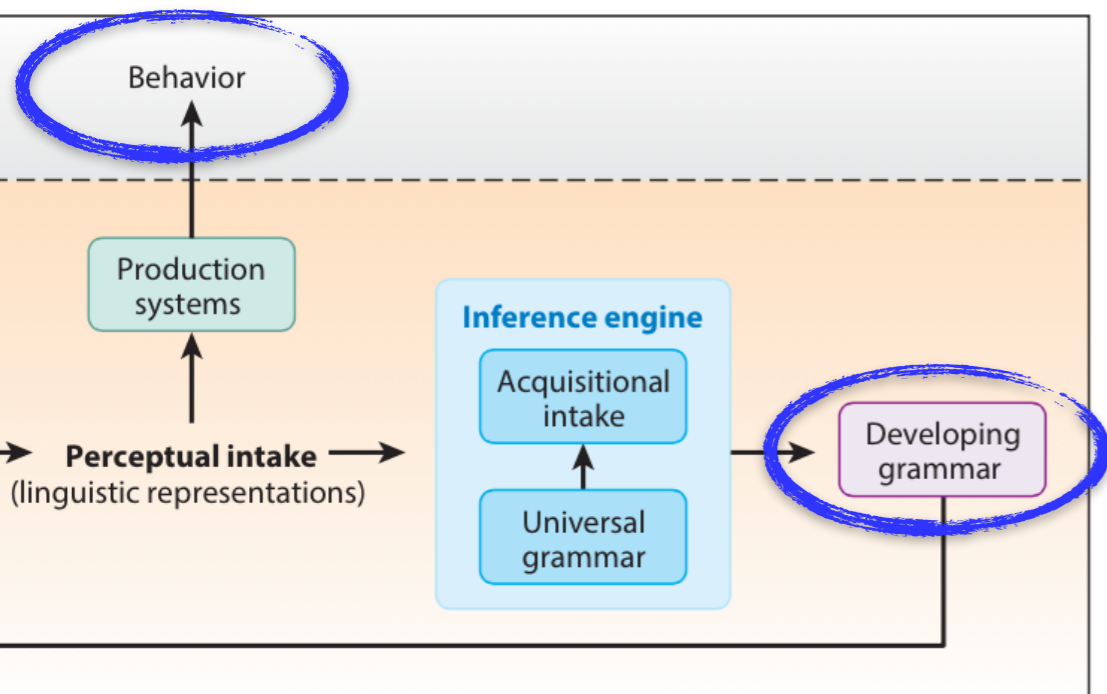
whether/if

"Jack ___ *whether/if* he can go."

5yrs



+ = ask, care, know, see, ...



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

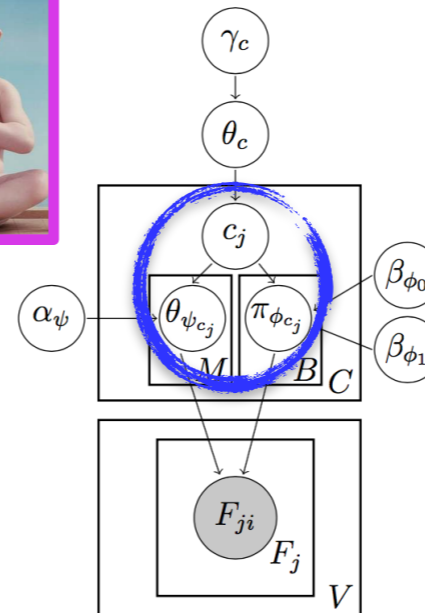
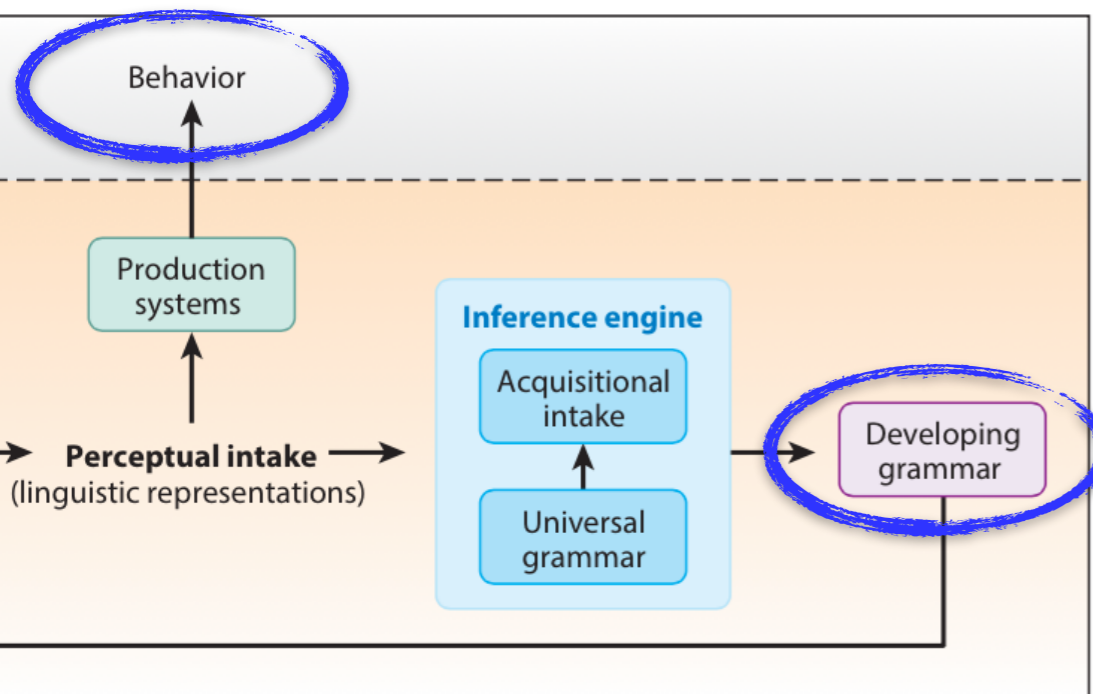
<3yrs

<4yrs

<5yrs



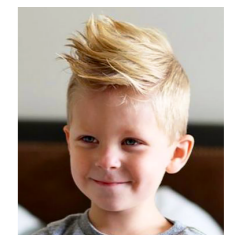
These verb behaviors yield a number of verb classes at each age



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<4yrs

<5yrs



These verb behaviors yield a number of verb classes at each age

Example classes

<3yrs



[+passive]: carry, chase, crash, drop, eat, hit, hold, hurt, jump, kick, kiss, knock, lick, punch, push, scratch, shake, turn, wash, watch

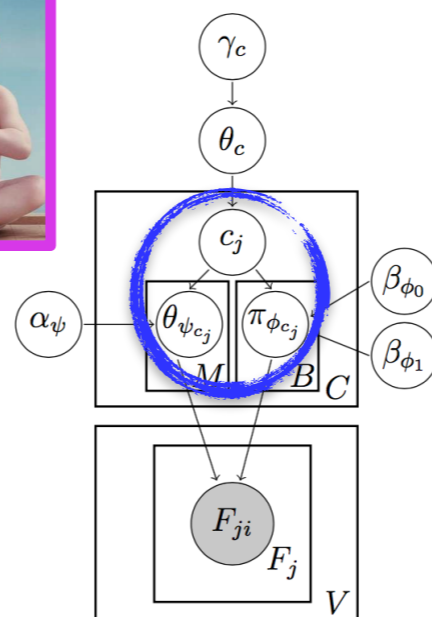
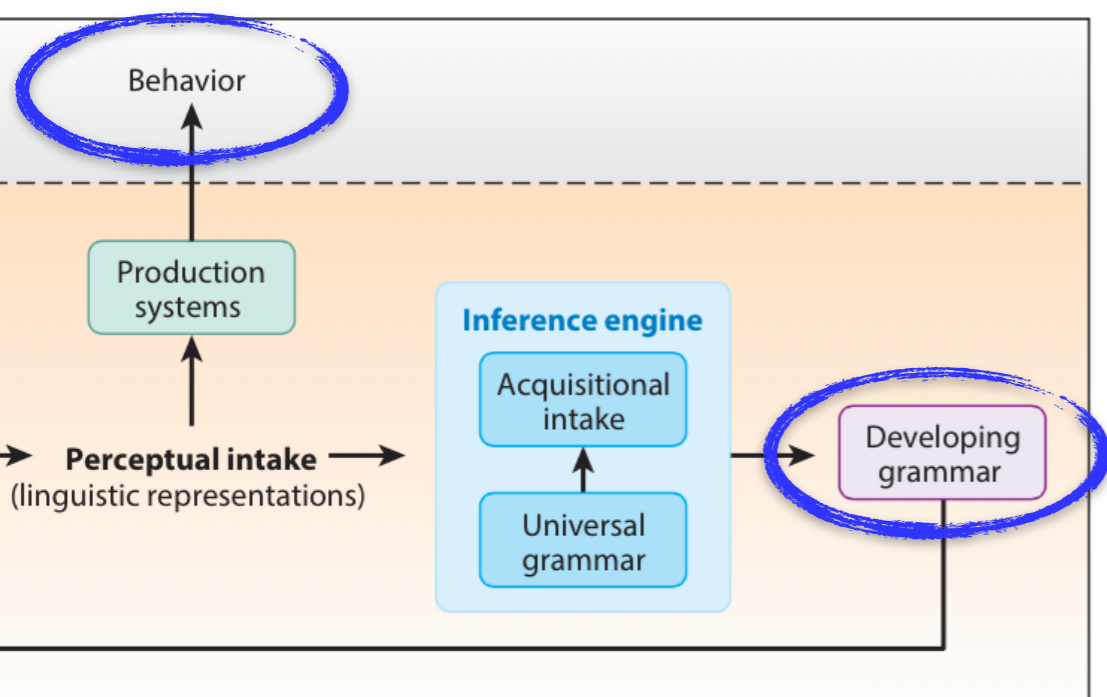
[-passive]: believe, remember

[+non-finite to]: ask, have, need, start, suppose, teach, try, use, want

[+that-comp]: bet, hope, think, wish

[+passive, +non-finite to]: like

[+passive, +that-comp]: see



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<5yrs



These verb behaviors yield a number of verb classes at each age

<4yrs



Example classes

[+passive]: bite, bump, carry, chase, crash, drop, find, hit, hold, hurt, jump, kick, kill, kiss, knock, lick, pull, punch, push, ride, scratch, shake, shoot, turn, wash, watch

[-passive]: believe, remember

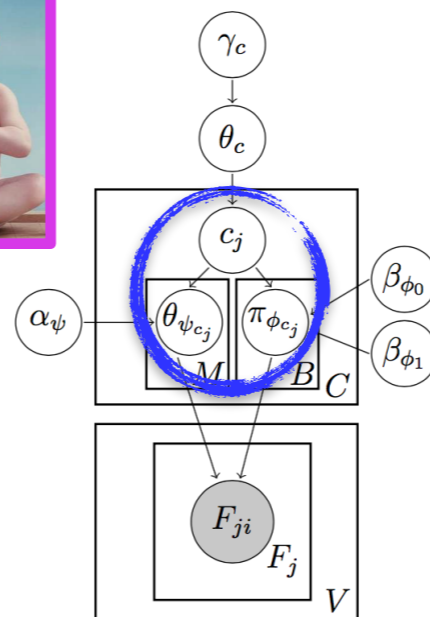
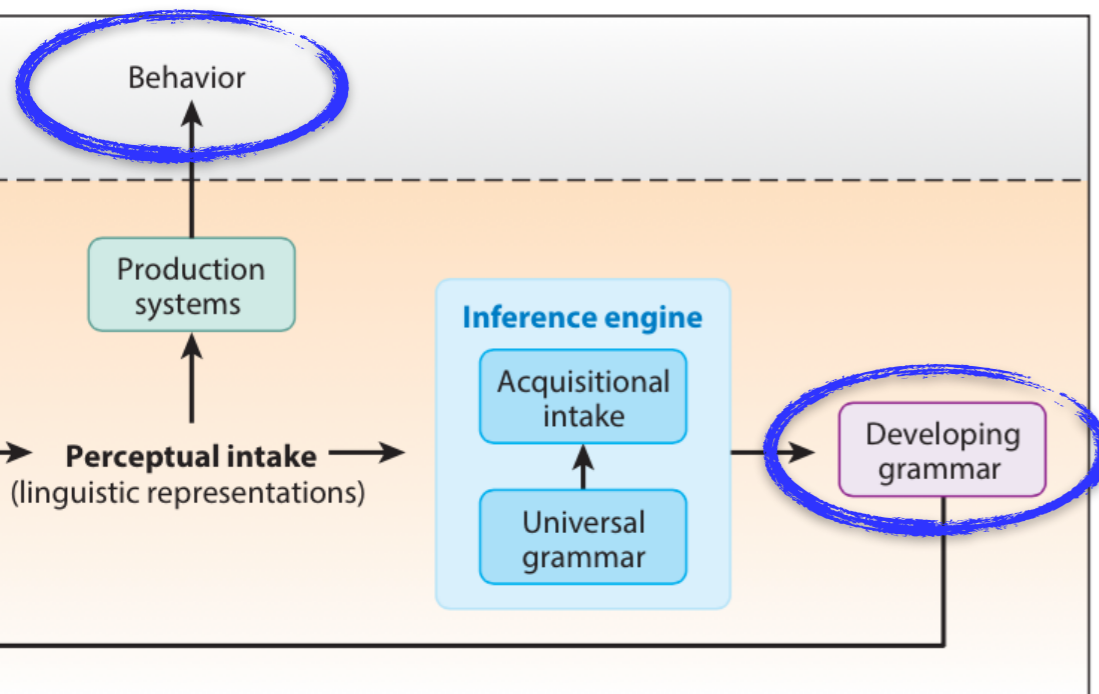
[+that-comp]: bet, hope, think, wish

[+non-finite to, +raising-obj]: need

[+non-finite to, +raising-obj, +control-subj]: want

[+passive, +non-finite to, +psych-subj]: like

[+passive, +that-comp]: see



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs



These verb behaviors yield a number of verb classes at each age

<5yrs



Example classes

[+passive]: bite, bump, carry, chase, crash, drop, find, hit, hold, hurt, jump, kick, kill, kiss, knock, lick pull, push, ride, scratch, shake, shoot, turn, wash, watch

[-passive]: believe, remember

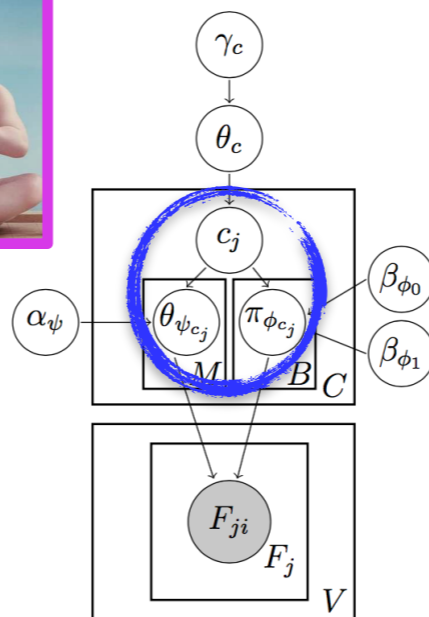
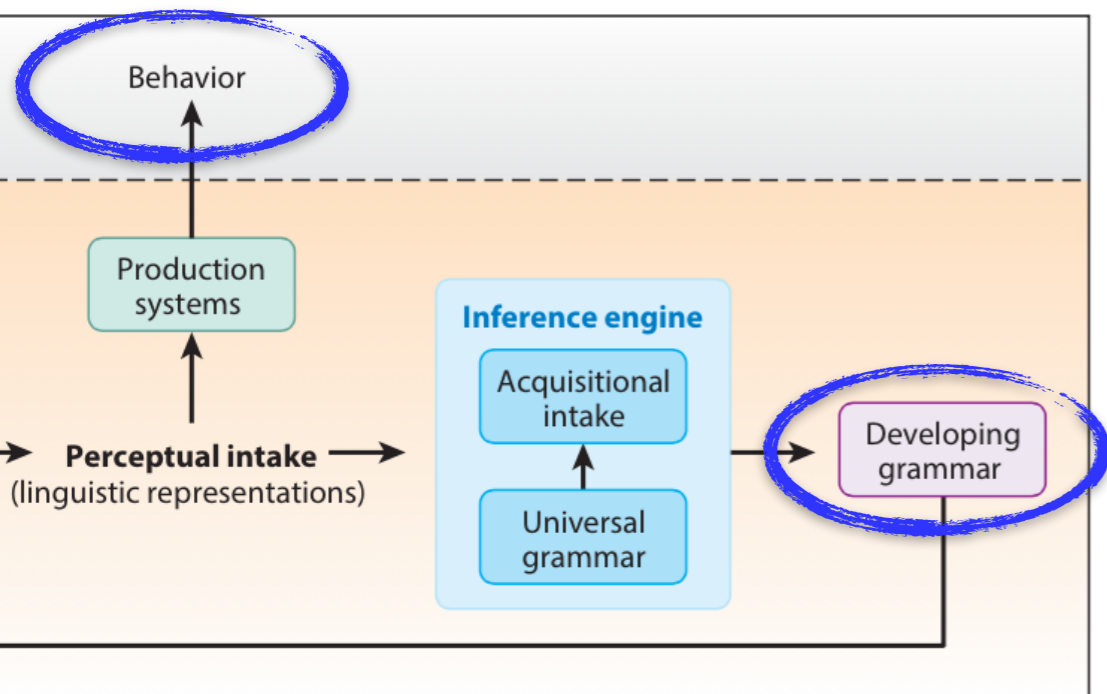
[+that-comp]: bet, dream, guess, hope, lie, pretend, think, wish

[+non-finite to, +raising-obj]: need

[+non-finite to, +raising-obj, +control-subj]: want

[+passive, +non-finite to, +psych-subj]: like

[+passive, +that-comp, +whether/if-comp]: see



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

These verb behaviors yield a number of verb classes at each age

<3yrs



15 classes of 60 verbs total

<4yrs

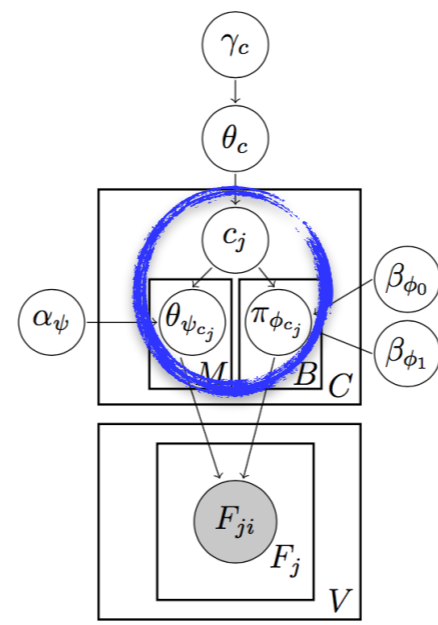
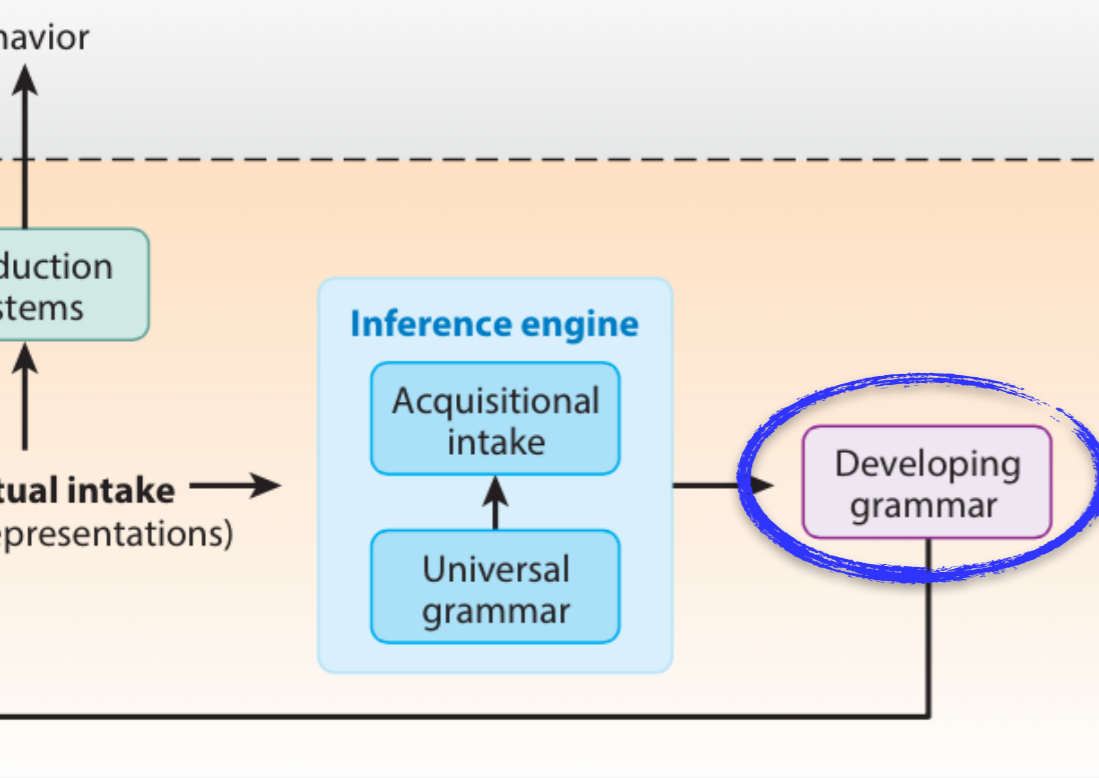


23 classes of 76 verbs total

<5yrs



24 classes of 82 verbs total

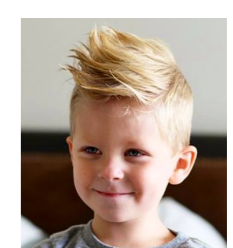


Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs

<5yrs



15 classes

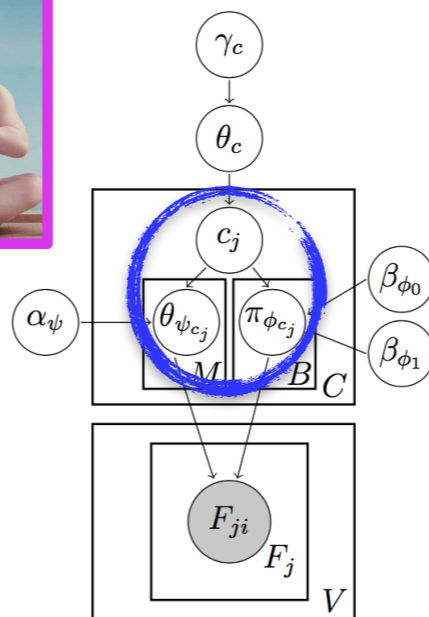
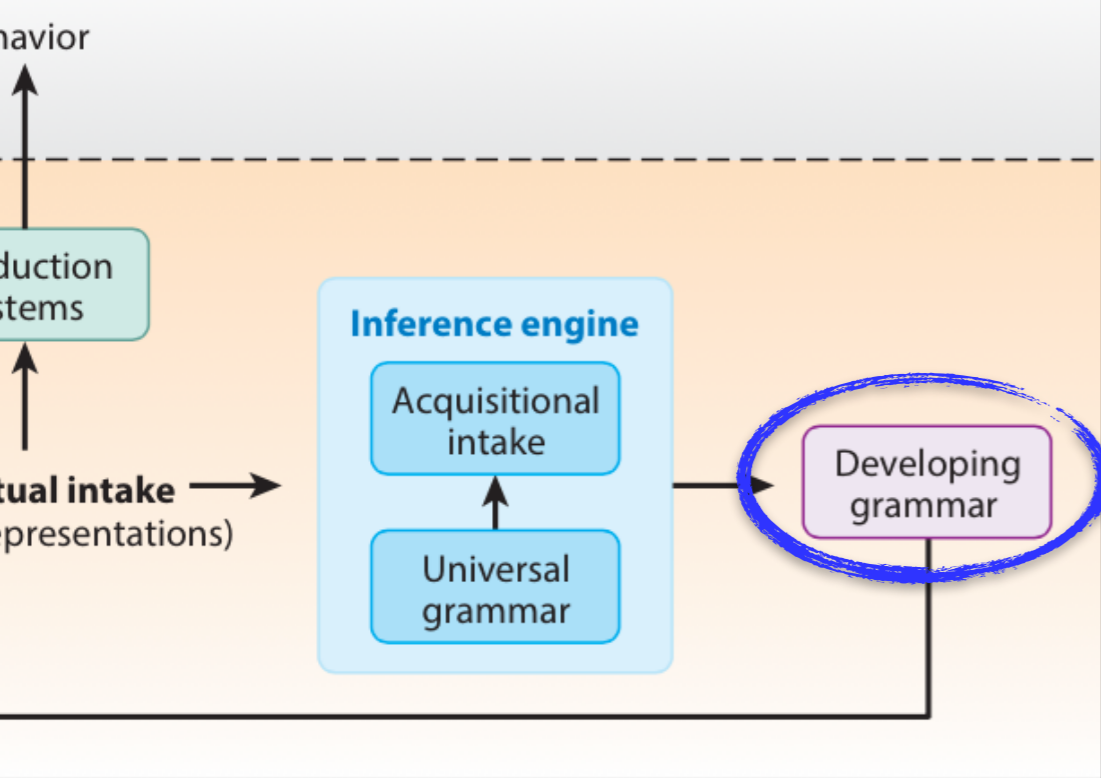
23 classes

24 classes

Evaluation:

How well did the modeled learner do at finding these verb classes?





Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs

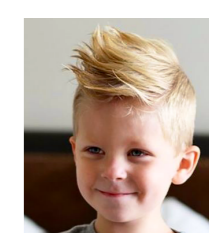
<5yrs



15 classes



23 classes



24 classes

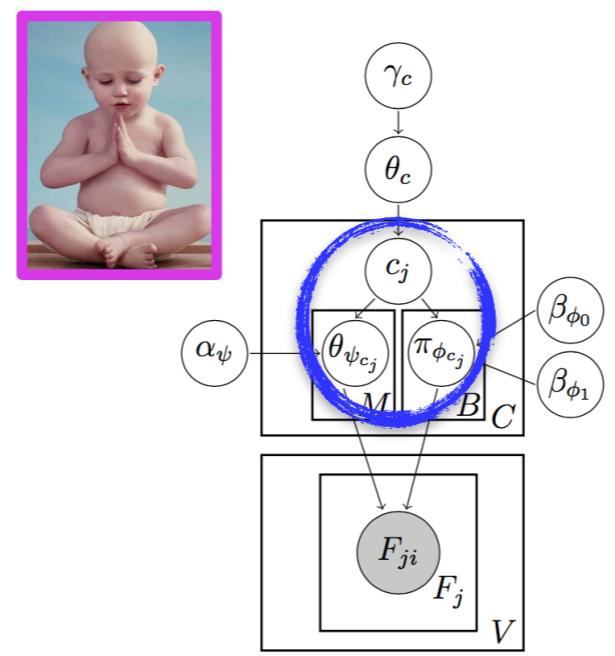
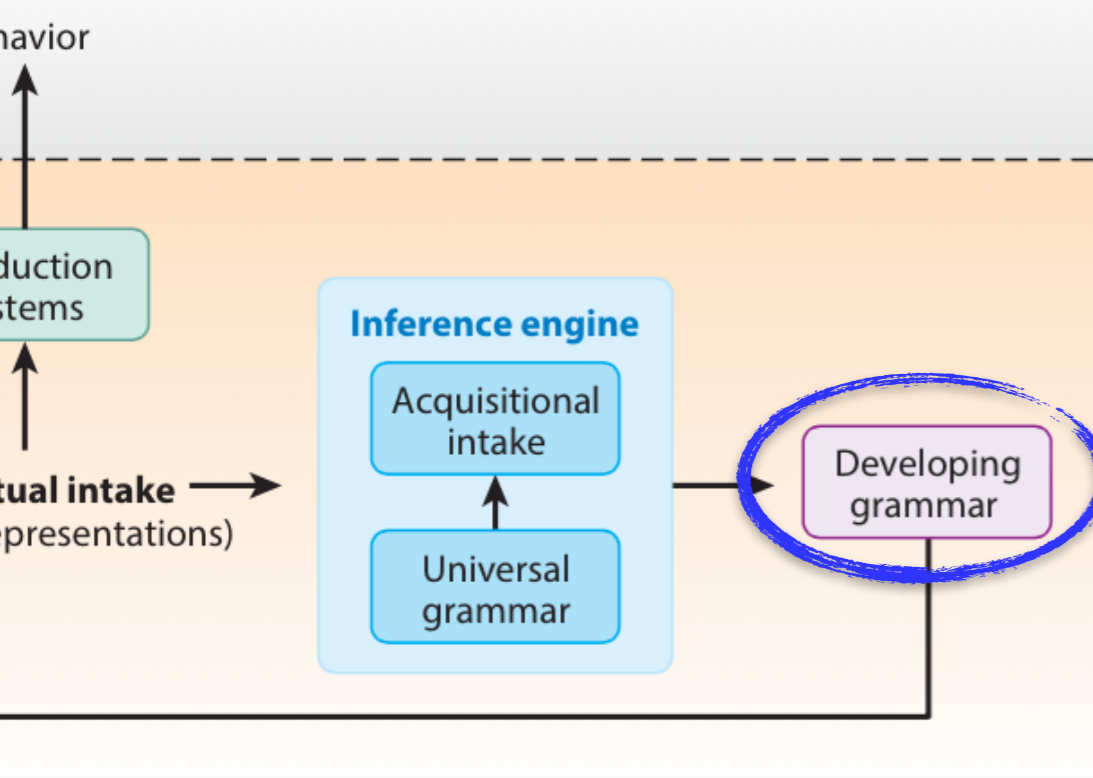
Implementation:
Random Index



$0.0 \leq RI \leq 1.0$





Intuition: Get credit for putting things together that belong together and keeping things apart that don't belong together.



Goal: Model the developmental trajectory from 3 to 4 to 5 years old



Implementation:
Random Index

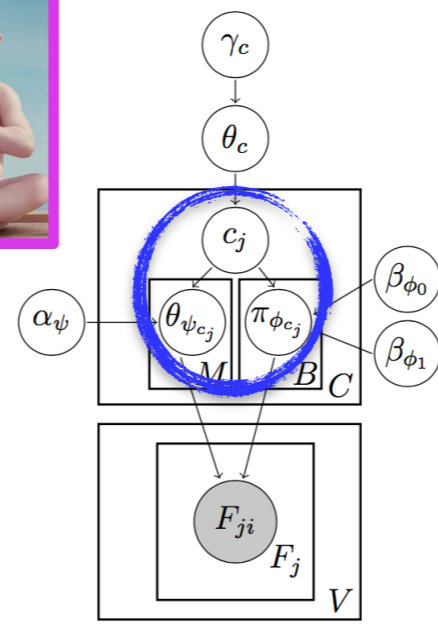
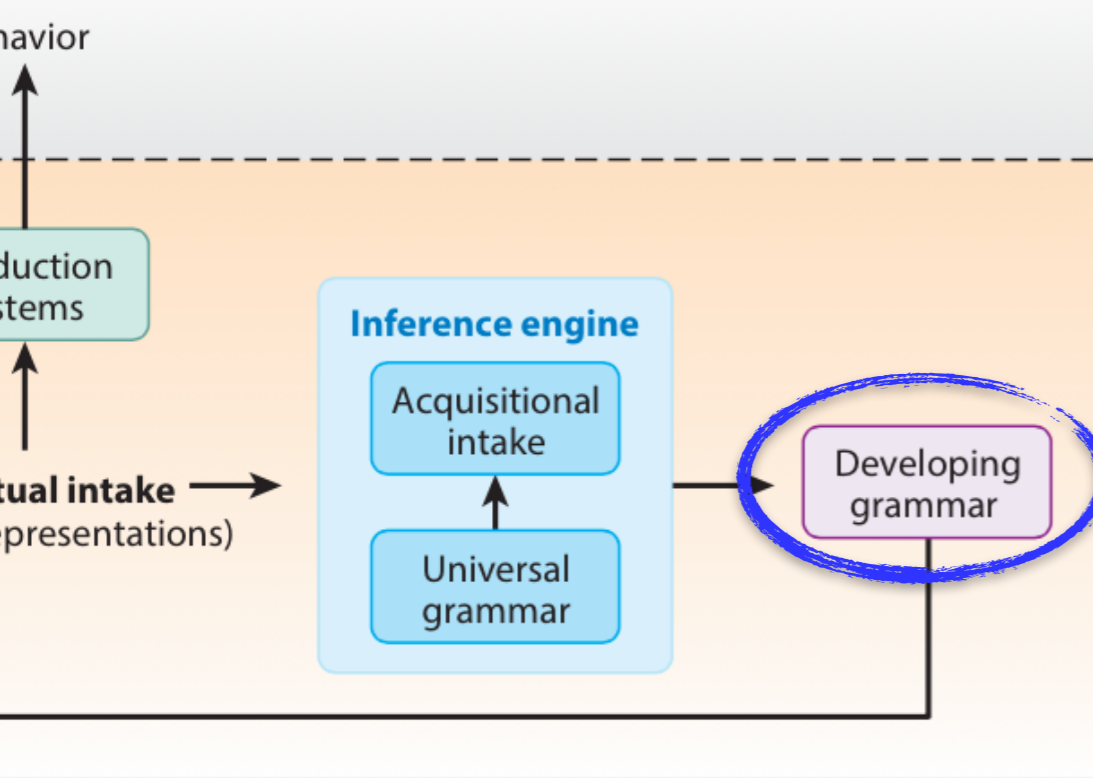


 $0.0 \leq RI \leq 1.0$



For each pair of verbs in $\text{verb}_i \text{ verb}_j$ the inferred classes:

| | | Inferred Class | |
|------|-----------------|----------------|-----------------|
| | | Same class | Different class |
| True | Same class | True Positive | False Negative |
| | Different class | False Positive | True Negative |

Intuition: Get credit for putting things together that belong together and keeping things apart that don't belong together.

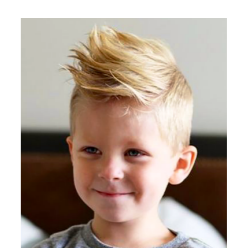


Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs

<5yrs

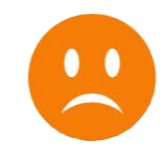


15 classes

23 classes

24 classes

Implementation:
Random Index



$$0.0 \leq RI \leq 1.0$$

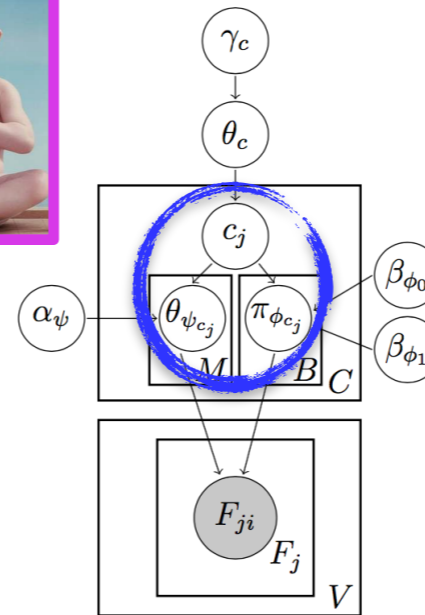
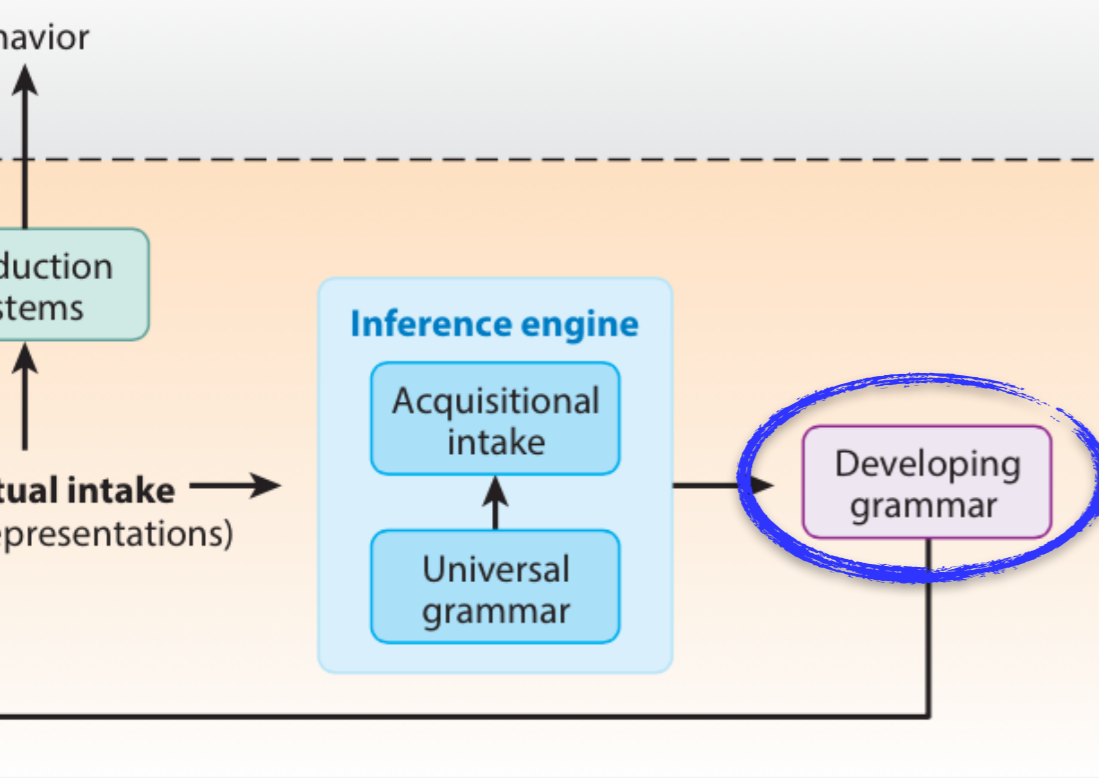
$$\frac{\text{True Positives} + \text{True Negatives}}{\text{True Positives} + \text{True Negatives} + \text{False Positives} + \text{False Negatives}}$$

For each pair of verbs in $\text{verb}_i \text{ verb}_j$ the inferred classes:

| | | Inferred Class | |
|------|-----------------|----------------|-----------------|
| | | Same class | Different class |
| True | Same class | True Positive | False Negative |
| | Different class | False Positive | True Negative |



Intuition: Get credit for putting things together that belong together and keeping things apart that don't belong together.



Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs

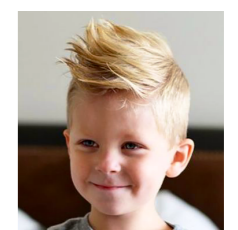
<5yrs



15 classes



23 classes



24 classes

Implementation:
Random Index



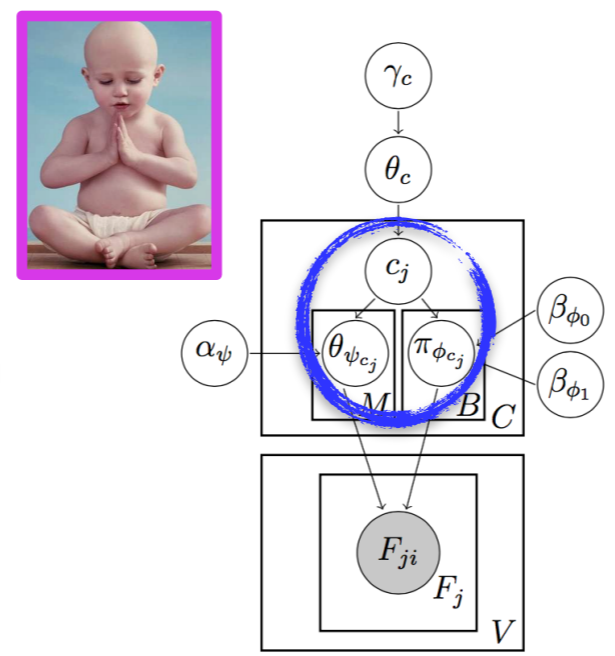
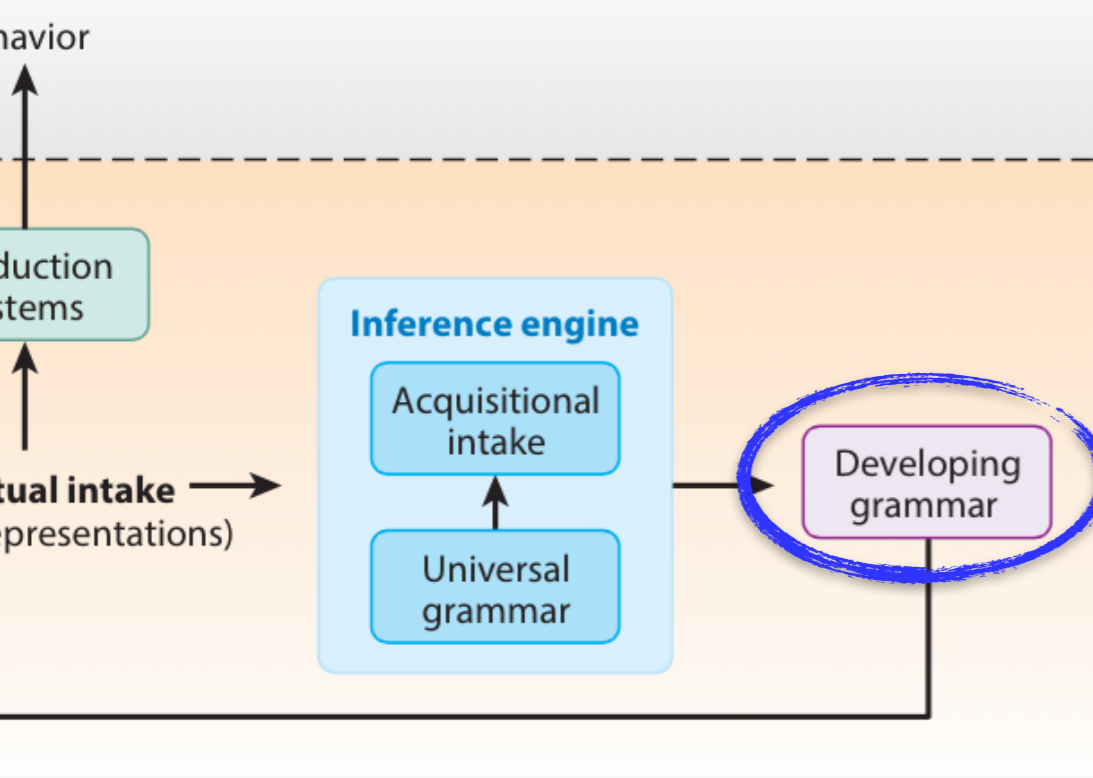
$$0.0 \leq RI \leq 1.0$$



Intuition: Get credit for putting things together that belong together and keeping things apart that don't belong together.

But how do we know we're doing better than chance?





Goal: Model the developmental trajectory from 3 to 4 to 5 years old



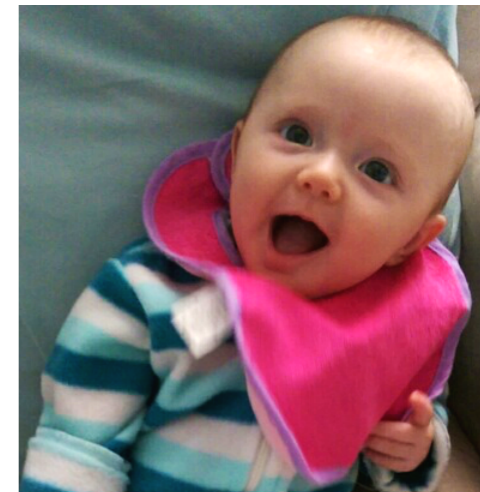
Implementation:

Adjusted Random Index $-1.0 \leq \text{ARI} \leq 1.0$



Compared against the expected value of the Random Index:

- 1.0 = perfect classification
- >0 = better than chance
- 0 = chance performance
- <0 = worse than chance
- 1.0 = perfectly awful classification



Today's plan

Verb classes



done-to

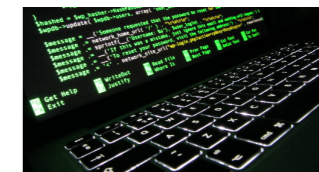
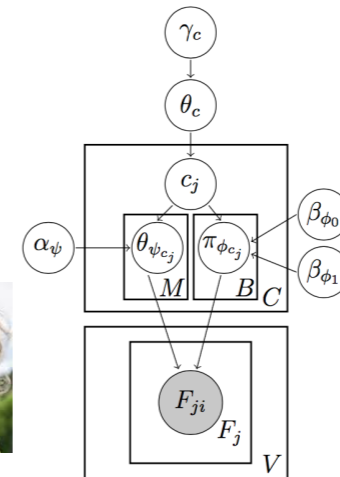
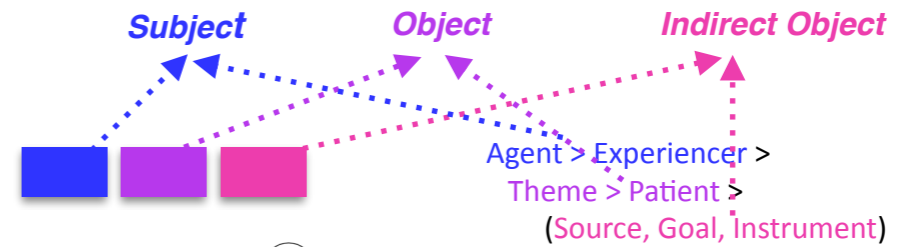
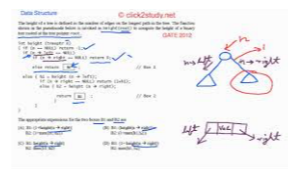
The ice melted.

The penguin climbed.

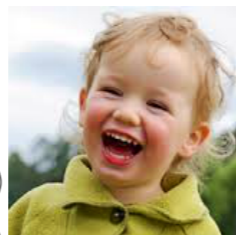
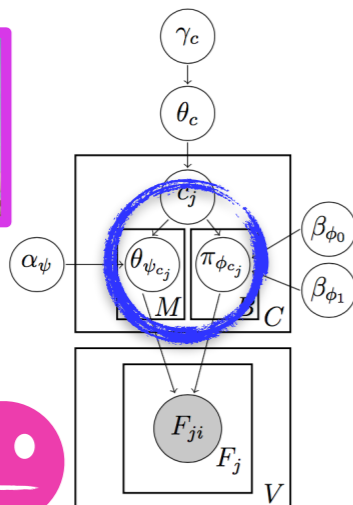
doer



Computational modeling

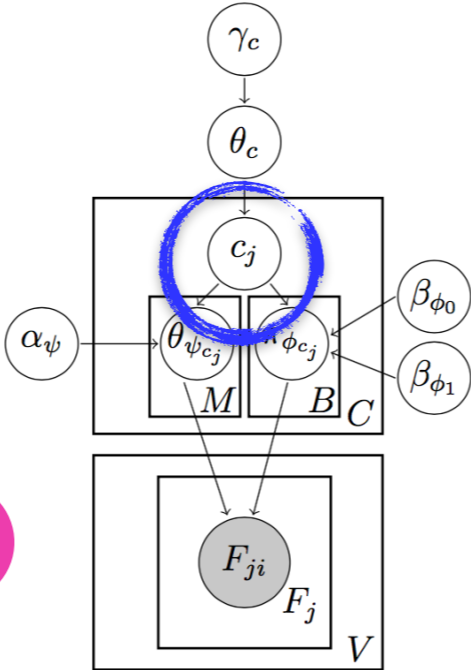


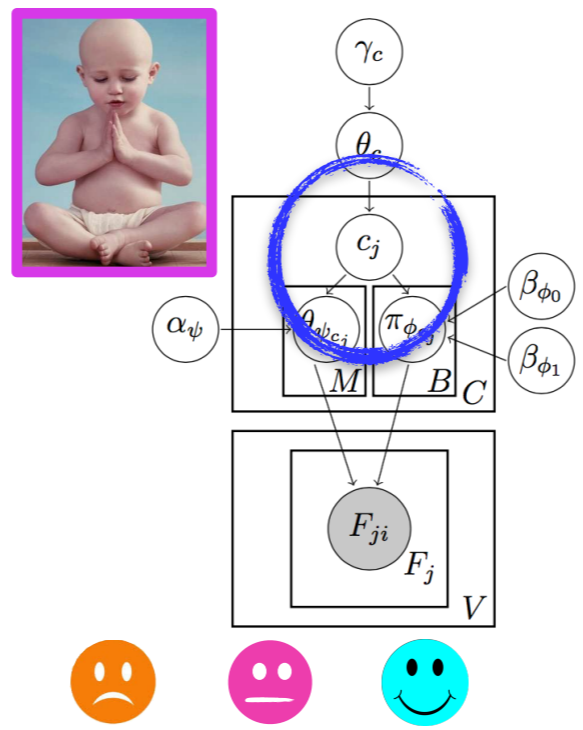
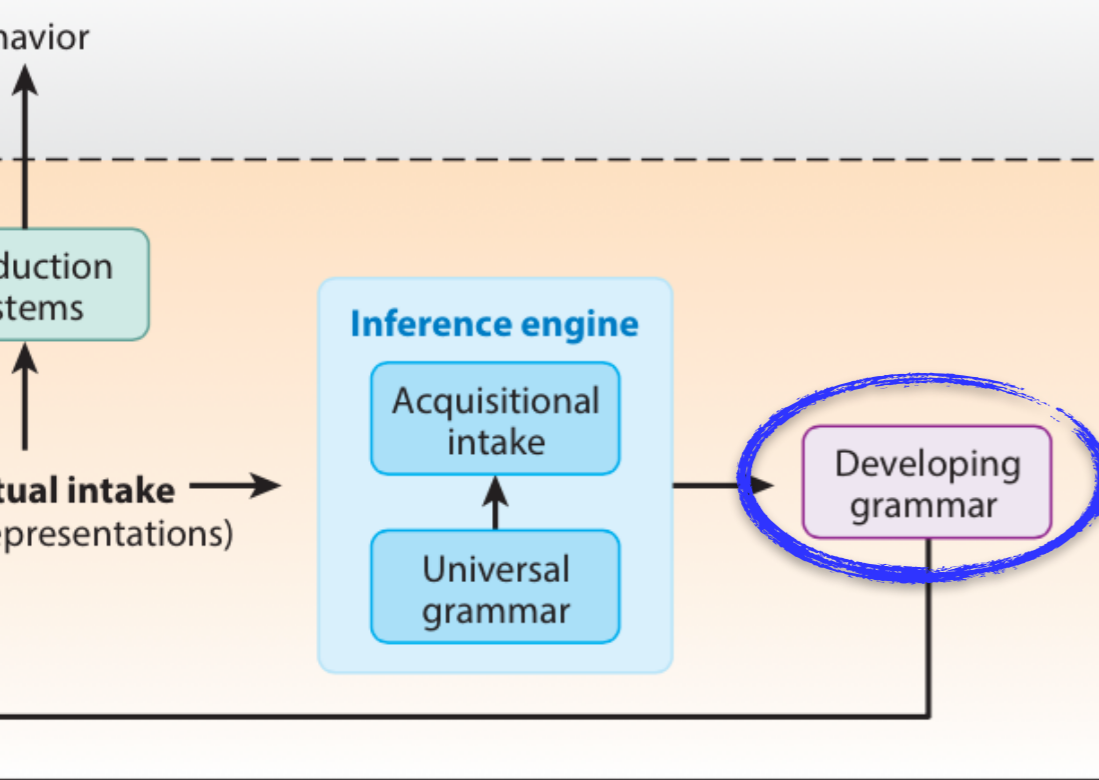
Results & implications



Today's plan

Results & implications





☹️ ☐ 😊

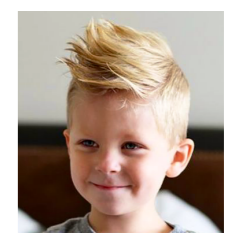
$-1.0 \leq \text{ARI} \leq 1.0$

Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs

<4yrs

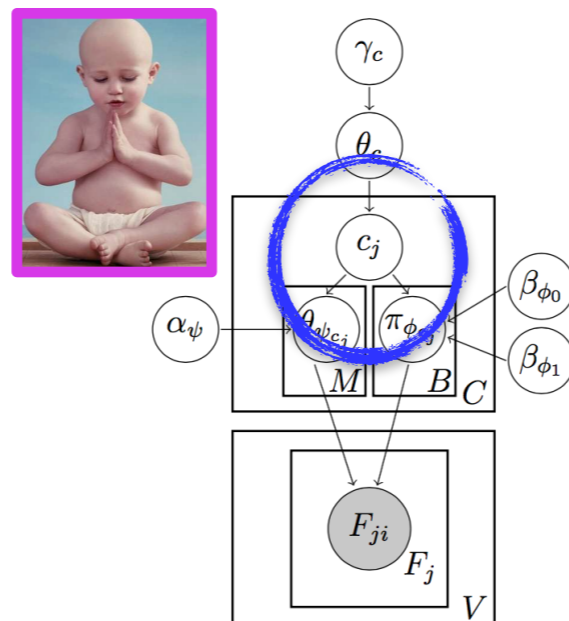
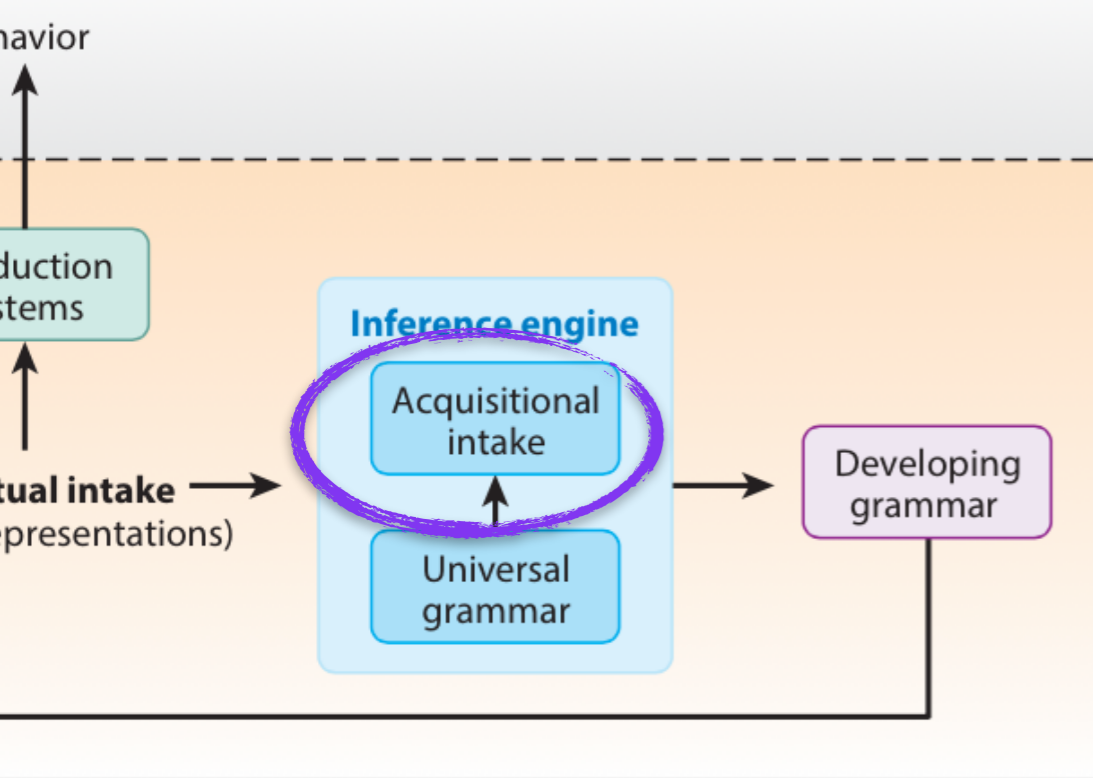
<5yrs




15 classes

23 classes

24 classes






 -1.0 <= ARI <= 1.0

Goal: Model the developmental trajectory from 3 to 4 to 5 years old

| | | |
|---|---|---|
| <3yrs | <4yrs | <5yrs |
|  |  |  |
| 15 classes | 23 classes | 24 classes |

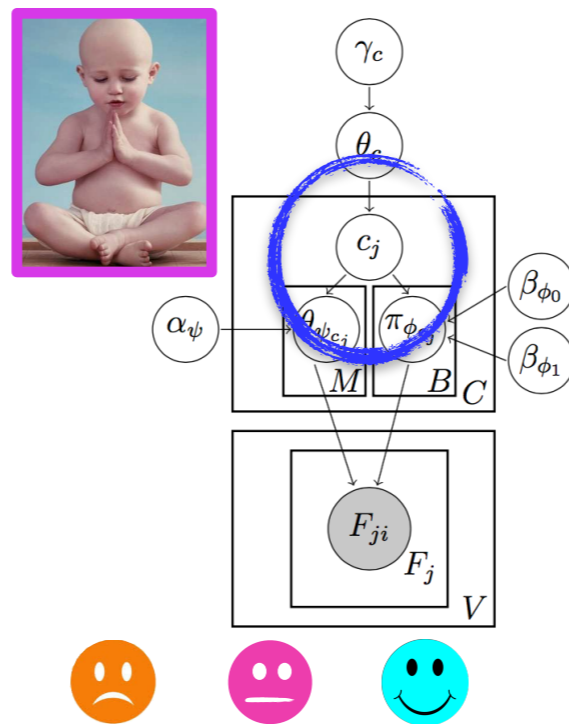
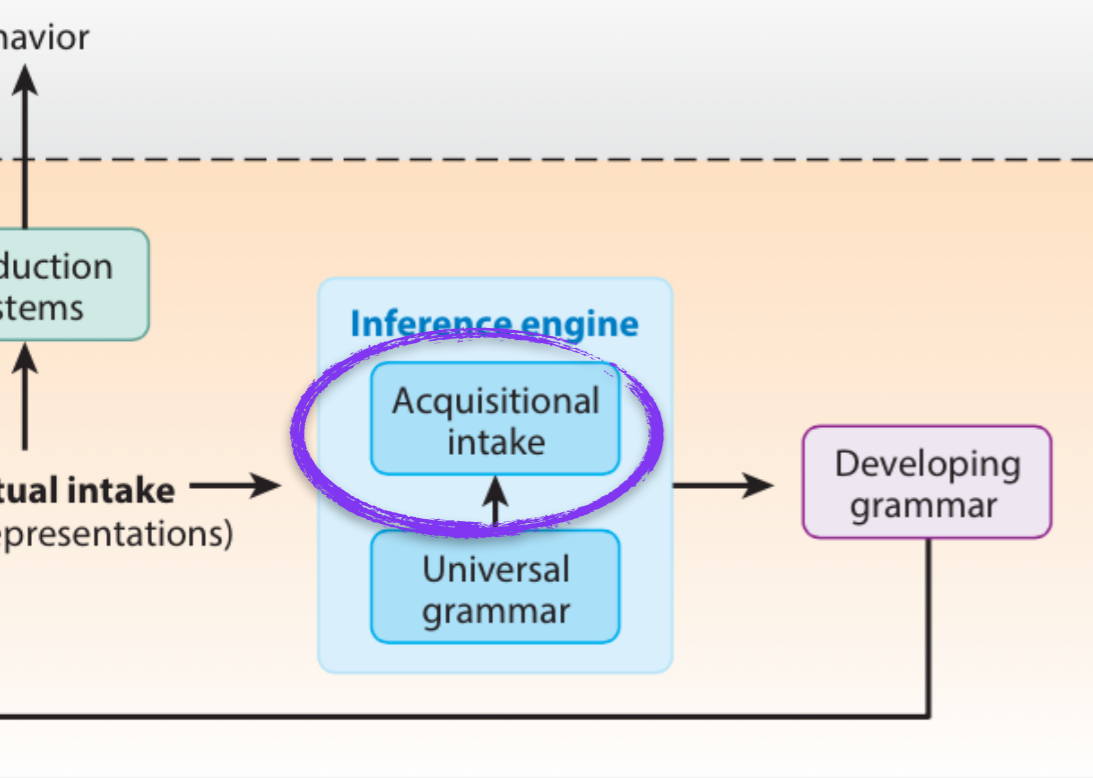
Animacy

+animate
The penguin tried to climb.



-animate
The ice seemed to melt.





-1.0 <= ARI <= 1.0

Animacy

Goal: Model the developmental trajectory from 3 to 4 to 5 years old

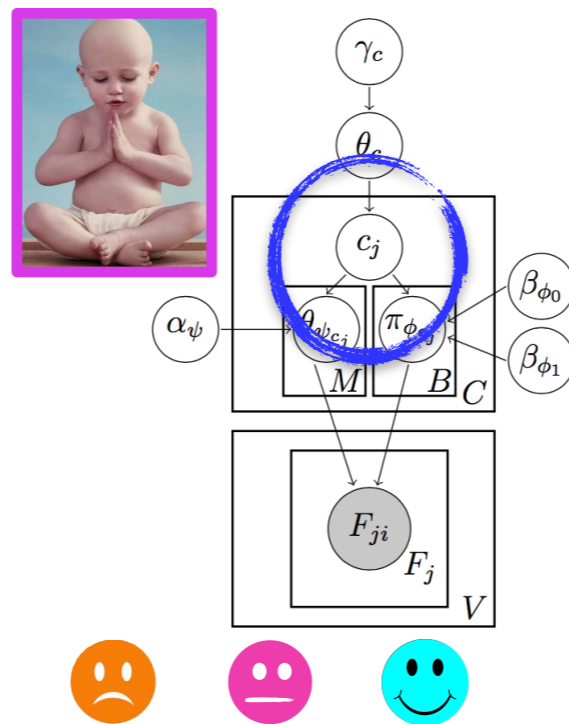
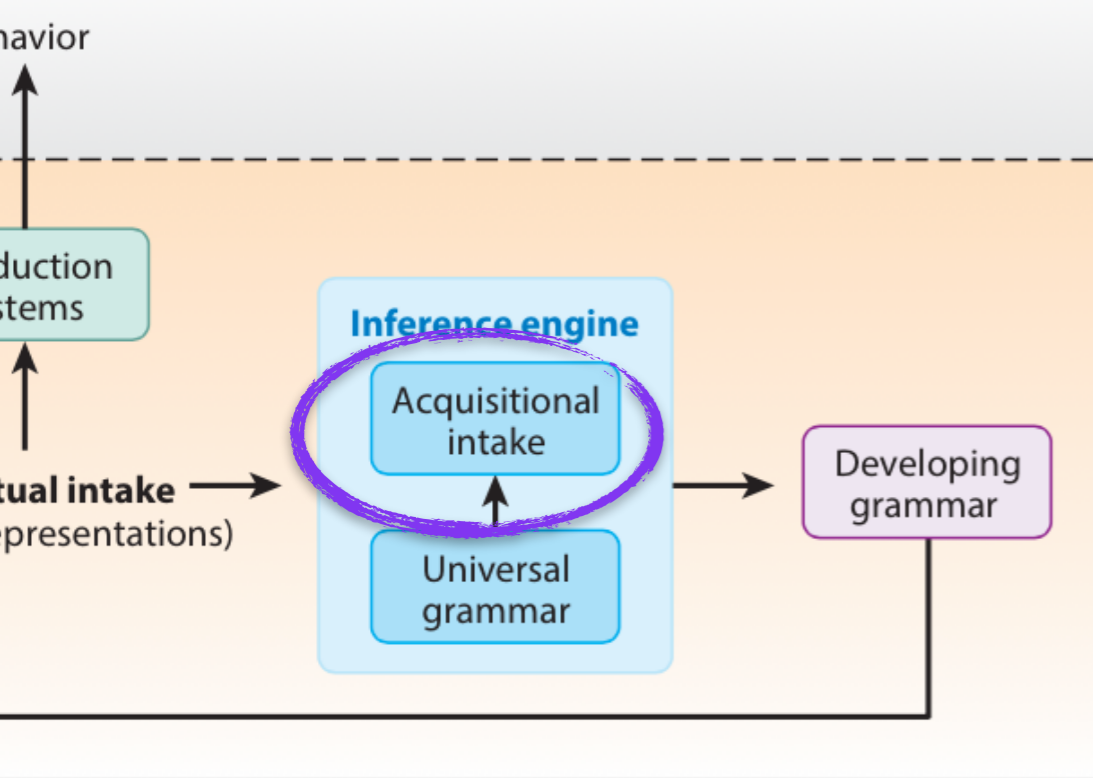
| | | |
|------------|------------|------------|
| <3yrs | <4yrs | <5yrs |
| | | |
| 15 classes | 23 classes | 24 classes |



Syntactic frame

The ice seemed to melt.

NP ___ S_{nonfinite} -surfmorph
 NP ___+past S_{nonfinite} +surfmorph






 $-1.0 \leq \text{ARI} \leq 1.0$

Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



15 classes 23 classes 24 classes

Animacy
Syntactic frame

+surfmorph

-surfmorph

Thematic roles and how to use them



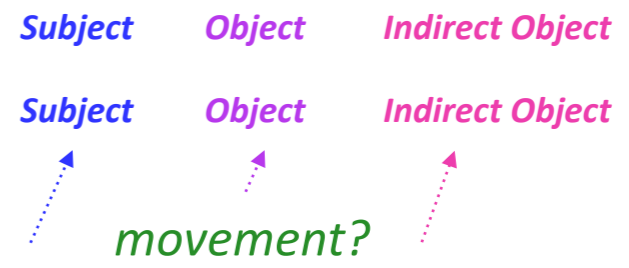
Agent > Experiencer >
Theme > Patient >
(Source, Goal, Instrument)

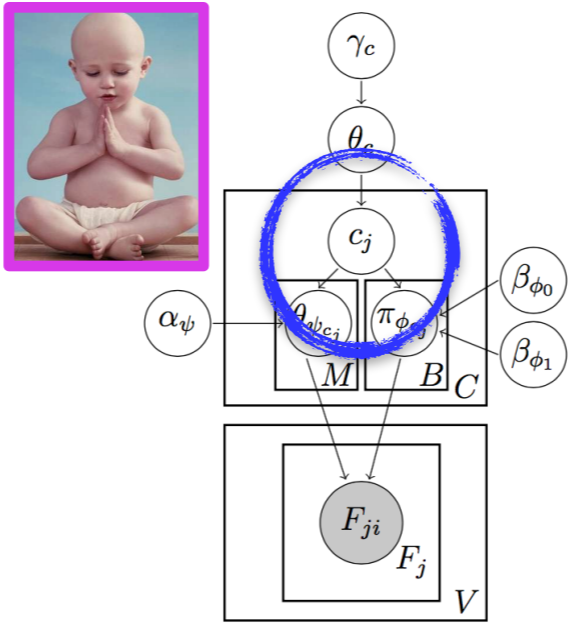
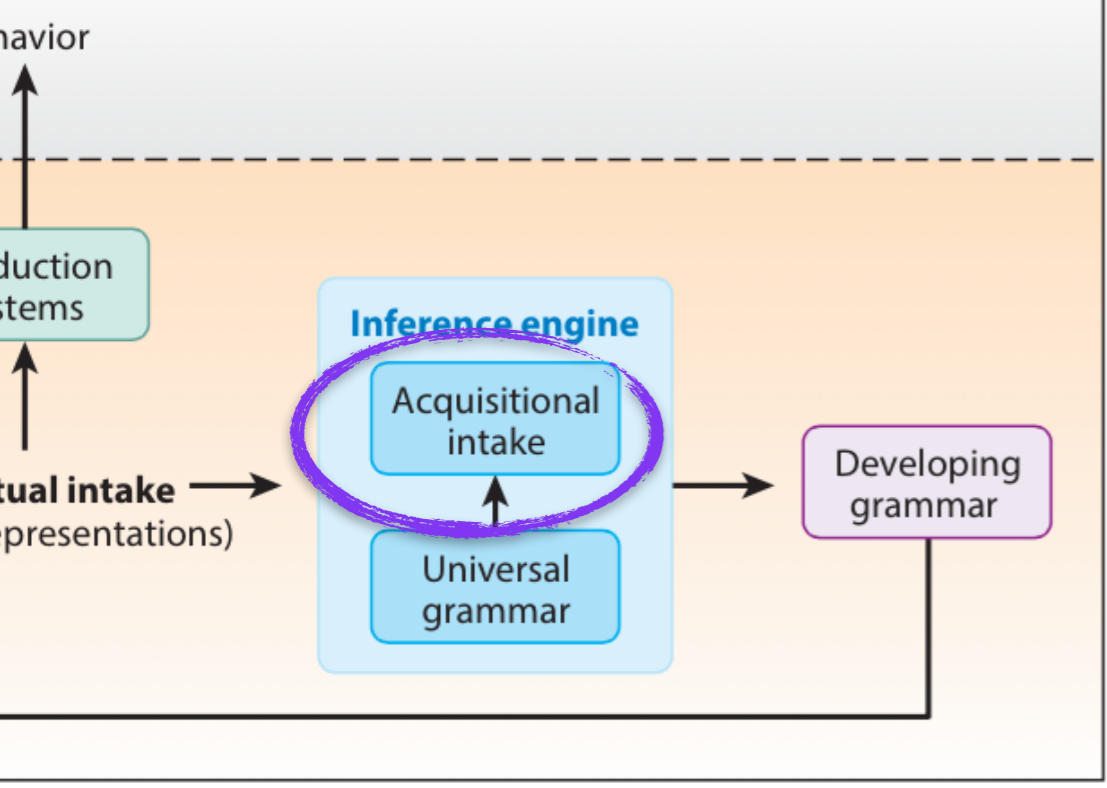
UTAH

rUTAH

-expmap

+expmap

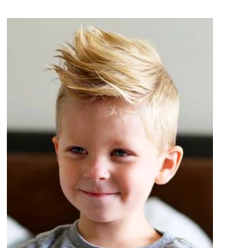




-1.0 <= ARI <= 1.0

Goal: Model the developmental trajectory from 3 to 4 to 5 years old

<3yrs <4yrs <5yrs



15 classes

23 classes

24 classes

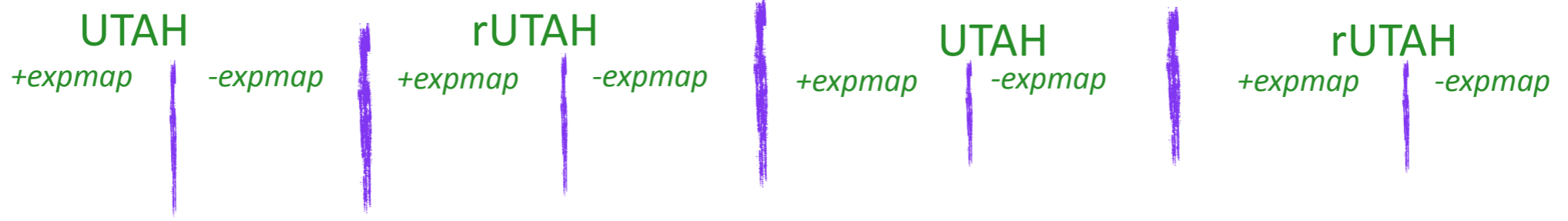
Animacy

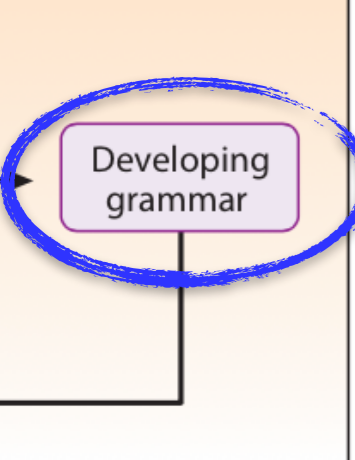
Syntactic frame

+surfmorph




-surfmorph

Thematic roles and how to use them





Animacy
Syntactic frame




 $-1.0 \leq \text{ARI} \leq 1.0$

<4yrs



23 classes

<5yrs

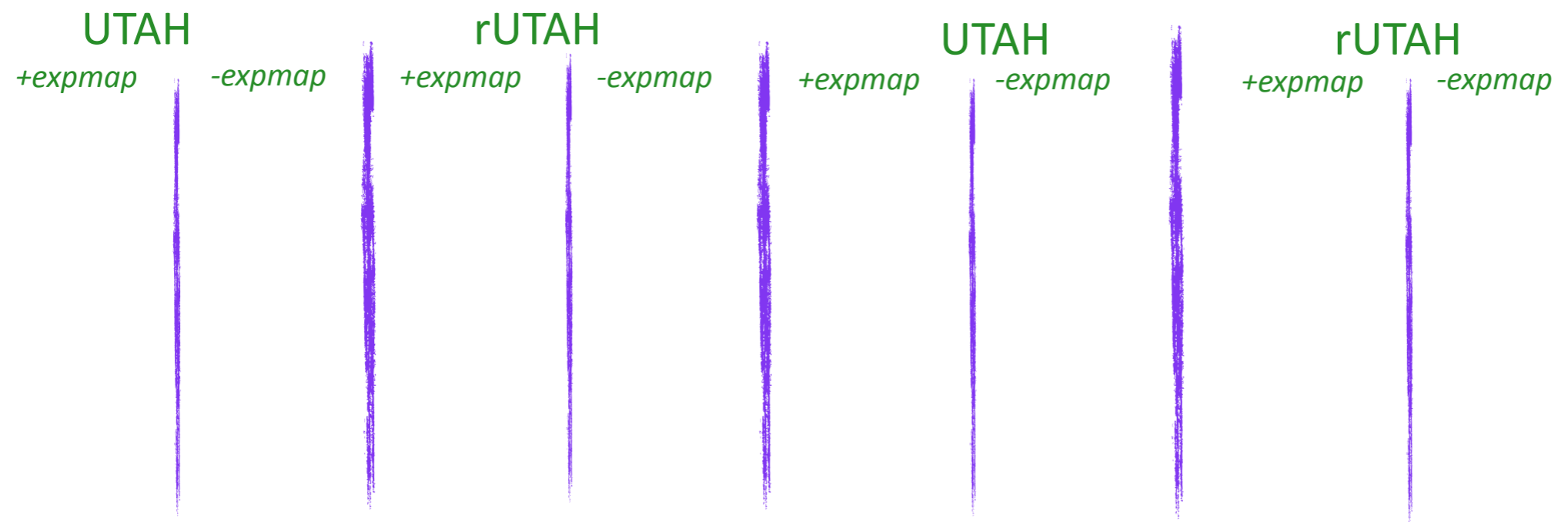


24 classes

+surfmorph

-surfmorph

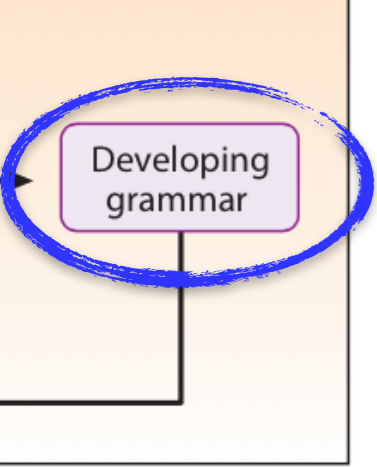
Thematic roles and how to use them






3yrs



15 classes



Animacy
Syntactic frame

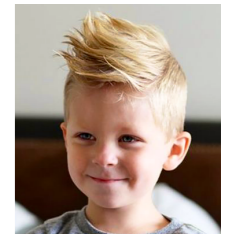



 $-1.0 \leq \text{ARI} \leq 1.0$

<4yrs



23 classes

<5yrs

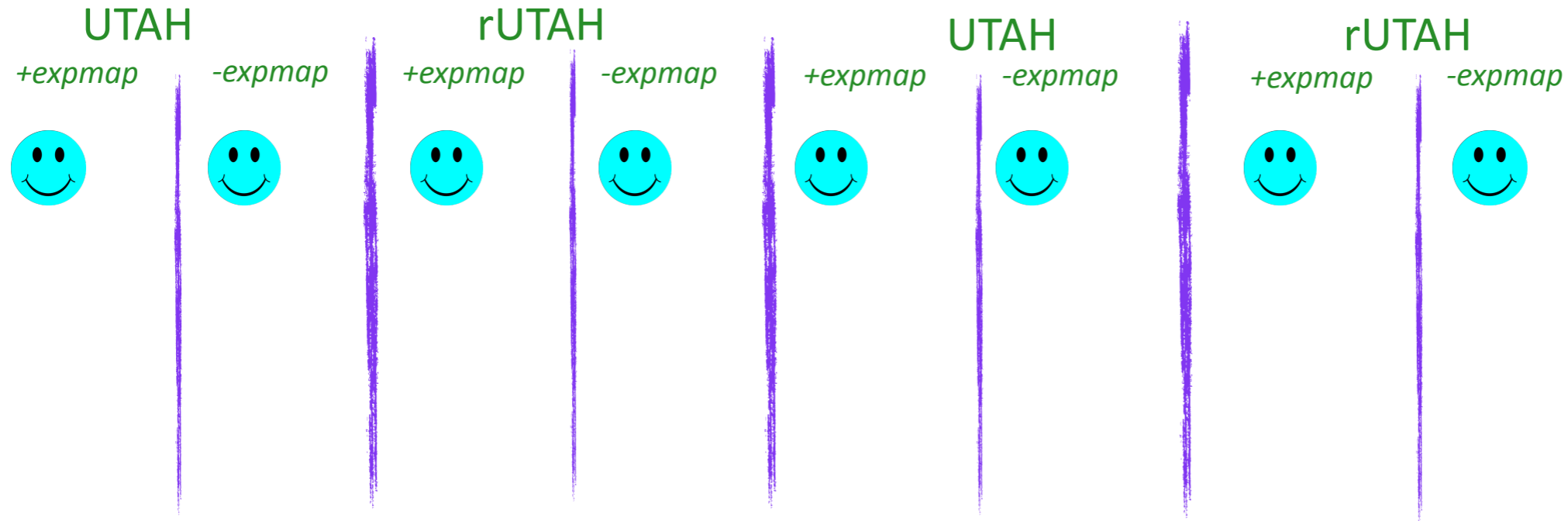


24 classes

+surfmorph

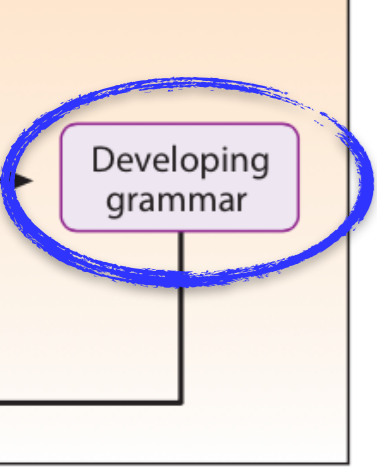
-surfmorph

Thematic roles and how to use them






3yrs
15 classes

All learning strategies are doing better than chance...



Animacy
Syntactic frame

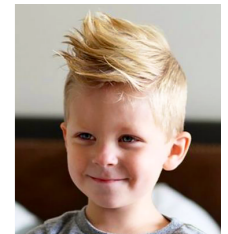



 $-1.0 \leq \text{ARI} \leq 1.0$

<4yrs



23 classes

<5yrs

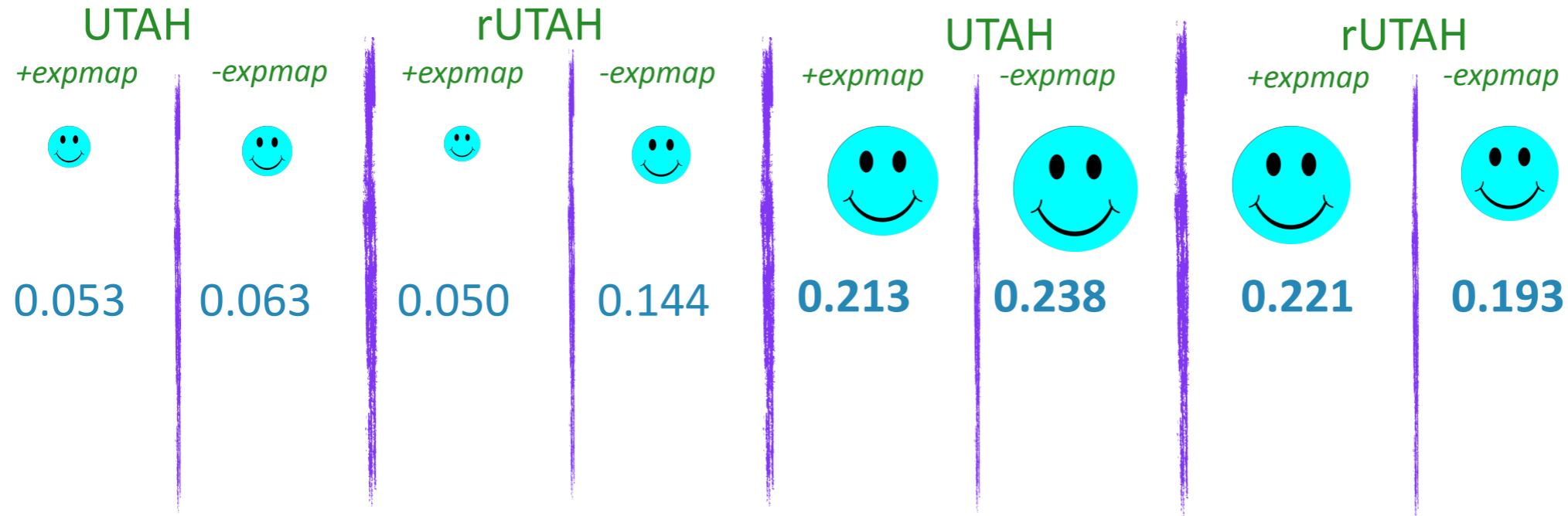


24 classes

+surfmorph

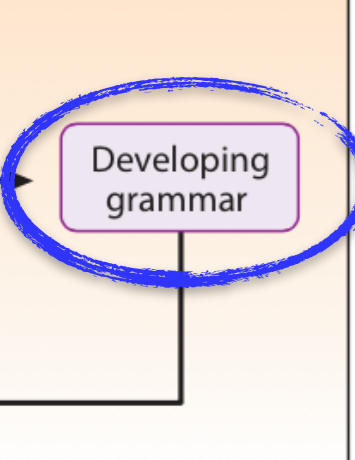
-surfmorph

Thematic roles and how to use them



3yrs
15 classes

But some are clearly doing better than others.



Animacy
Syntactic frame




 -1.0 <= ARI <= 1.0

<5yrs

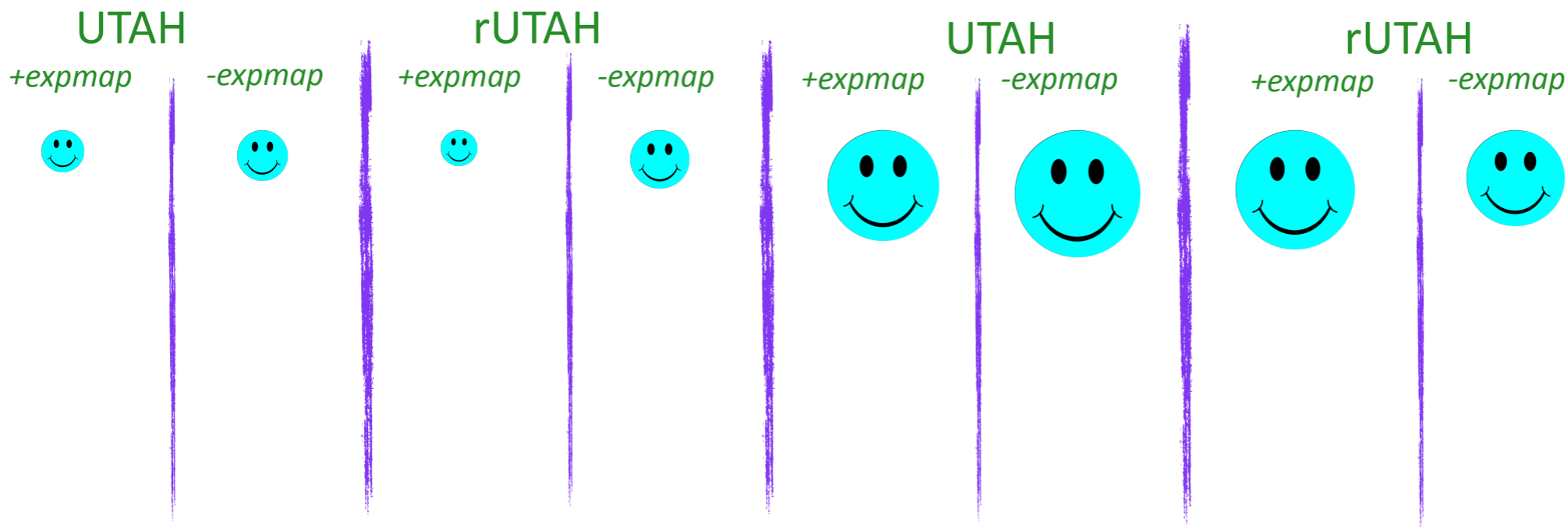


24 classes

+surfmorph

-surfmorph

Thematic roles and how to use them

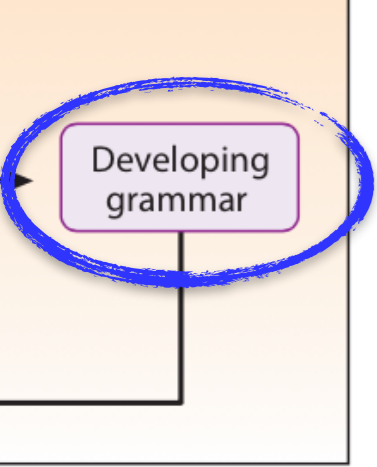


3yrs
15 classes




<4yrs



23 classes



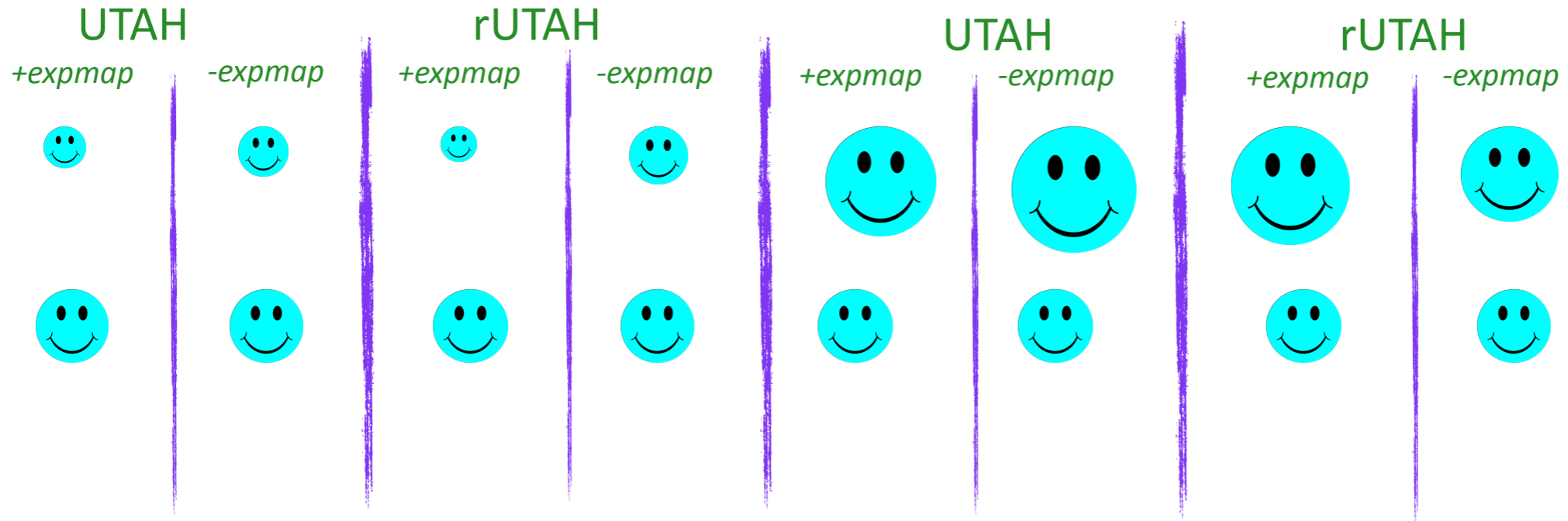
Animacy
Syntactic frame




 $-1.0 \leq \text{ARI} \leq 1.0$

+surfmorph

-surfmorph

Thematic roles and how to use them



<5yrs



24 classes



3yrs

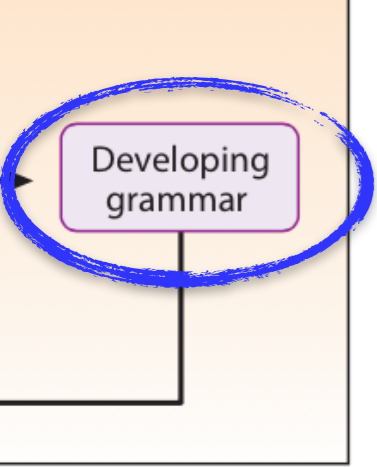
15 classes



4yrs

23 classes

All learning strategies are doing better than chance...






<5yrs



24 classes

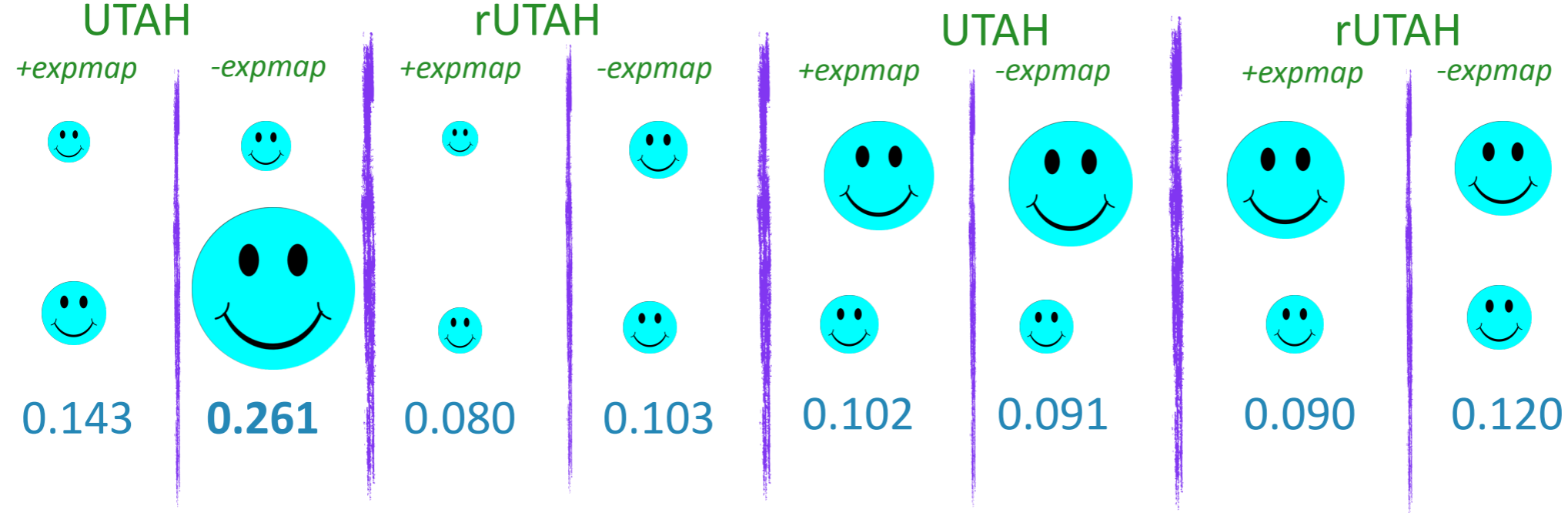
Animacy
Syntactic frame




 $-1.0 \leq \text{ARI} \leq 1.0$

+surfmorph

-surfmorph

Thematic roles and how to use them

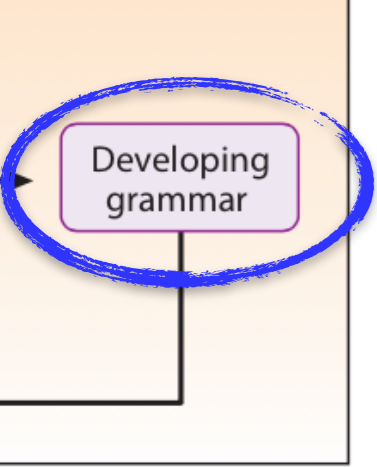


3yrs
15 classes



4yrs
23 classes

But one is clearly doing better than others.



Animacy
Syntactic frame

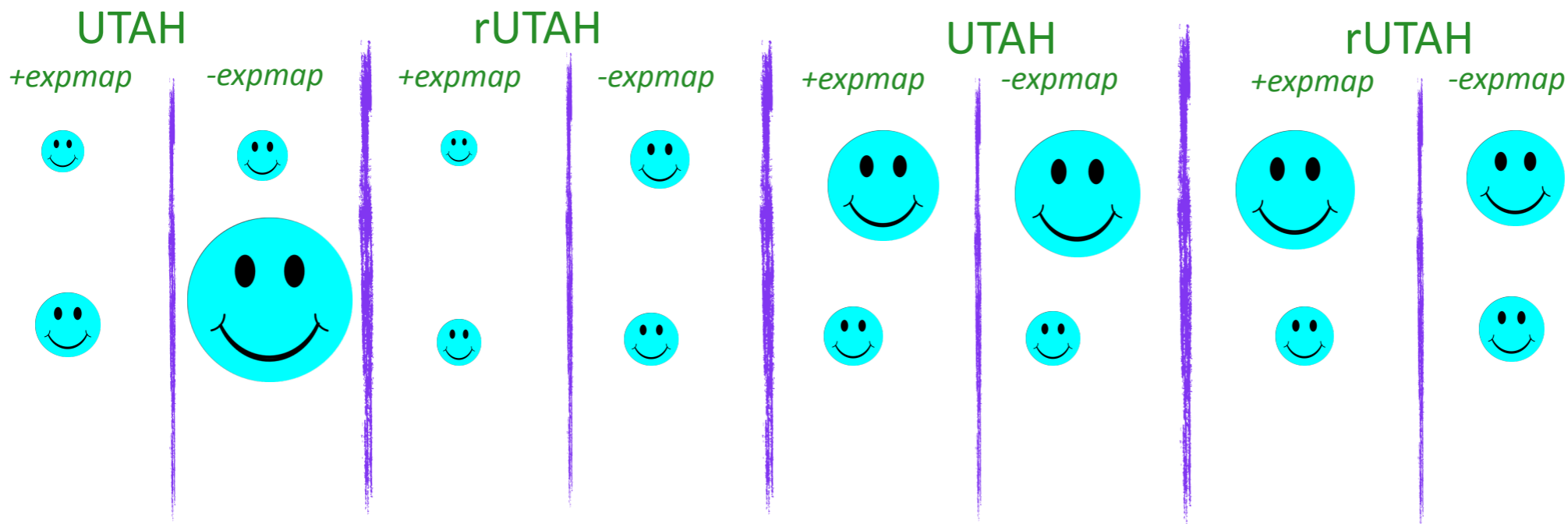



 $-1.0 \leq \text{ARI} \leq 1.0$

+surfmorph

-surfmorph

Thematic roles and how to use them



3yrs
15 classes

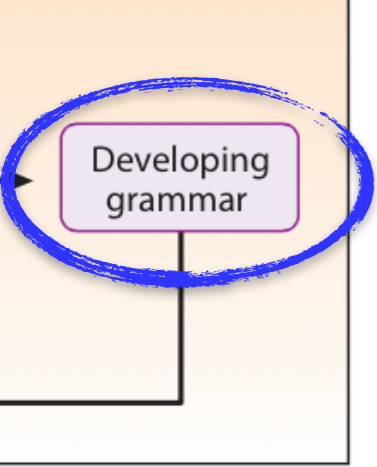


4yrs
23 classes




<5yrs



24 classes



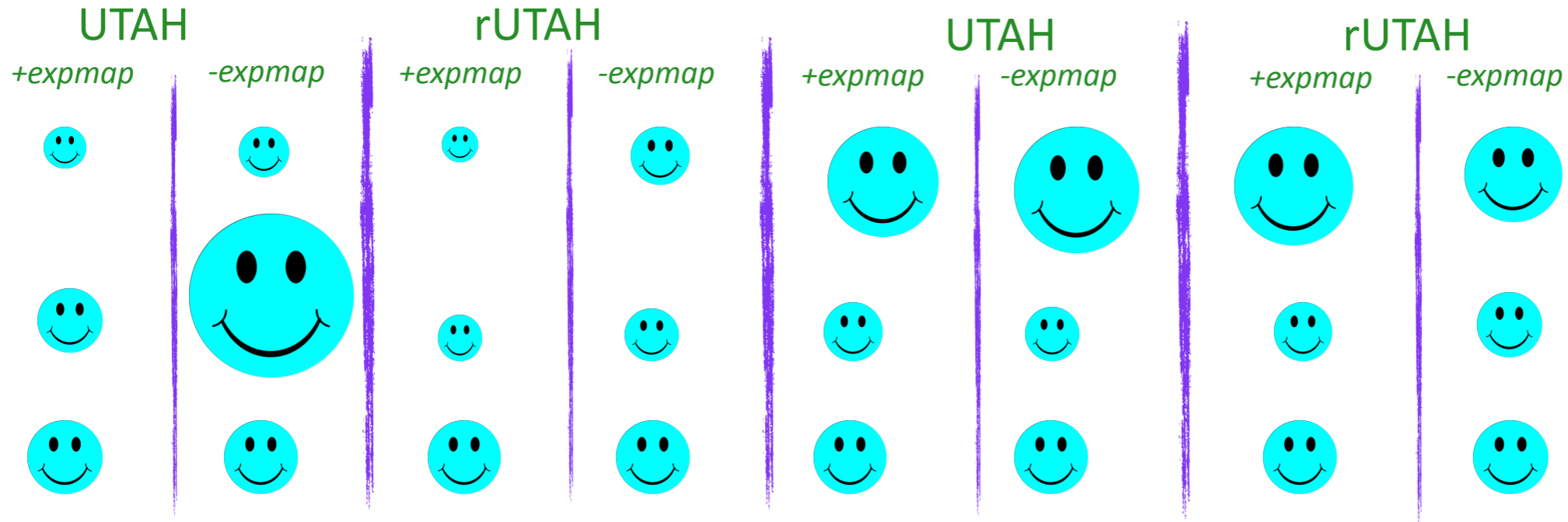
Animacy
Syntactic frame






 $-1.0 \leq \text{ARI} \leq 1.0$

+surfmorph

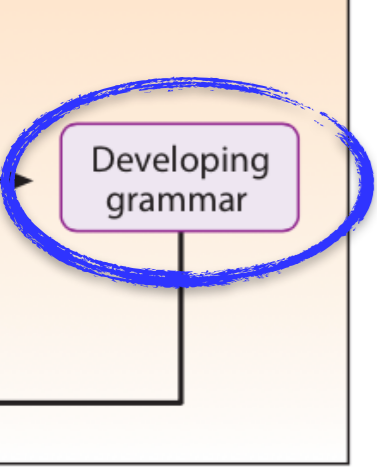
-surfmorph

Thematic roles and how to use them






 **3yrs**
15 classes
 **4yrs**
23 classes
 **5yrs**
24 classes

All learning strategies are doing better than chance...



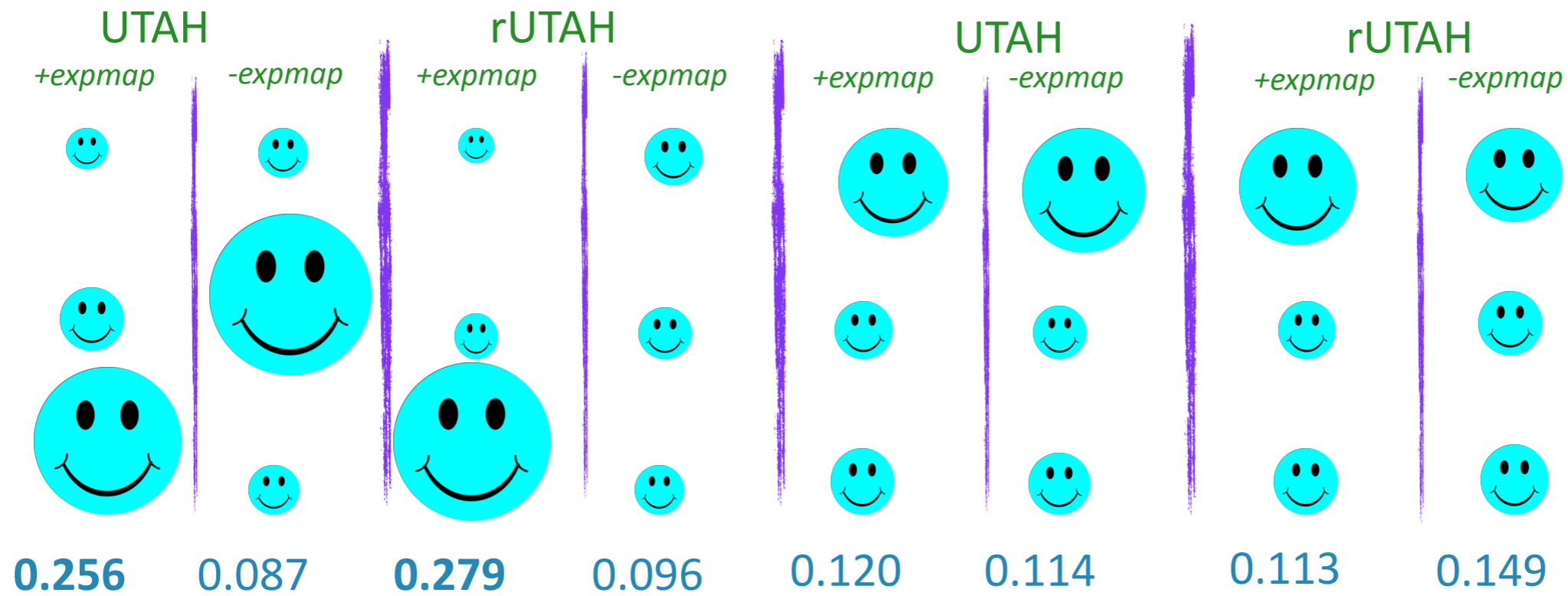
Animacy
Syntactic frame




 $-1.0 \leq \text{ARI} \leq 1.0$

+surfmorph

-surfmorph

Thematic roles and how to use them



3yrs
15 classes

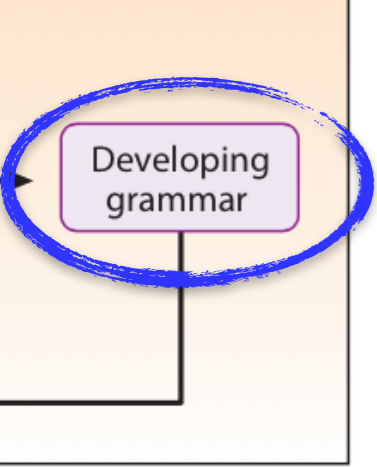


4yrs
23 classes






5yrs
24 classes

But two are clearly doing better than others.



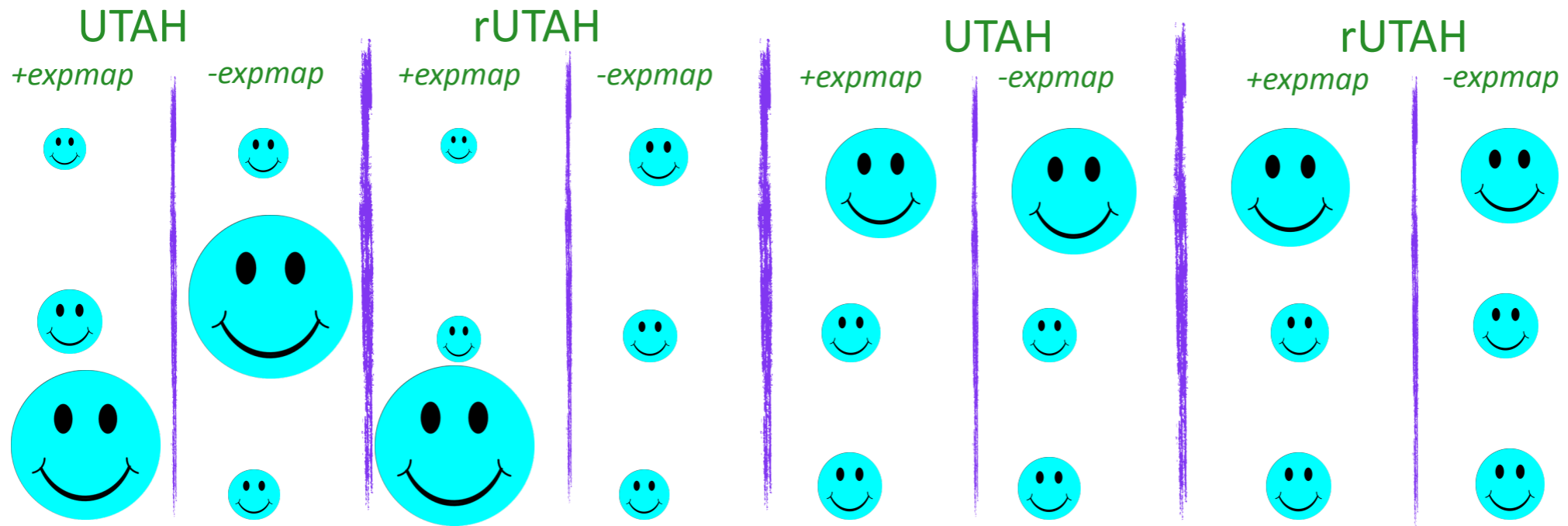
Animacy
Syntactic frame





 $-1.0 \leq \text{ARI} \leq 1.0$

+surfmorph

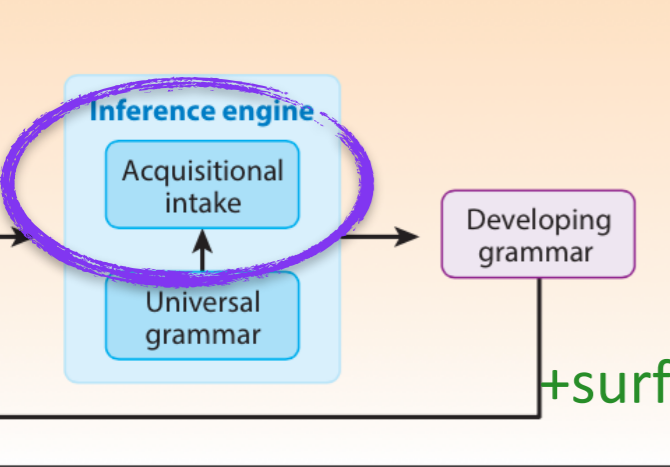
-surfmorph




Thematic roles and how to use them

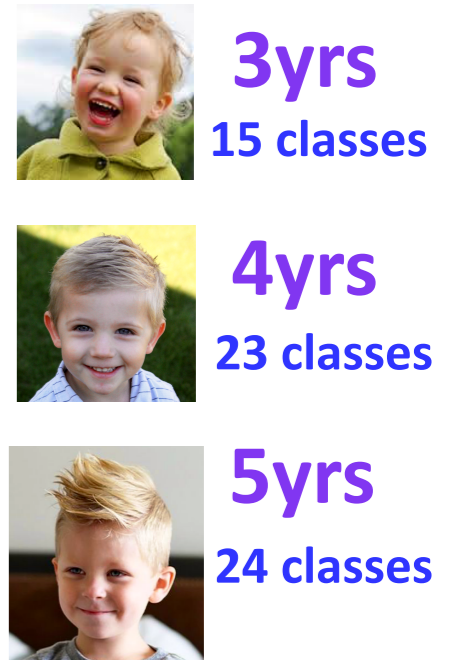
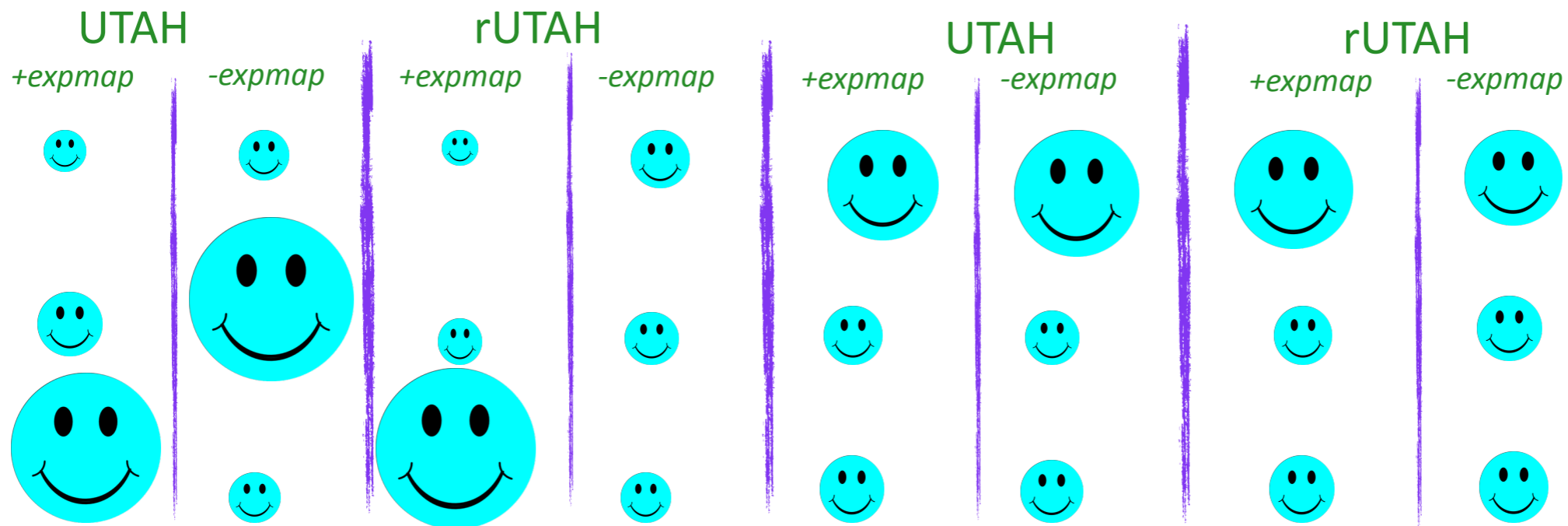


| | |
|---|---------------------------|
|  | 3yrs 15 classes |
|  | 4yrs 23 classes |
|  | 5yrs 24 classes |

What does this mean?



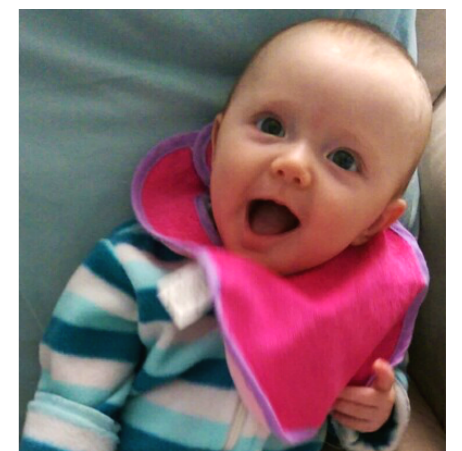



 $-1.0 \leq \text{ARI} \leq 1.0$
 -surfmorph

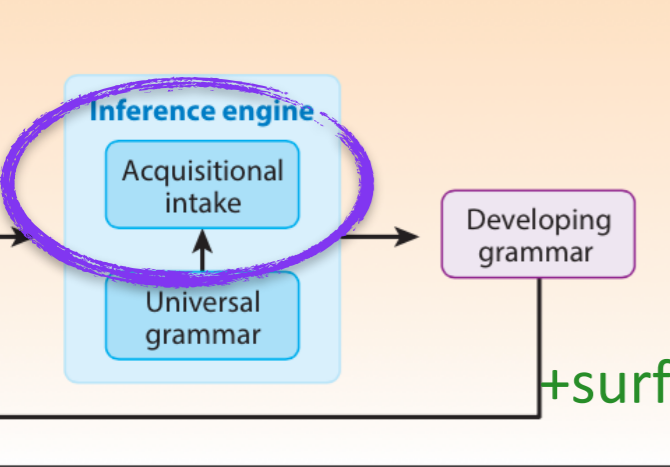


Animacy
Syntactic frame
Thematic roles and how to use them



Using animacy, syntactic frame, and thematic role information is a pretty good match for what children seem to be doing when creating verb classes.

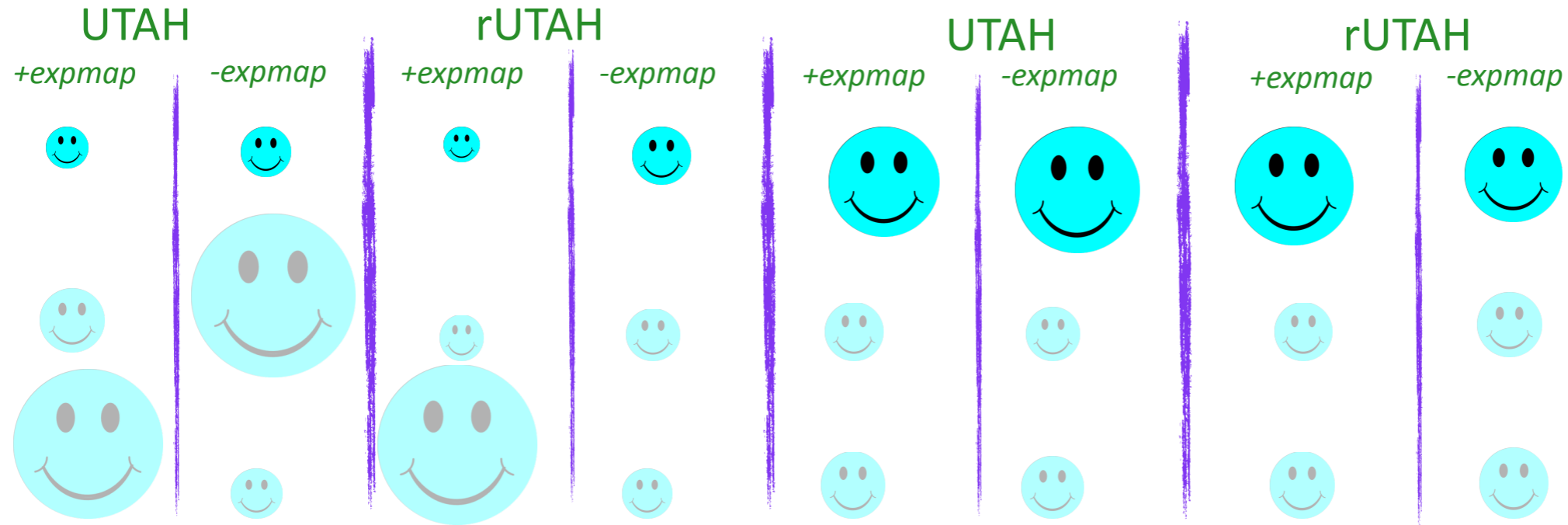




Animacy
Syntactic frame

-surfmorph

Thematic roles and how to use them



3yrs



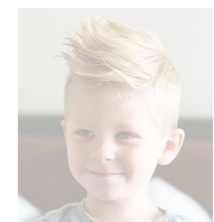
Syntactic frame

The ice seemed to melt.
NP ____ S_{nonfinite} -surfmorph

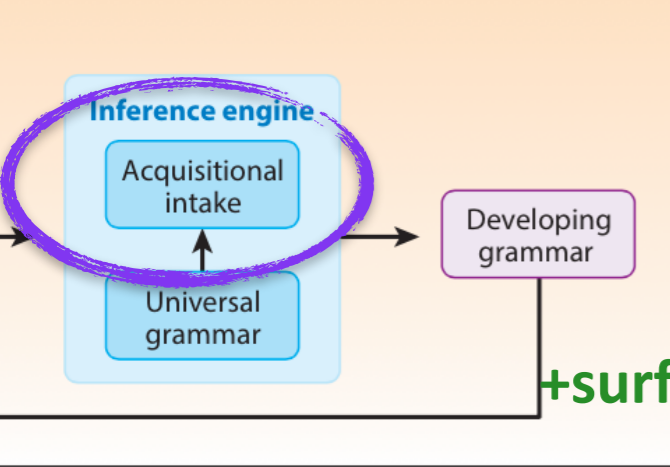
Before 3, children ignore verb morphology but may be using any of the options for thematic roles.



4yrs
23 classes



5yrs
24 classes



Animacy Syntactic frame

+surfmorph

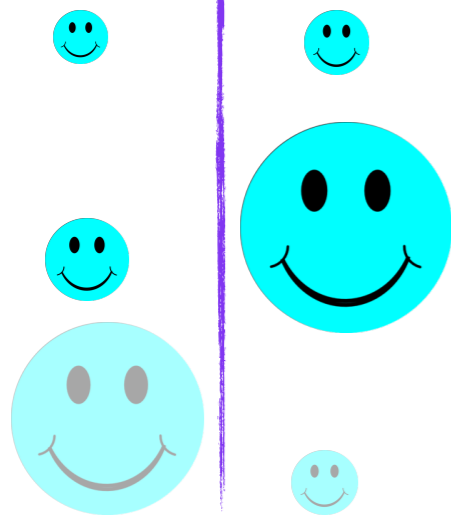
-surfmorph

Thematic roles and how to use them

UTAH

+expmap

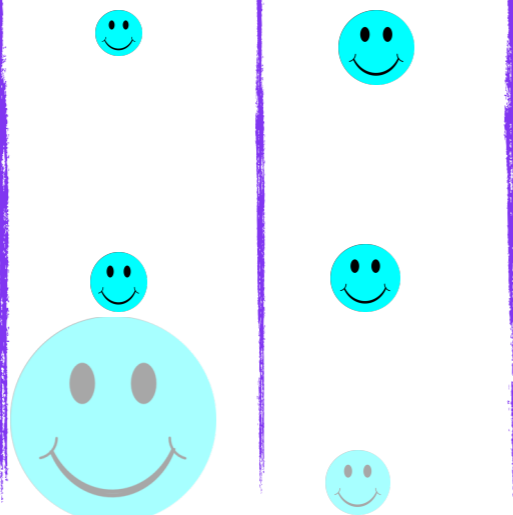
-expmap



rUTAH

+expmap

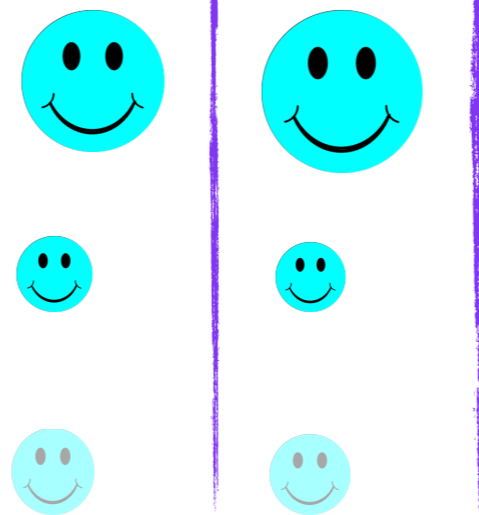
-expmap



UTAH

+expmap

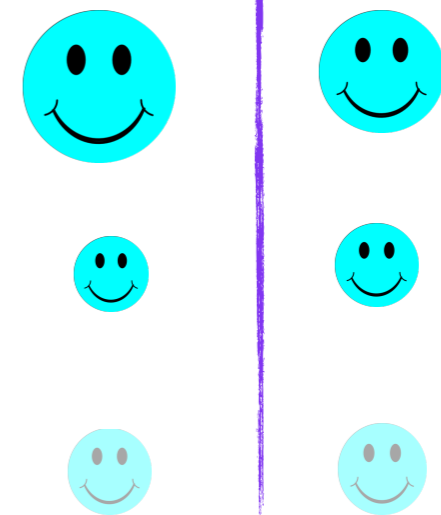
-expmap



rUTAH

+expmap

-expmap



3yrs



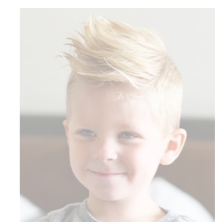
-surfmorph

4yrs



5yrs

24 classes



By 4, children heed verb morphology, are using the UTAH intermediate representation, and don't expect a mapping a priori.

Syntactic frame

+surfmorph

The ice seemed to melt.
 NP ____ +past S_{nonfinite}

Thematic roles

and how to use them



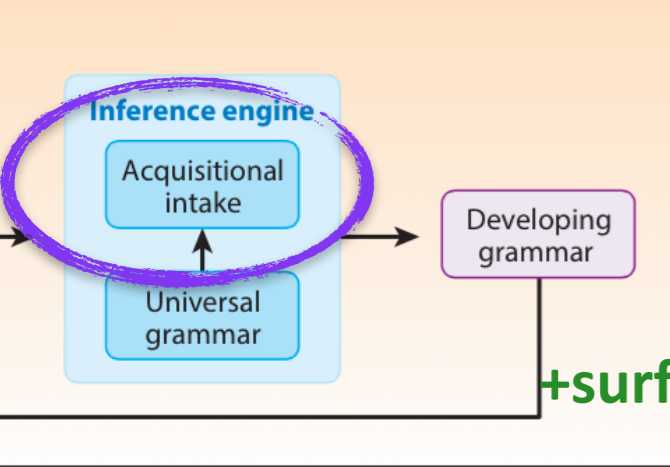
Subject

Object

Indirect Object

UTAH

-expmap

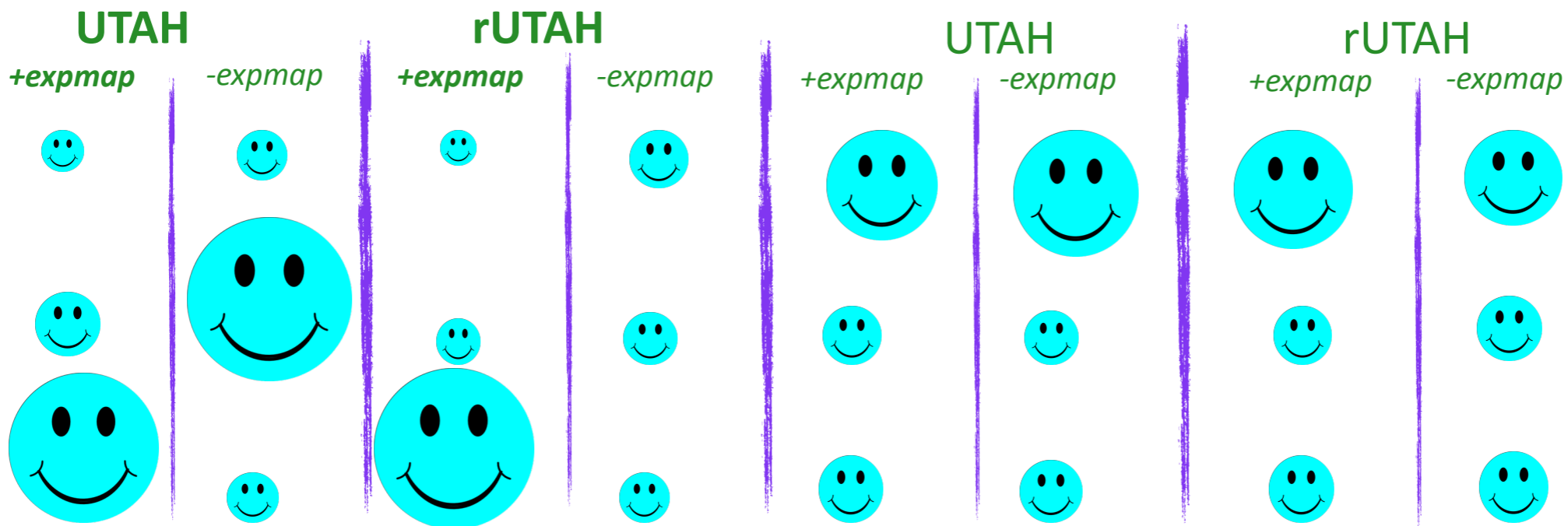


Animacy Syntactic frame

+surfmorph

-surfmorph

Thematic roles and how to use them



3yrs



-surfmorph

4yrs



+surfmorph

UTAH

-expmap

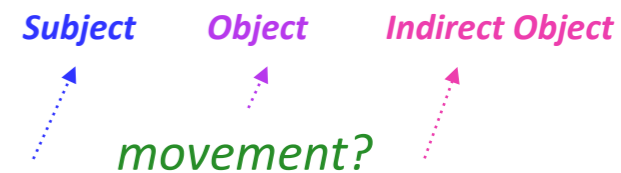
5yrs

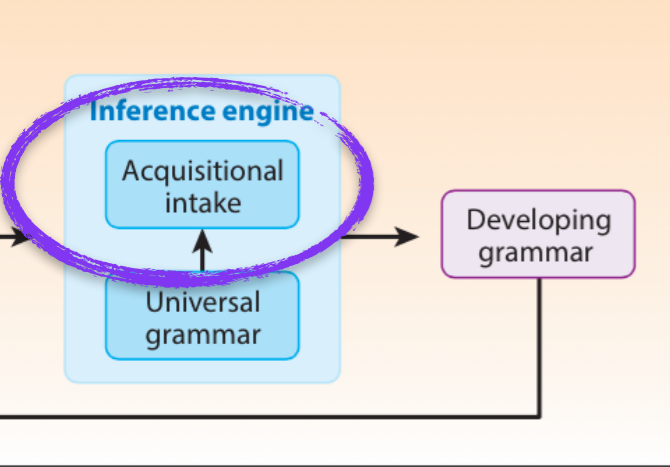


By 5, children still heed verb morphology, but now may be using either the UTAH or rUTAH representation and expect a mapping.



rUTAH Agent > Experiencer > +expmap
Theme > Patient >
(Source, Goal, Instrument)





-animate
The ice seemed to melt.

NP _____ S_{nonfinite}



Agent > Experiencer >

? Theme > Patient >
(Source, Goal, Instrument)

Subject Object Indirect Object

3yrs



-surfmorph

4yrs

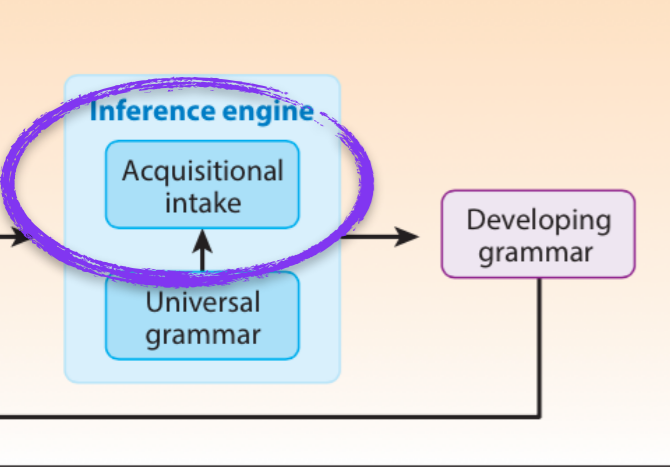


+surfmorph
UTAH
-expmap

5yrs



+surfmorph
UTAH rUTAH
+expmap



-animate
Subject
 The ice seemed to melt.

NP ____ +past Snonfinite



Subject

Object

Indirect Object

3yrs



-surfmorph

4yrs



+surfmorph

UTAH

-expmap

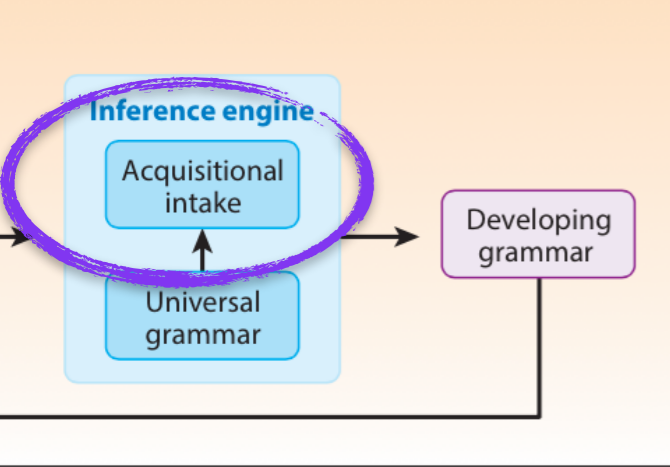
5yrs



+surfmorph

UTAH rUTAH

+expmap



-animate
Subject
The ice seemed to melt.

+movement



NP _____ +past Snonfinite

Highest -movement
Theme



Agent > Experiencer >
Theme > Patient >
(Source, Goal, Instrument)

3yrs



-surfmorph

4yrs



+surfmorph

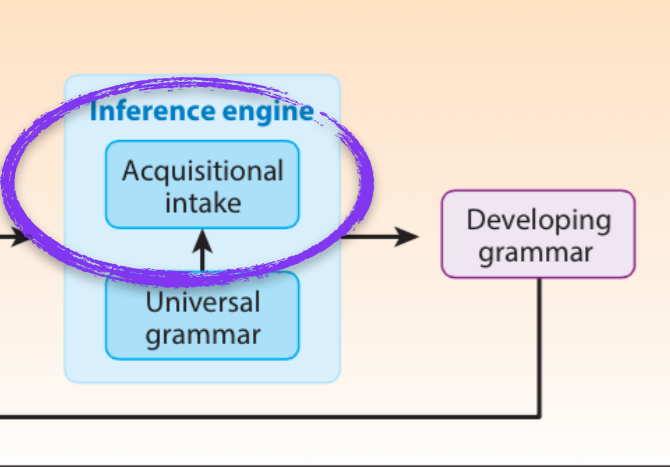
UTAH
-expmap

5yrs



+surfmorph

UTAH rUTAH
+expmap



3yrs



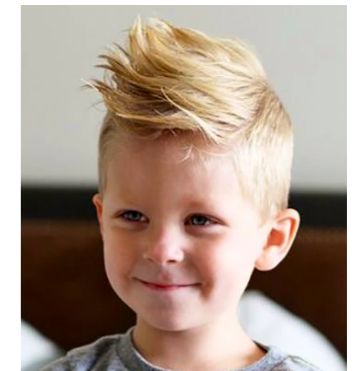
-surfmorph

4yrs



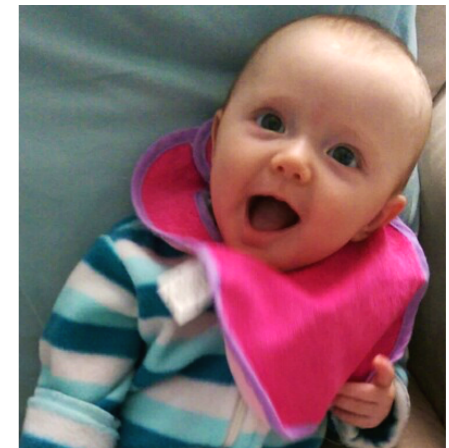
+surfmorph
UTAH
-expmap

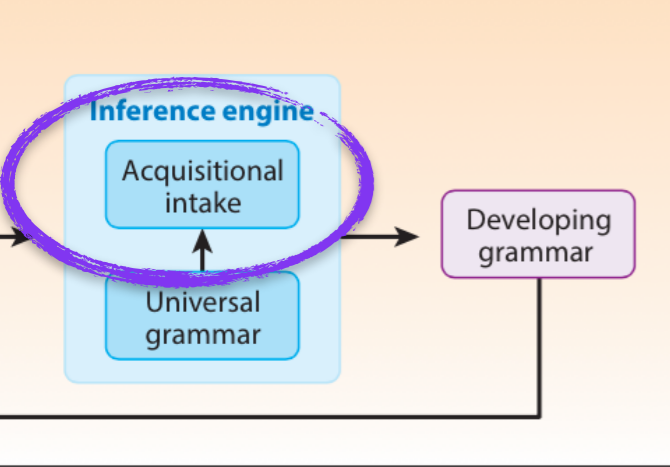
5yrs



+surfmorph
UTAH rUTAH
+expmap

This is the first articulation of the trajectory of learning assumptions children may have that causes them to group verbs into useful classes the way we observe.





3yrs



-surfmorph

4yrs



+surfmorph

UTAH
-expmap

5yrs



+surfmorph

UTAH rUTAH
+expmap

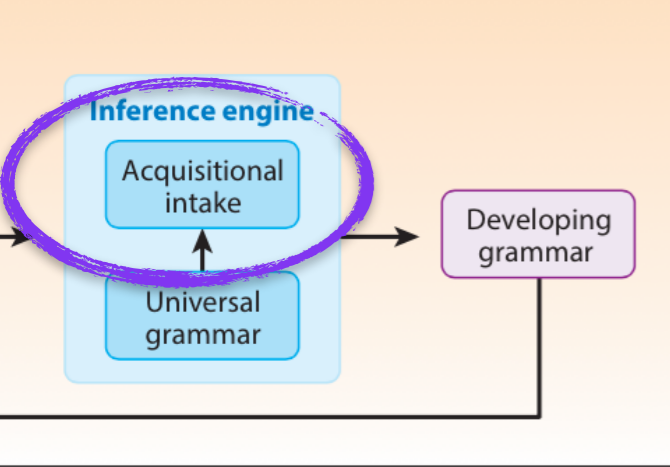


The ice seemed to melt.

NP ____ S_{nonfinite}

NP ____ +past S_{nonfinite}

It suggests there are different timelines for
- ignoring vs. heeding surface morphology on verbs ...



3yrs



-surfmorph

4yrs



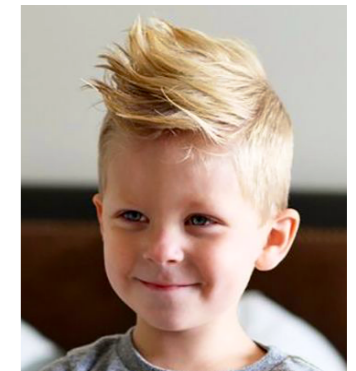
+surfmorph

UTAH

-expmap



5yrs



+surfmorph

UTAH **rUTAH**

+expmap

Agent > Experiencer >

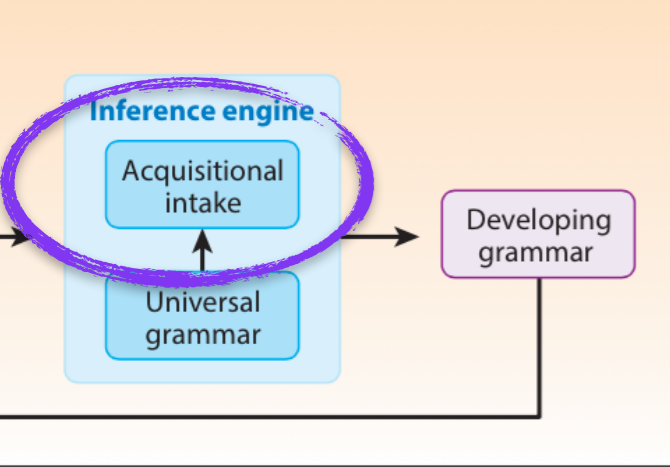
Theme > Patient >

(Source, Goal, Instrument)

It suggests there are different timelines for

- ignoring vs. heeding surface morphology on verbs

- a simpler vs. more flexible intermediate thematic representation...



3yrs



-surfmorph

4yrs



+surfmorph
UTAH
-expmap

5yrs



+surfmorph
UTAH rUTAH
+expmap



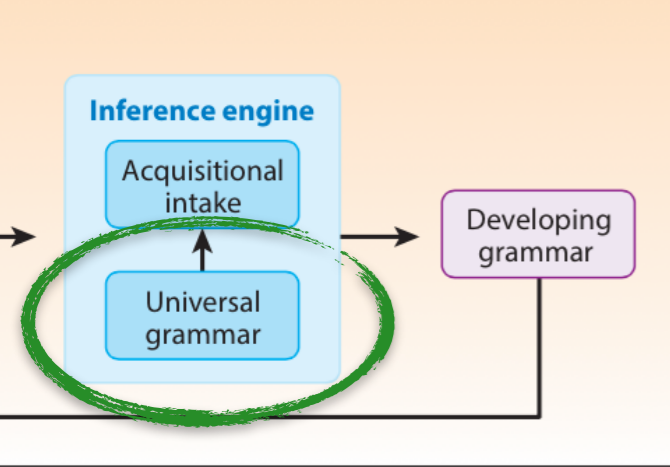
Agent > Experiencer >
Theme > Patient >
(Source, Goal, Instrument)

movement?

Subject Object Indirect Object

It suggests there are different timelines for

- ignoring vs. heeding surface morphology on verbs
- a simpler vs. more flexible intermediate thematic representation
- not expecting vs. expecting a mapping between that intermediate thematic representation and syntactic positions



3yrs



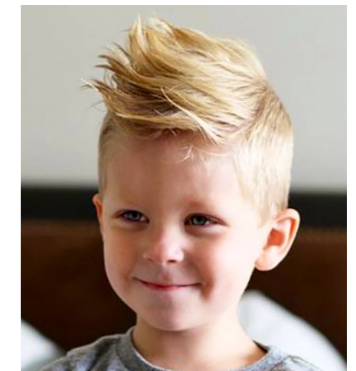
-surfmorph

4yrs



+surfmorph
UTAH
-expmap

5yrs



+surfmorph
UTAH rUTAH
+expmap

What does this mean for linguistic theory?



3yrs



-surfmorph

4yrs



+surfmorph
UTAH
-expmap

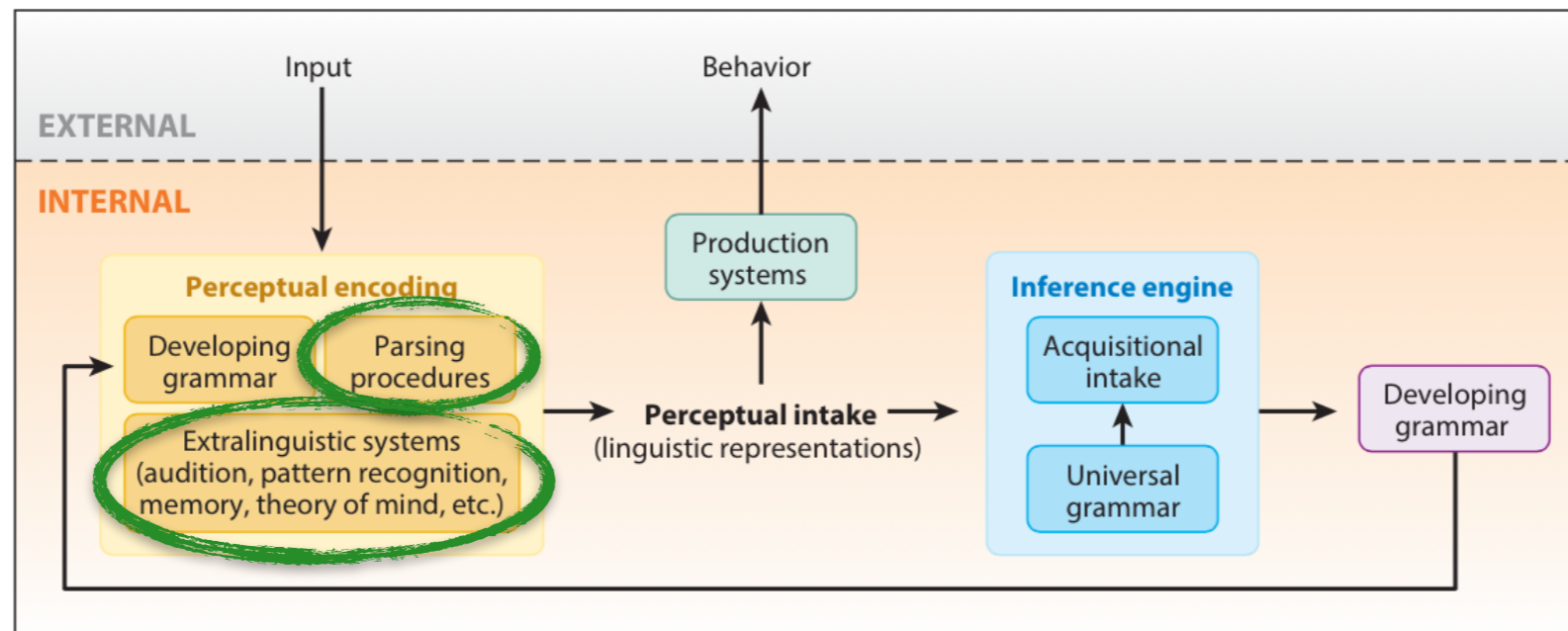
5yrs



+surfmorph
UTAH rUTAH
+expmap

**What seems to develop earlier
(perhaps because it's easy to derive from existing biases):**

-surfmorph: Preference to ignore surface morphology
(perhaps due to processing limitations)



3yrs



-surfmorph

4yrs



+surfmorph

UTAH
-expmap

5yrs



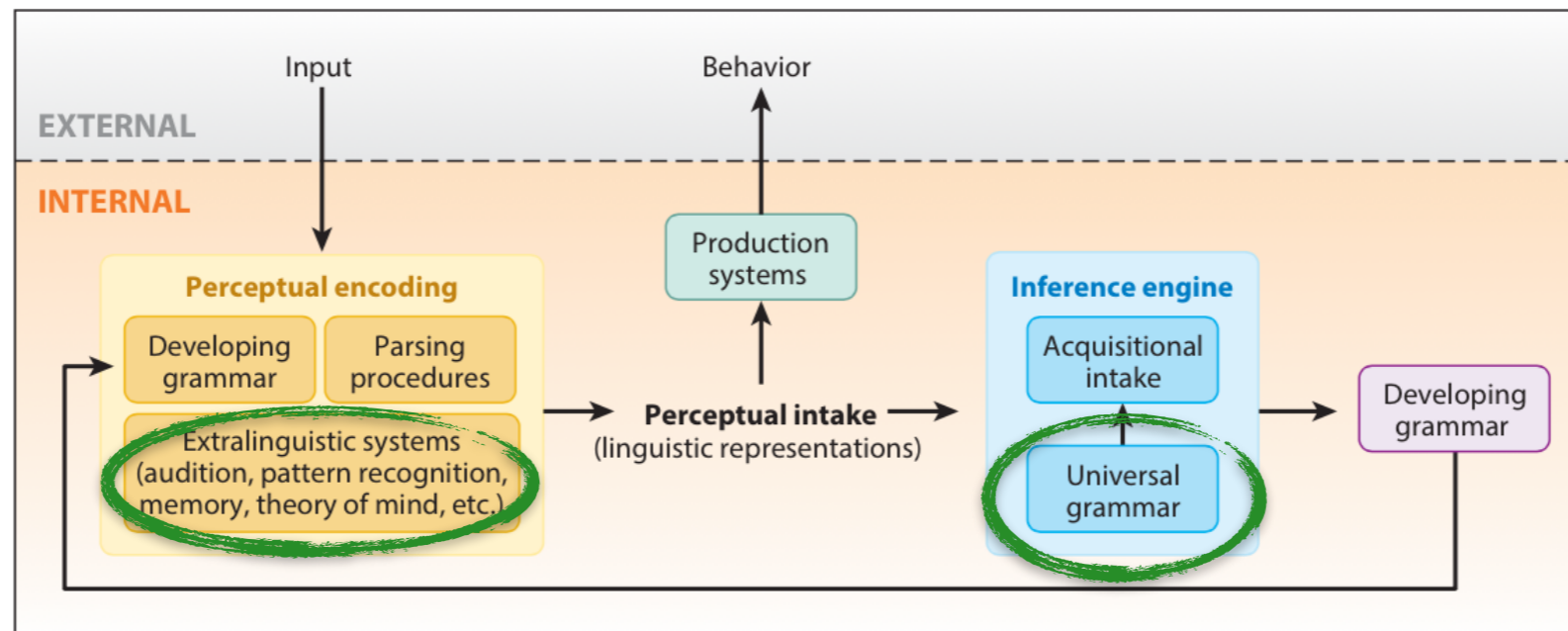
+surfmorph

UTAH rUTAH
+expmap

What seems to develop somewhat earlier
(perhaps because it's easy to derive from
existing biases):



UTAH: Simpler thematic representation



3yrs



-surfmorph

4yrs



+surfmorph

UTAH
-expmap

5yrs



+surfmorph

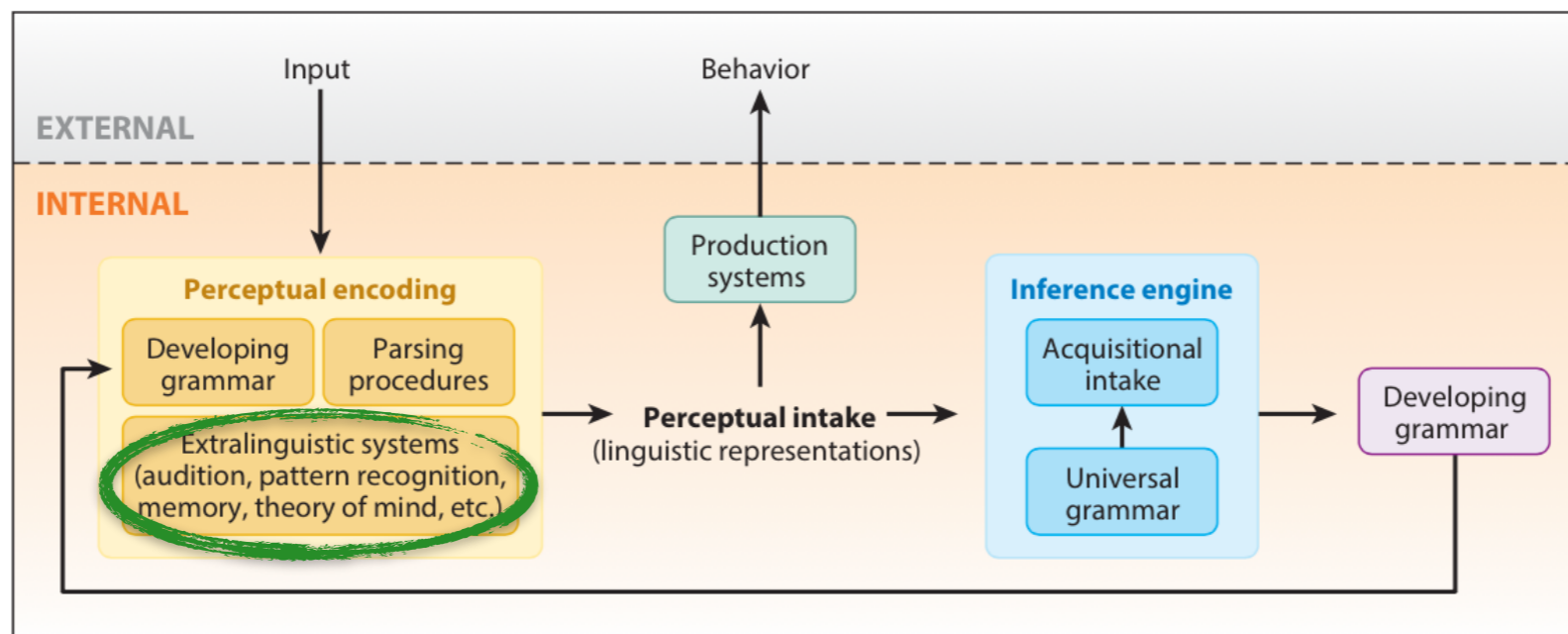
UTAH rUTAH
+expmap

What seems to develop somewhat earlier (perhaps because it's easy to derive from existing biases):

Subject Object Indirect Object



-expmap: No prior expectation about how to map — learn this from the intake



3yrs



-surfmorph

4yrs



+surfmorph

UTAH
-expmap

5yrs



+surfmorph

UTAH rUTAH
+expmap

Subject

Object

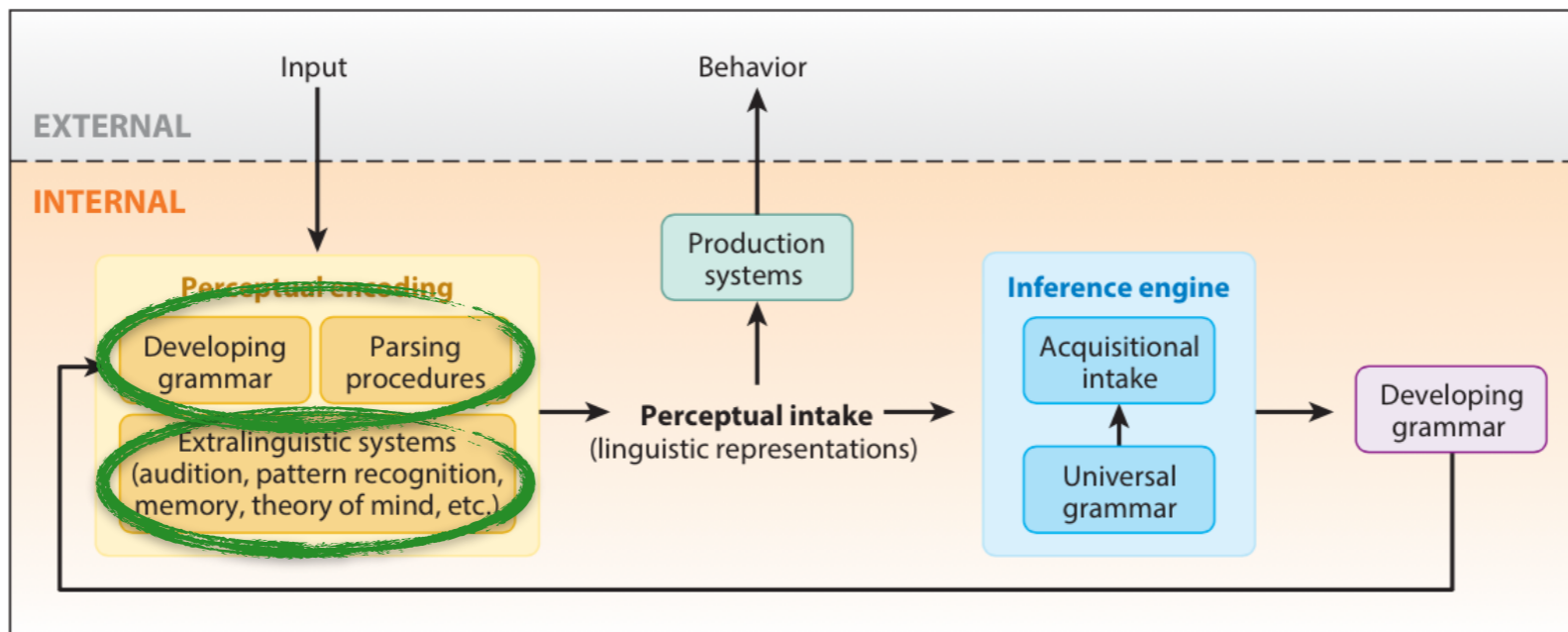
Indirect Object



Agent > Experiencer >
Theme > Patient >
(Source, Goal, Instrument)

What seems to develop later
(perhaps building on prior knowledge):

rUTAH: more sophisticated
thematic representation



3yrs



-surfmorph

4yrs



+surfmorph

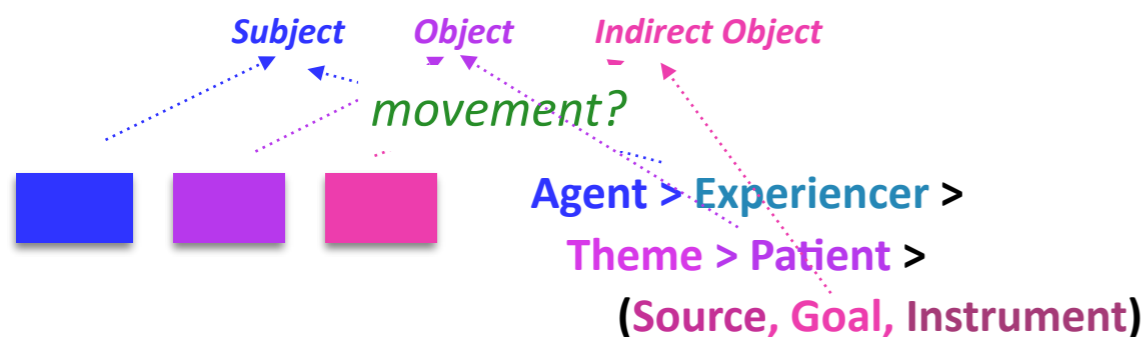
UTAH
-expmap

5yrs



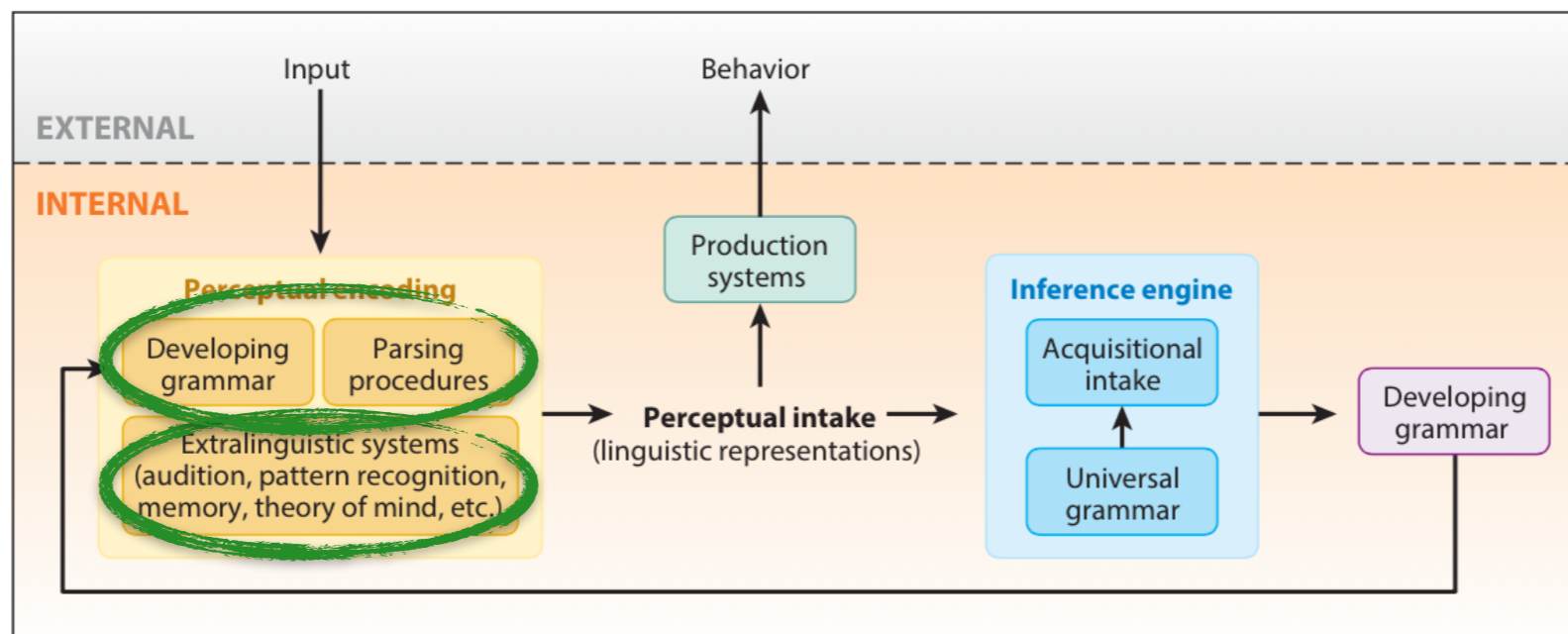
+surfmorph

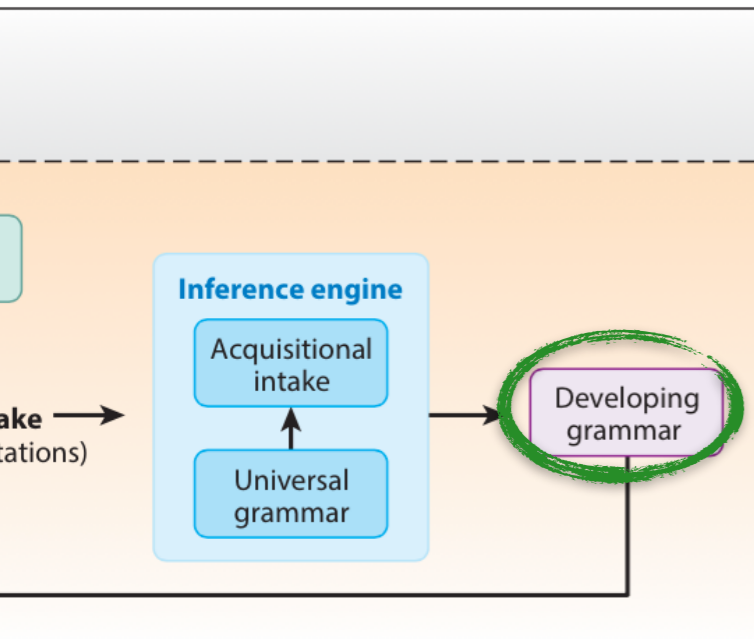
UTAH rUTAH
+expmap



What seems to develop later
(perhaps building on prior knowledge
and the intake):

+expmap: an expectation for a mapping between that
representation and grammatical positions





3yrs



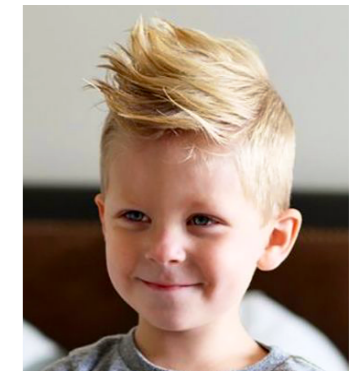
-surfmorph

4yrs



+surfmorph
UTAH
-expmap

5yrs



+surfmorph
UTAH rUTAH
+expmap

Bigger theoretical takeaway:

Everyone's right about the representation at some stage of development.

+animate



-surfmorph
NP ___ S_{nonfinite}
+surfmorph
NP ___+past S_{nonfinite}

UTAH

rUTAH Agent > Experiencer >
Theme > Patient >
(Source, Goal, Instrument)

-expmap Subject Object Indirect Object

+expmap movement?

3yrs



-surfmorph

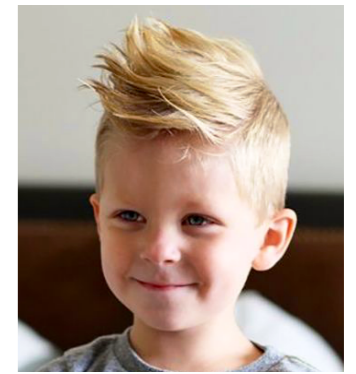
4yrs



+surfmorph

UTAH
-expmap

5yrs



+surfmorph

UTAH rUTAH
+expmap

So now what?



So now what?

3yrs



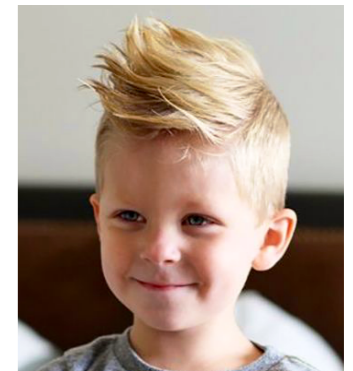
-surfmorph

4yrs



+surfmorph
UTAH
-expmap

5yrs



+surfmorph
UTAH rUTAH
+expmap

(1) A broader assessment of children's verb class knowledge



So now what?

3yrs

-surfmorph

4yrs

+surfmorph

UTAH

-expmap

5yrs

+surfmorph

UTAH rUTAH

+expmap



(1) A broader assessment of children's verb class knowledge

We need more observable behavior for verbs in children's input to match modeling results against.

<3yrs



239 verbs
15 classes
of 60 verbs

<4yrs



267 verbs
23 classes
of 76 verbs

<5yrs



284 verbs
24 classes
of 82 verbs

Input

Children's behavior

So now what?

3yrs

-surfmorph

4yrs

+surfmorph

UTAH

-expmap

5yrs

+surfmorph

UTAH rUTAH

+expmap



(1) A broader assessment of children's verb class knowledge

This will further test these theoretical proposals, and validate (or not) the current findings.

<3yrs



239 verbs
15 classes
of 60 verbs

<4yrs



267 verbs
23 classes
of 76 verbs

<5yrs



284 verbs
24 classes
of 82 verbs

Input

Children's behavior

So now what?

3yrs

-surfmorph

4yrs

+surfmorph

UTAH

-expmap

5yrs

+surfmorph

UTAH rUTAH

+expmap



(1) A broader assessment of children's verb class knowledge

(a) More verbs

<3yrs



239 verbs
15 classes
of 60 verbs

<4yrs



267 verbs
23 classes
of 76 verbs

<5yrs



284 verbs
24 classes
of 82 verbs

Input

Children's behavior

So now what?

3yrs

-surfmorph

4yrs

+surfmorph

UTAH

-expmap

5yrs

+surfmorph

UTAH rUTAH

+expmap



(1) A broader assessment of children's verb class knowledge

(a) More verbs

(b) More behaviors

transitive
unergative *intransitive*

non-finite -ing
small clause
wager-class

<3yrs



239 verbs
15 classes
of 60 verbs

<4yrs



267 verbs
23 classes
of 76 verbs

<5yrs



284 verbs
24 classes
of 82 verbs

Input

Children's behavior

So now what?

(1) A broader assessment of children's verb class knowledge



experimental

(2) Models incorporating more cognitively plausible assumptions

This may give us an even better match to children's observed verb class behavior.

3yrs

-surfmorph

4yrs

+surfmorph

UTAH

-expmap

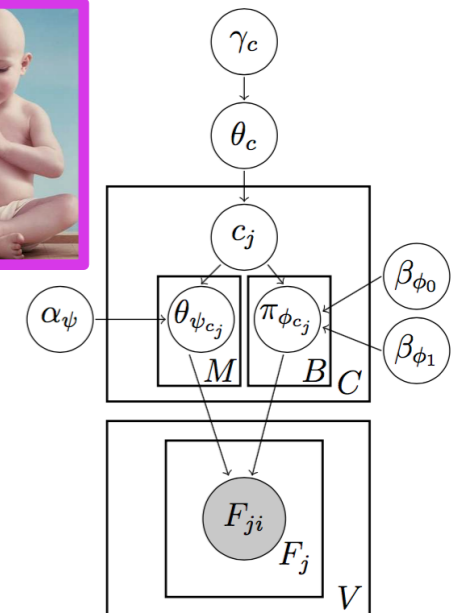
5yrs

+surfmorph

UTAH

rUTAH

+expmap



So now what?

(1) A broader assessment of children's verb class knowledge

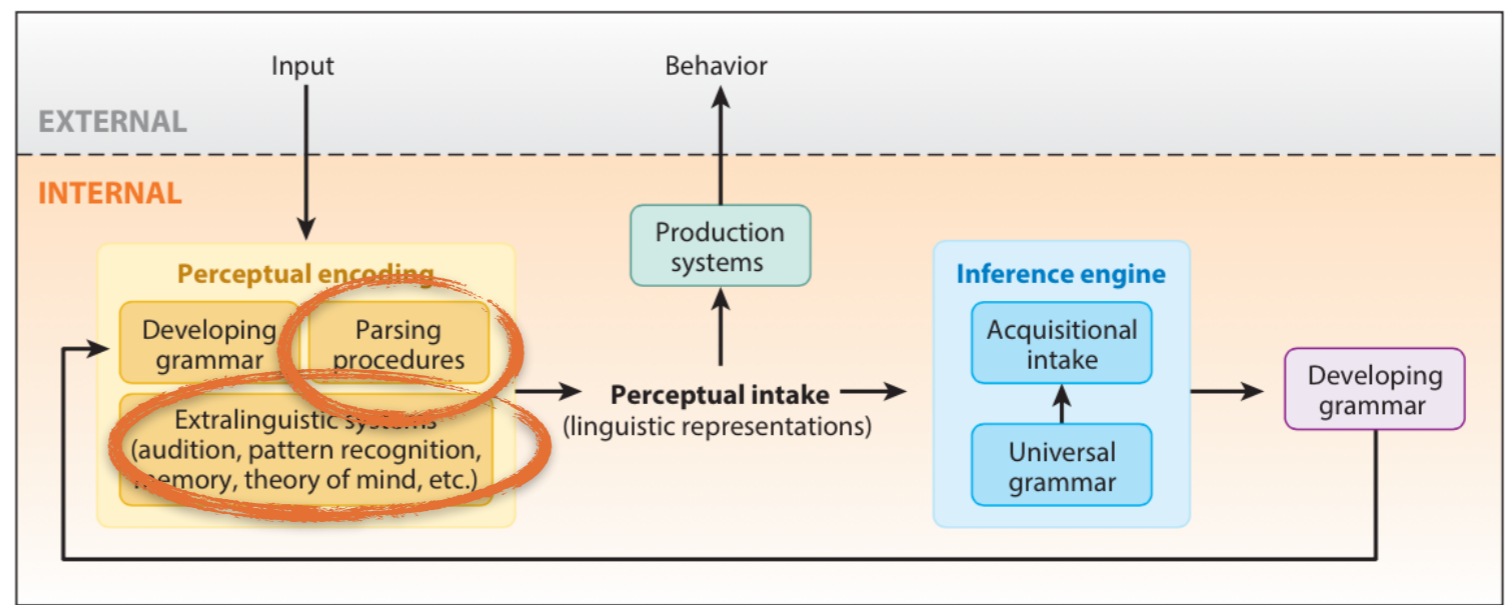
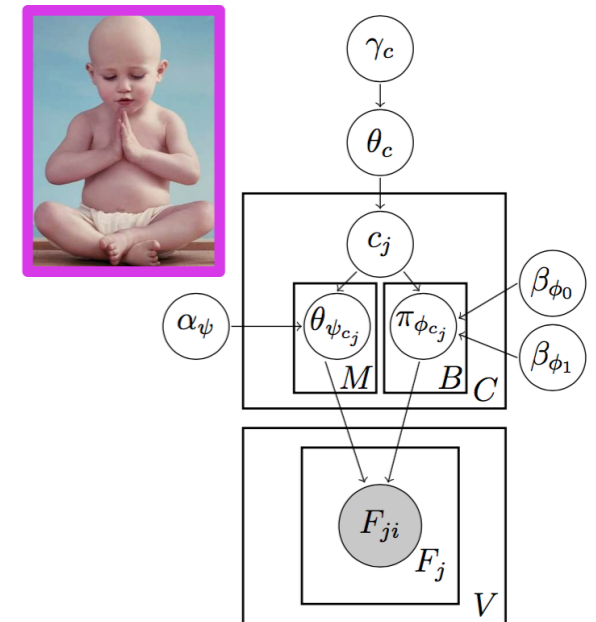


experimental

| 3yrs | 4yrs | 5yrs |
|------------|------------|------------|
| -surfmorph | +surfmorph | +surfmorph |
| | UTAH | UTAH rUTAH |
| | -expmap | +expmap |

(2) Models incorporating more cognitively plausible assumptions

What happens when we embed these theories in a learning model that **learns incrementally** and has age-appropriate **memory & processing limitations**?



So now what?

(1) A broader assessment of children's verb class knowledge

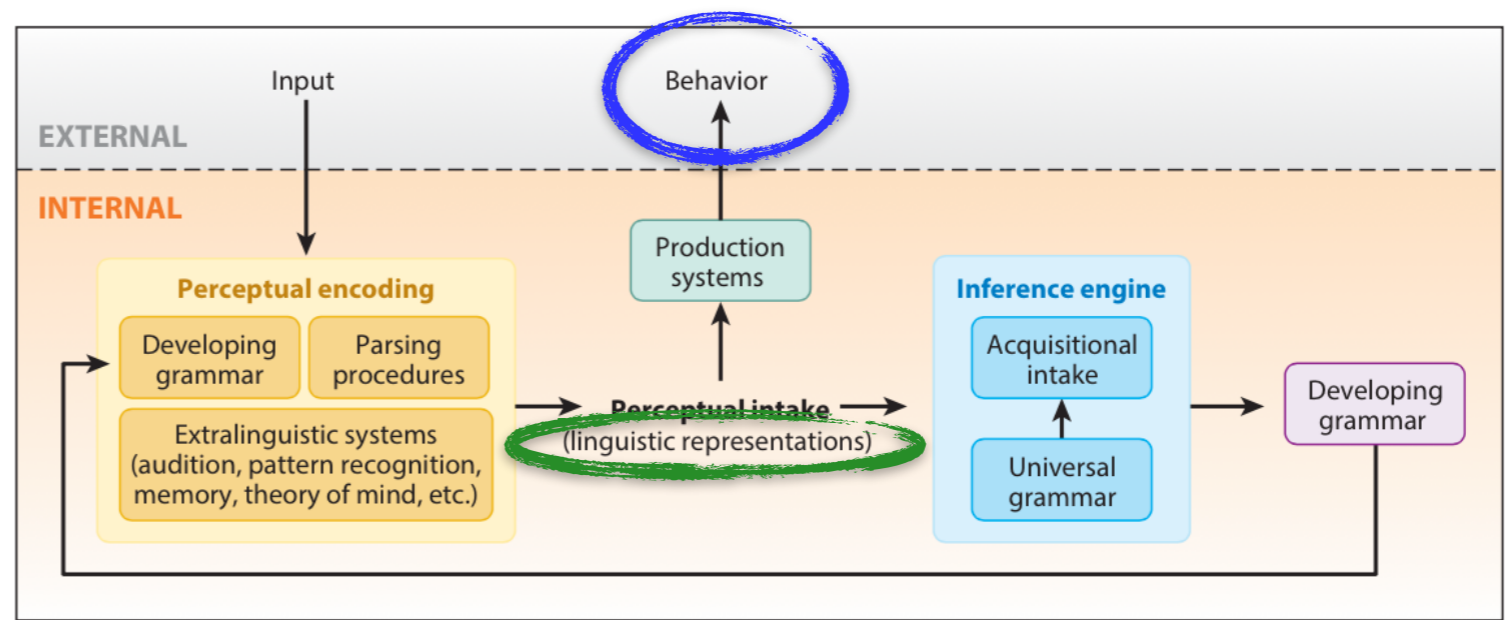
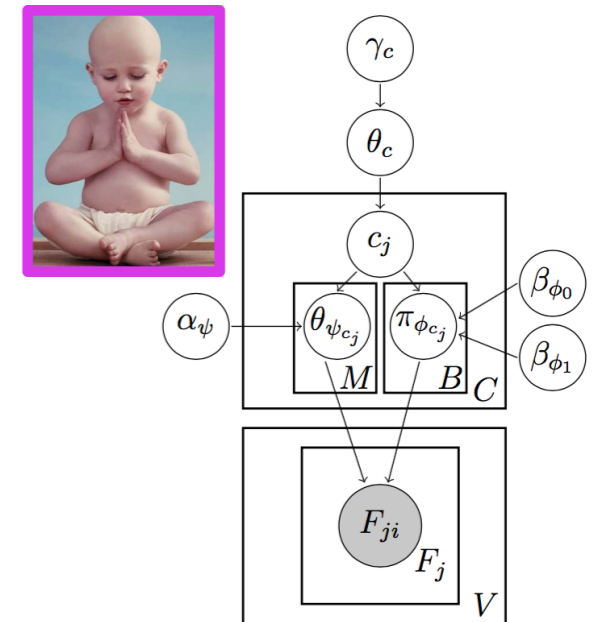


experimental

| 3yrs | 4yrs | 5yrs |
|------------|------------|------------|
| -surfmorph | +surfmorph | +surfmorph |
| | UTAH | UTAH rUTAH |
| | -expmap | +expmap |

(2) Models incorporating more cognitively plausible assumptions

What kinds of child **behavior** does the model predict in the experimental scenarios already available, based on its **internal representations**?



So now what?

(1) A broader assessment of children's verb class knowledge



experimental

3yrs

-surfmorph

4yrs

+surfmorph

UTAH

-expmap

5yrs

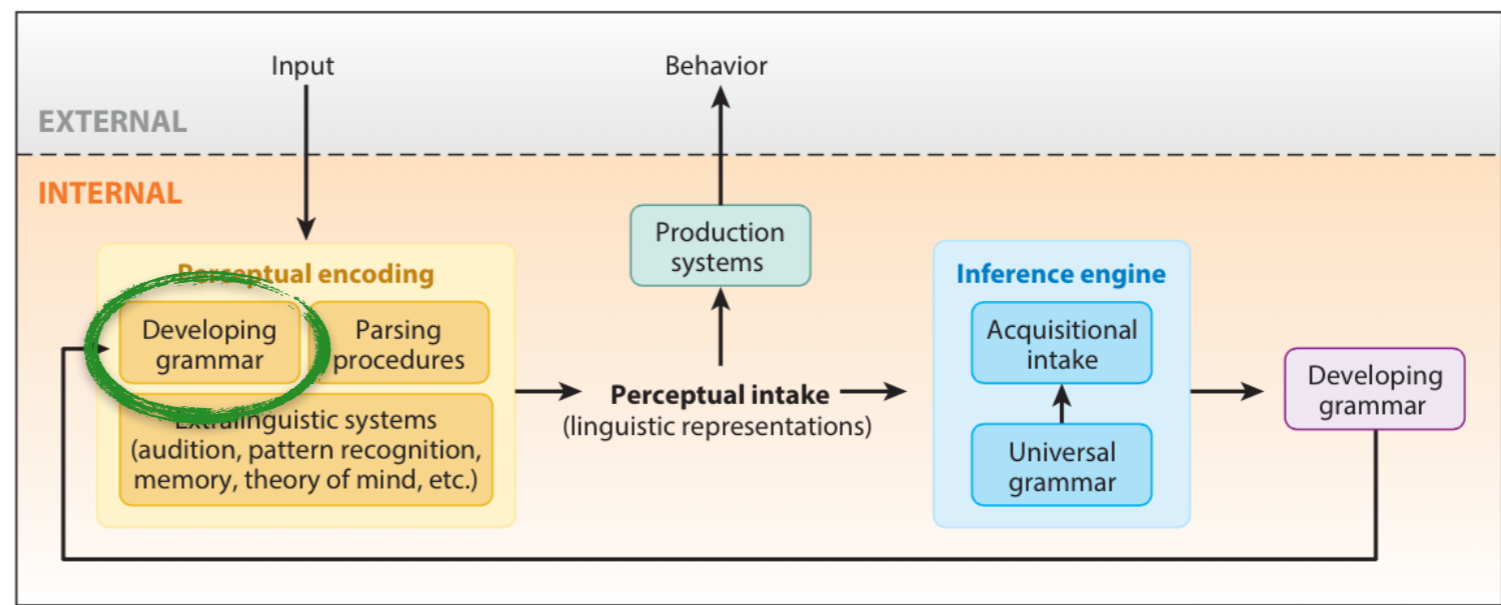
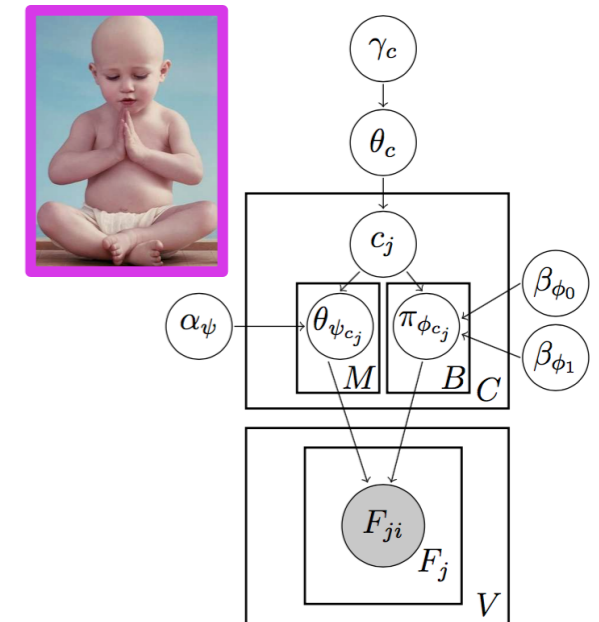
+surfmorph

UTAH rUTAH

+expmap

(2) Models incorporating more cognitively plausible assumptions

What other types of information may be available, especially throughout development as children learn from their intake?



So now what?

(1) A broader assessment of children's verb class knowledge



experimental

3yrs

-surfmorph

4yrs

+surfmorph

UTAH

-expmap

5yrs

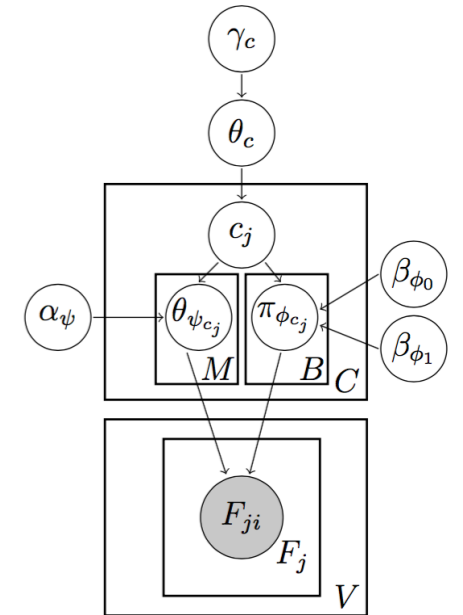
+surfmorph

UTAH rUTAH

+expmap

(2) Models incorporating more cognitively plausible assumptions

computational



(3) Other theories of representation

Are there other options for linking thematic role information to syntactic structure that we can explore in this framework?



Agent > Experiencer >
Theme > Patient >
(Source, Goal, Instrument)



Subject

Object

Indirect Object

???

So now what?

(1) A broader assessment of children's verb class knowledge



experimental

3yrs

-surfmorph

4yrs

+surfmorph

UTAH

-expmap

5yrs

+surfmorph

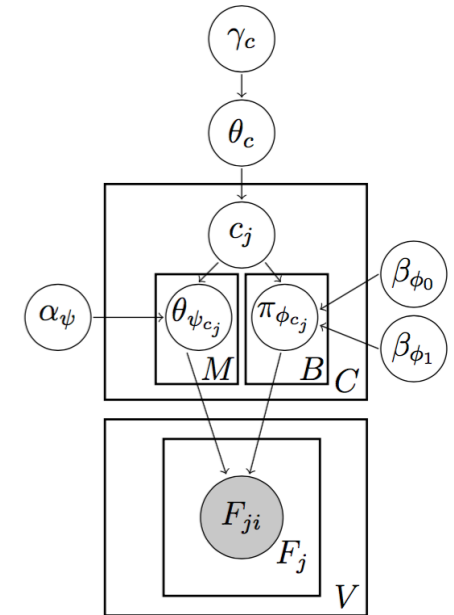
UTAH

rUTAH

+expmap

(2) Models incorporating more cognitively plausible assumptions

computational



(3) Other theories of representation



Agent > Experiencer > ???
 Theme > Patient >
 (Source, Goal, Instrument)

theoretical

Subject Object Indirect Object

What we saw today

Verb classes



done-to

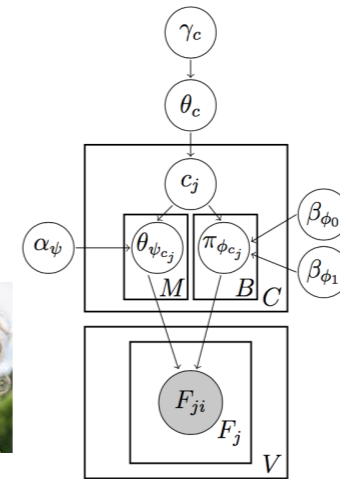
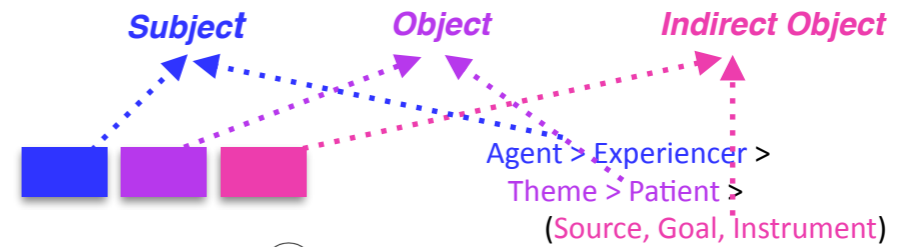
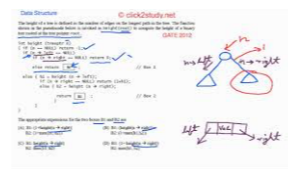
The ice melted.

The penguin climbed.

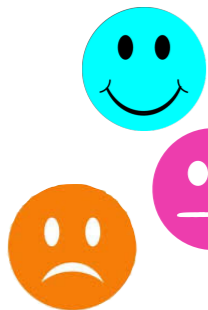
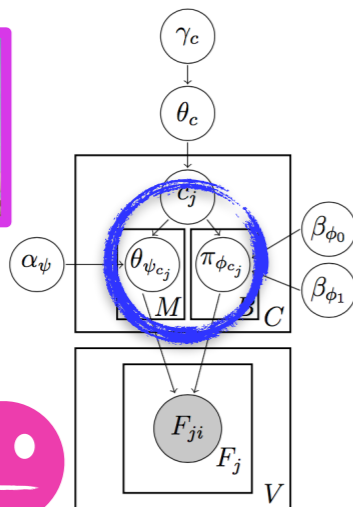
doer



Computational modeling



Results & implications



What we saw today

Verb classes: An example of complex linguistic knowledge that children develop, involving several theoretical options for the representations they may be using.

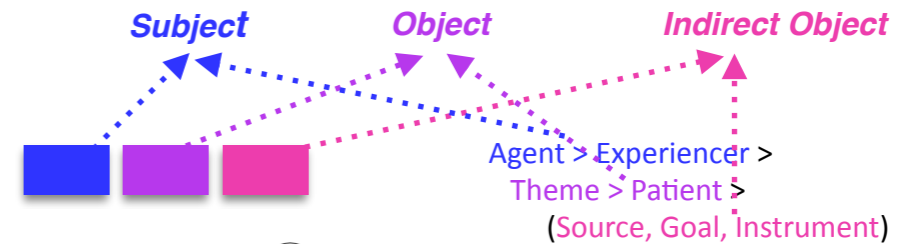
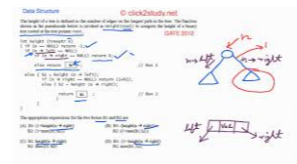


done-to

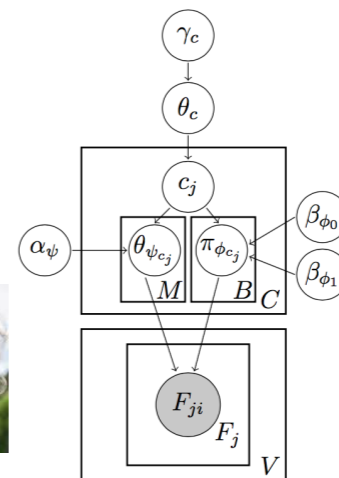
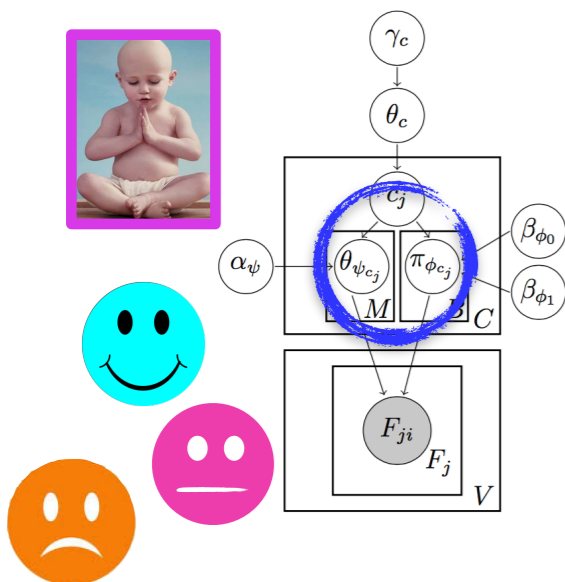
The ice melted.
The penguin climbed.
doer



Computational modeling



Results & implications



What we saw today

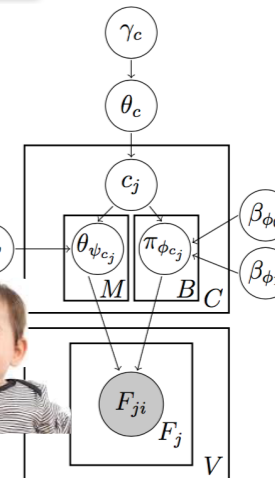
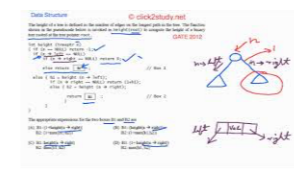
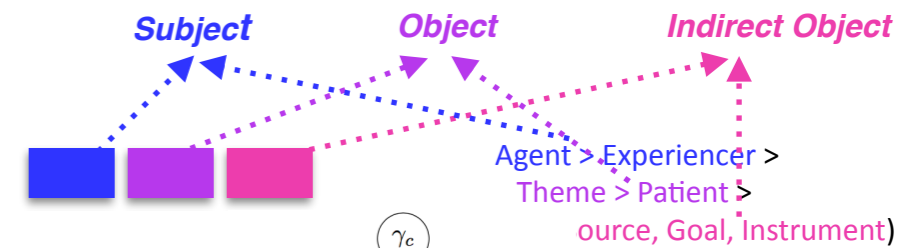
Verb classes: complex linguistic knowledge involving several theoretical options for representations

Computational modeling: A way to explicitly test these theories by implementing them concretely in an empirically grounded model of the acquisition process.

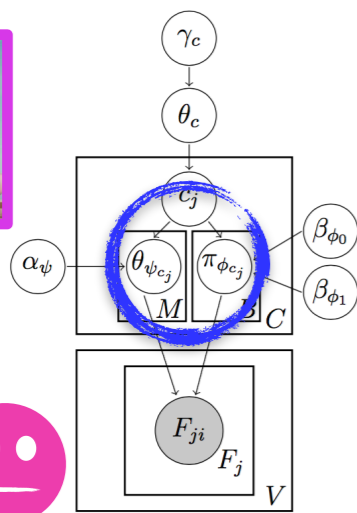
done-to

The ice melted.
The penguin climbed.

doer



Results & implications



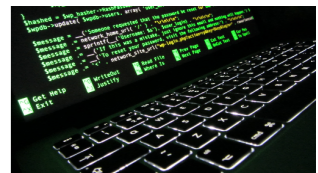
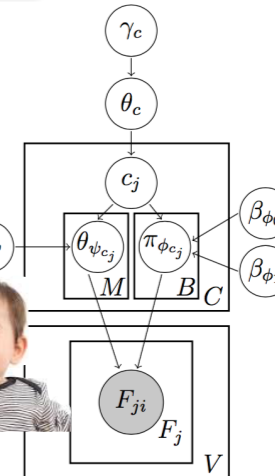
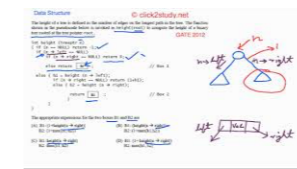
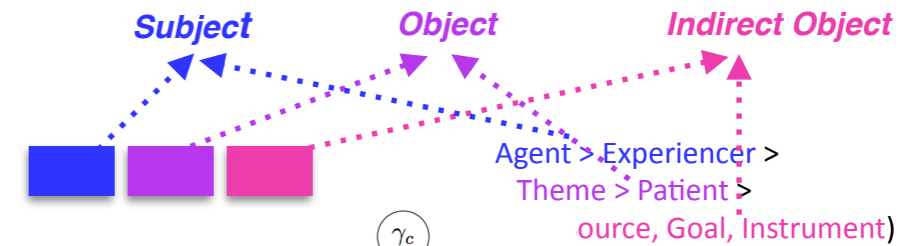
What we saw today

Verb classes: complex linguistic knowledge involving several theoretical options for representations

Computational modeling: explicitly test these theories

done-to

The ice melted.
The penguin climbed.
doer



Results & implications:
Articulating the trajectory of representations and learning assumptions children have at different stages of development

γ_c
 θ_c
 c_j
 α_ψ
 $\theta_{\psi c_j}$ $\pi_{\phi c_j}$ β_{ϕ_0} β_{ϕ_1}
 M B C
 F_{ji} F_j
 V

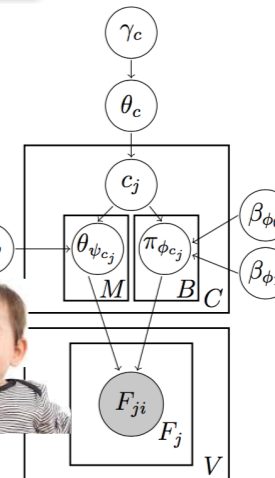
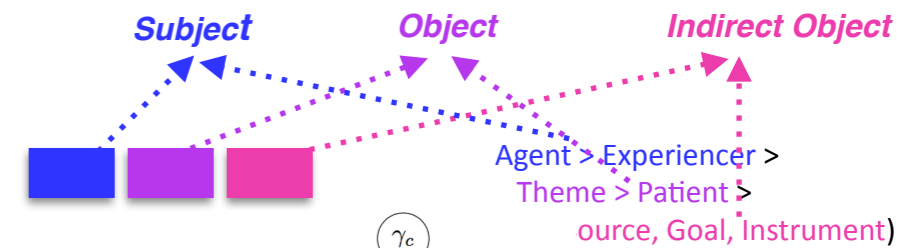
What we saw today

Verb classes: complex linguistic knowledge involving several theoretical options for representations

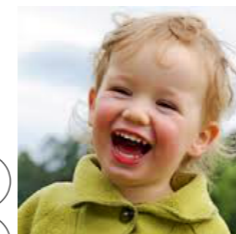
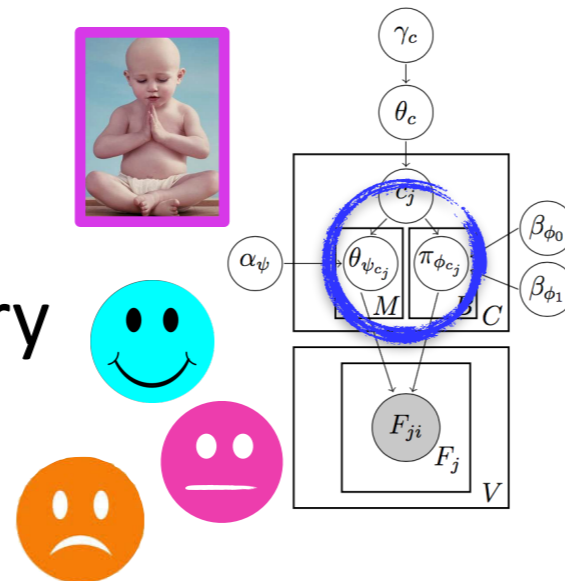
Computational modeling: explicitly test these theories

done-to

The ice melted.
The penguin climbed.
doer



Results & implications:
Articulating the representational trajectory over development



This approach allows us to connect theories of **linguistic representation** and theories of **language acquisition** to understand more about both.

Thank you!

Jon Sprouse



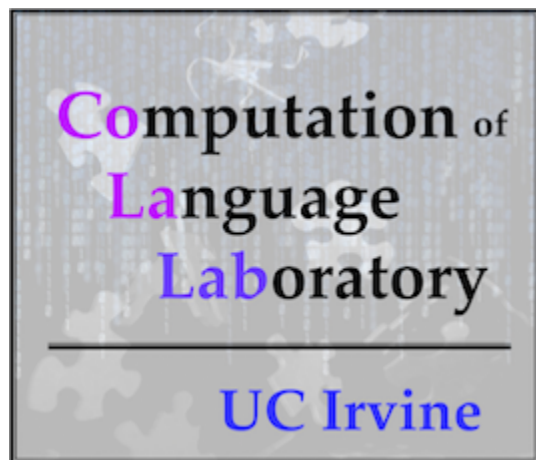
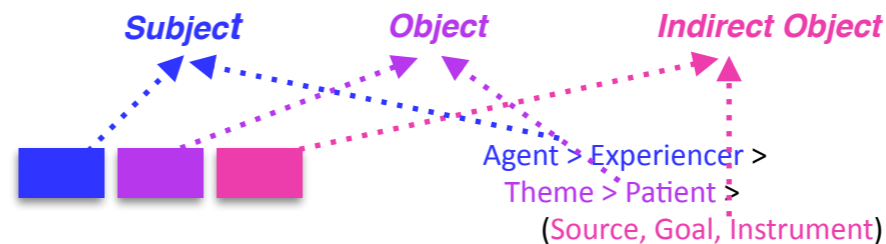
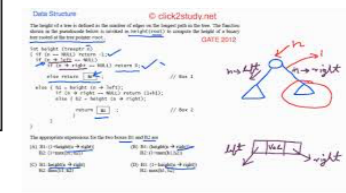
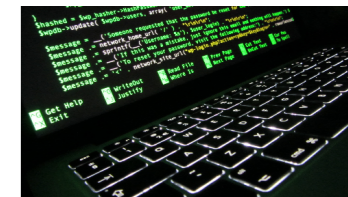
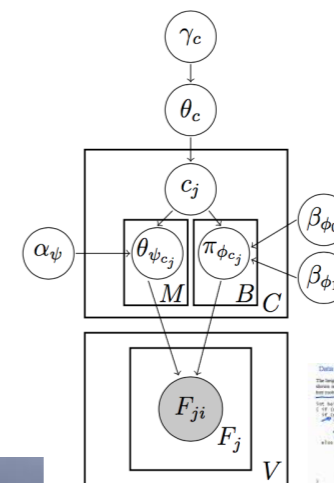
SynLinks workshop 2016
 McGill University
 Linguistics 2016



done-to

The ice melted.
 The penguin climbed.

doer



Lisa S. Pearl
 Associate Professor
 Department of Linguistics
 Department of Cognitive Sciences
 SSPB 2219, SBSG 2314
 University of California, Irvine
 lpearl@uci.edu

This work was supported in part
 by NSF grant BCS-1347028.



Special thanks to Abbie Thornton, Alandi Bates, Emily Yang,
 and BreAnna Silva for CHILDES Treebank corpus annotation.



Thematic roles & how to use them

One idea about how children could use thematic role information: (r)UTAH.

The (relativized) Uniformity of Theta Assignment Hypothesis

UG knowledge

UTAH: Baker 1988, Baker 1997, Dowty 1991, Fillmore 1968, Grimshaw 1990, Jackendoff 1987, Perlmutter & Postal 1984, Speas 1990
Each thematic role maps to a specific syntactic position (grammatical role).

control



She **tried** to **melt** the ice.

doer
doer

done-to

*It **tried** that she **melted** the ice.

doer

done-to



The penguin **seemed** to **climb** the hill.

doer

done-to

It **seemed** that the penguin **climbed** the hill.

doer

done-to

raising

Thematic roles & how to use them

One idea about how children could use thematic role information: (r)UTAH.

The (relativized) Uniformity of Theta Assignment Hypothesis

UG knowledge

UTAH: Baker 1988, Baker 1997, Dowty 1991, Fillmore 1968, Grimshaw 1990, Jackendoff 1987, Perlmutter & Postal 1984, Speas 1990
Each thematic role maps to a specific syntactic position (grammatical role).

Agent-like = grammatical subject

- Agent
- Causer
- Experiencer
- Possessor

("internal cause" = Rappaport-Hovav 1995)



control

She *tried* to melt the ice.
doer *done-to*

*It *tried* that she *melted* the ice.
doer *done-to*



The penguin *seemed* to climb the hill.
doer *done-to*

It *seemed* that the penguin *climbed* the hill.
doer *done-to*

raising

Thematic roles & how to use them

One idea about how children could use thematic role information: (r)UTAH.

The (relativized) Uniformity of Theta Assignment Hypothesis

UG knowledge

UTAH: Baker 1988, Baker 1997, Dowty 1991, Fillmore 1968, Grimshaw 1990, Jackendoff 1987, Perlmutter & Postal 1984, Speas 1990
 Each thematic role maps to a specific syntactic position (grammatical role).

Agent-like = grammatical subject

- Agent
- Causer
- Experiencer (*Baker: only when subject)
- Possessor

("internal cause" = Rappaport-Hovav 1995)




control

She *tried* to melt the ice.
doer done-to

*It *tried* that she *melted* the ice.
doer done-to

She fears spiders.
Experiencer



Spiders frighten her.
Experiencer



The penguin *seemed* to climb the hill.
doer done-to

It *seemed* that the penguin *climbed* the hill.
doer done-to

raising

Thematic roles & how to use them

One idea about how children could use thematic role information: (r)UTAH.

The (relativized) Uniformity of Theta Assignment Hypothesis

UG knowledge

UTAH: Baker 1988, Baker 1997, Dowty 1991, Fillmore 1968, Grimshaw 1990, Jackendoff 1987, Perlmutter & Postal 1984, Speas 1990
Each thematic role maps to a specific syntactic position (grammatical role).

Agent-like = grammatical subject

Patient-like = grammatical object

Patient

Theme

Experiencer

Subject Matter

(“external cause”)



control

She tried to melt the ice.

doer
doer

done-to

*It tried that she melted the ice

doer

done-to



The penguin seemed to climb the hill.

doer

done-to

It seemed that the penguin climbed the hill.

doer

done-to

raising

Thematic roles & how to use them

One idea about how children could use thematic role information: (r)UTAH.

The (relativized) Uniformity of Theta Assignment Hypothesis

UG knowledge

UTAH: Baker 1988, Baker 1997, Dowty 1991, Fillmore 1968, Grimshaw 1990, Jackendoff 1987, Perlmutter & Postal 1984, Speas 1990
Each thematic role maps to a specific syntactic position (grammatical role).

Agent-like = grammatical subject

Patient-like = grammatical object

Patient

Theme

Experiencer (*Baker: only when not subject)

Subject Matter

("external cause")



control

She **tried** to melt the ice.
doer
doer *done-to*

*It **tried** that she **melted** the ice.
doer *doer* *done-to*



The penguin **seemed** to climb the hill.
doer *doer* *done-to*

It **seemed** that the penguin **climbed** the hill.
doer *doer* *done-to*

raising

She **fears** spiders.
Experiencer



Spiders **frighten** her.
Experiencer

Thematic roles & how to use them

One idea about how children could use thematic role information: (r)UTAH.

The (relativized) Uniformity of Theta Assignment Hypothesis

UG knowledge

UTAH: Baker 1988, Baker 1997, Dowty 1991, Fillmore 1968, Grimshaw 1990, Jackendoff 1987, Perlmutter & Postal 1984, Speas 1990

Each thematic role maps to a specific syntactic position (grammatical role).

Agent-like = grammatical subject

Patient-like = grammatical object

Goal-like = grammatical indirect object

Location

Source

Goal

Benefactor

Instrument



control

She *tried* to *melt* the ice with a blow dryer.

doer
doer

done-to

done-with

*It *tried* that she *melted* the ice with a blow dryer.

doer

done-to

done-with



The penguin *seemed* to *climb* the hill.

doer

done-to

It *seemed* that the penguin *climbed* the hill.

doer

done-to

raising

Thematic roles & how to use them



Syntax

She melted the ice with a blow dryer.

Subject

Object

Indirect Object

Mapping to Syntax

UG knowledge

The **U**niformity of **T**heta **A**ssignment **H**ypothesis:

Baker 1988, Baker 1997, Dowty 1991, Fillmore 1968, Grimshaw 1990, Jackendoff 1987, Perlmutter & Postal 1984, Speas 1990

UTAH

Intermediate representations



Thematic roles map to one of three categories.

thematic-roles

(likely derived from lower level conceptual info) =
Agent, Experiencer, Patient, Theme, Goal, Source, Instrument...

Thematic roles & how to use them

One idea about how children could use thematic role information: (r)UTAH.

The (r)elativized U niformity of T heta A ssignment H ypothesis

UG knowledge

rUTAH: Larson 1988, Larson 1990

Thematic roles are ordered relative to each other, with the highest thematic role mapping to the highest grammatical role (subject > object > indirect object).

control



She **tried** to **melt** the ice with a blow dryer.

doer
doer

done-to

done-with

*It **tried** that she **melted** the ice with a blow dryer.

doer

done-to

done-with



The penguin **seemed** to **climb** the hill.

doer

done-to

It **seemed** that the penguin **climbed** the hill.

doer

done-to

raising

Thematic roles & how to use them

One idea about how children could use thematic role information: (r)UTAH.

The (r)elativized U niformity of T heta A ssignment H ypothesis

UG knowledge

rUTAH: Larson 1988, Larson 1990

Thematic roles are ordered relative to each other, with the highest thematic role mapping to the highest grammatical role (subject > object > indirect object).

Basic intuition:

doer (Agent-like) >

done-to (Patient-like) >

done-for/with (Goal-like)



control

She **tried** to **melt** the ice with a blow dryer.

doer
doer

done-to

done-with

*It **tried** that she **melted** the ice with a blow dryer.

doer

done-to

done-with



The penguin **seemed** to **climb** the hill.

doer

done-to

It **seemed** that the penguin **climbed** the hill.

doer

done-to

raising

Thematic roles & how to use them

One idea about how children could use thematic role information: (r)UTAH.

The (relativized) Uniformity of Theta Assignment Hypothesis

UG knowledge

rUTAH: Larson 1988, Larson 1990

Thematic roles are ordered relative to each other, with the highest thematic role mapping to the highest grammatical role (subject > object > indirect object).

Basic intuition:

doer (Agent-like) >

done-to (Patient-like) >

done-for/with (Goal-like)



An example implementation:

Agent > Causer > Experiencer > Possessor >

Subject Matter > Causee > Theme > Patient >

(Location, Source, Goal, Benefactor, Instrument)



control

She **tried** to **melt** the ice with a blow dryer.

doer
doer

done-to

done-with

*It **tried** that she **melted** the ice with a blow dryer.

doer

done-to

done-with

The penguin **seemed** to **climb** the hill.

doer

done-to

It **seemed** that the penguin **climbed** the hill.

doer

done-to

raising

Thematic roles & how to use them

One idea about how children could use thematic role information: (r)UTAH.

The (r)elativized U niformity of T heta A ssignment H ypothesis

UG knowledge

rUTAH: Larson 1988, Larson 1990

Thematic roles are ordered relative to each other, with the highest thematic role mapping to the highest grammatical role (subject > object > indirect object).

Basic intuition:

doer (Agent-like) >

done-to (Patient-like) >

done-for/with (Goal-like)



An example implementation:

Agent > Causer > Experiencer > Possessor >

Subject Matter > Causee > Theme > Patient >

(Location, Source, Goal, Benefactor, Instrument)

Note: You don't need to have every role relatively ranked. If some are unranked with respect to each other, the order in which they get mapped to grammatical positions doesn't matter.



control

She **tried** to **melt** the ice with a blow dryer.
doer *done-to* *done-with*

*It **tried** that she **melted** the ice with a blow dryer.
doer *done-to* *done-with*

The penguin **seemed** to **climb** the hill.
doer *done-to*

It **seemed** that the penguin **climbed** the hill.
doer *done-to*

raising

Thematic roles & how to use them

One idea about how children could use thematic role information: (r)UTAH.

The (relativized) Uniformity of Theta Assignment Hypothesis

UG knowledge

rUTAH: Larson 1988, Larson 1990

Thematic roles are ordered relative to each other, with the highest thematic role mapping to the highest grammatical role (subject > object > indirect object).

Basic intuition:

doer (Agent-like) >

done-to (Patient-like) >

done-for/with (Goal-like)

An example implementation:

Agent > Causer > Experiencer > Possessor >

Subject Matter > Causee > Theme > Patient >

(Location, Source, Goal, Benefactor, Instrument)

This relative ranking can help deal with certain situations, like those involving Experiencers.

She fears spiders.
Experiencer Subject Matter

Experiencer > Subject Matter

Subject Object



Spiders frighten her.
Causer Experiencer

Causer > Experiencer

Subject Object